# Dividends and the Time of Ruin under Barrier Strategies with a Capital-Exchange Agreement 

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#### Abstract

We consider a capital-exchange agreement, where two insurers recapitalize each other in certain situations with funds they would otherwise use for dividend payments. We derive equations characterizing the expected time of ruin and the expected value of the respective discounted dividends until ruin, if dividends are paid according to a barrier strategy. In a Monte Carlo simulation study we illustrate the potential advantages of this type of collaboration.


## 1 Introduction

The identification of dividend payout strategies that balance safety and profitability is a classical topic of insurance risk theory. Whereas ruin theory focuses on the safety aspects (see e.g. Asmussen and Albrecher [2] for a survey), the de Finetti problem of maximizing expected discounted dividends over the lifetime of an insurance portfolio concentrates exclusively on the profitability aspect (see e.g. Azcue and Muler [4] for a recent overview of control problems arising from that). For control problems that address a balancing of the time of ruin against early dividend pay-outs, see e.g. $[12,13]$ and, in the form of a constraint on the ruin time, [11]. At the same time, there have recently been some research efforts to address the analysis of several surplus processes simultaneously, see e.g Chan et al. [7], Cai and Li [6], Gong et al. [10] and Avram et al. [3] on ruin-related measures and Badescu et al. [5] for a capital allocation problem. It is a natural

[^0]question in this context whether certain forms of collaboration between two different companies can lead to a better overall profit and safety compromise than what the two can optimally achieve stand-alone. Gerber and Shiu [9] discuss the effects of merging two portfolios on optimal dividends according to barrier strategies, and Albrecher, Azcue and Muler [1] recently identified the optimal dividend strategy when two companies pay each other's deficit as long as it can be afforded.

In this paper we look at a different type of collaboration between two companies: whenever a company is in a sufficiently comfortable position to pay out capital, it first helps the other company to reach a well-capitalized position before it starts to pay out dividends to shareholders. Such a collaboration strategy clearly has a smoothing effect on the survival of both companies, while dividends are still paid out if the overall situation is sufficiently favorable. Within the family of barrier dividend strategies we look at the effects of such a type of collaboration on the expected ruin time and the resulting expected discounted dividend payments.

Section 2 introduces the model assumptions in detail. In Sections 3 and 4, we derive equations which are satisfied by the insurer's expected time of ruin and the expectation of the discounted dividends, respectively, under the capital-exchange agreement. In Section 5, we provide an efficient Monte Carlo algorithm which we apply in a simulation study. Finally, we aim to illustrate some decision criteria for when to enter such a capital-exchange agreement.

## 2 The Model

Let $I_{1}$ and $I_{2}$ be two insurers, and initially consider the situation where their surplus processes $C_{i}(t), i=1,2$, are independent and each surplus follows a Cramér-Lundberg process,

$$
\begin{equation*}
C_{i}(t)=x_{i}+c_{i} t-S_{i}(t), \tag{1}
\end{equation*}
$$

where $x_{i}$ is the insurer's initial surplus, $c_{i}$ is the premium (income) rate, and $S_{i}(t)$ is a compound Poisson process, representing the aggregate claims of $I_{i}$ up to time $t$, with rate $\lambda_{i}$ and individual claim size distribution function $F_{Y_{i}}(y)$ (density function $f_{Y_{i}}(y)$, respectively).

We now adjust this framework as follows. The two insurers enter into a capital exchange agreement, and each insurer sets a respective barrier $b_{i}$. Like under a classical dividend barrier strategy, $I_{i}$ fully pays out its income as long as its current surplus is at barrier $b_{i}$ (i.e. the surplus process of $I_{i}$ is reflected at $b_{i}$ ). The capital-exchange agreement now defines that these pay-outs go to the other insurer if the surplus of that one is below its barrier level, and otherwise to the own shareholders in the form of dividends. Note that such a capital-exchange agreement introduces dependence on the adjusted surplus processes of the two insurers.

Let $D_{i}(t)$ be the aggregate dividend payments at time $t$ of insurer $i$, and $A_{i}(t)$ are the aggregate payments insurer $I_{i}$ has paid to the partner company under the agreement by time $t$. The adjusted surplus $U_{i}(t)$ of insurer $i$ is then given by

$$
\begin{aligned}
& U_{1}(t)=C_{1}(t)-\left(D_{1}(t)+A_{1}(t)\right)+A_{2}(t), \\
& U_{2}(t)=C_{2}(t)-\left(D_{2}(t)+A_{2}(t)\right)+A_{1}(t)
\end{aligned}
$$

and we can write the dynamics as

$$
\begin{aligned}
d U_{1}(t) & =c_{1} d t-d S_{1}-d D_{1}-d A_{1}+d A_{2} \\
d U_{2}(t) & =c_{2} d t-d S_{2}-d D_{2}-d A_{2}+d A_{1}
\end{aligned}
$$

The time of ruin of insurer $i$ in this framework can then be defined as a function of the two initial surplus levels and the barrier heights, and we write

$$
\begin{equation*}
\tau_{i}\left(x_{1}, x_{2}, b_{1}, b_{2}\right)=\inf \left\{t \mid U_{i}(t)<0 ; U_{1}(0)=x_{1}, U_{2}(0)=x_{2}, b_{1}, b_{2}\right\} \tag{2}
\end{equation*}
$$

We define that the capital-exchange agreement ceases to exist once one of the two insurers is ruined, and the surviving insurer keeps operating its dividend barrier strategy with barrier $b_{i}$ on a stand-alone basis.


Figure 1: Sample path of $\left(U_{1}, U_{2}\right)$.

Figure 1 depicts a sample path of $U_{1}, U_{2}$. Up to time $t_{3}$, both adjusted surplus processes run below their respective pay-out barriers $b_{1}$ and $b_{2}$, and the slope is $c_{1}$ and $c_{2}$, respectively. At time $t_{3}$, $U_{2}$ reaches its pay-out barrier $b_{2}$. Income at rate $c_{2}$ is from now on paid to the partner insurer (who now has an income rate of $c_{1}+c_{2}$ ) up to time $t_{4}$ where also $I_{1}$ reaches its pay-out barrier $b_{1}$. Between times $t_{4}$ and $t_{5}$, any income is paid to the respective shareholders as dividends, because both adjusted surpluses now run at their pay-out barriers. At time $t_{5}$, a claim pulls the adjusted surplus of $I_{2}$ below $b_{2}$, so that it is now supported by $I_{1}$ up to time $t_{7}$ (during this period $I_{2}$ has an income rate of $c_{1}+c_{2}$ ). Finally, at time $t_{8}, I_{2}$ suffers a large claim and is ruined. The capital-exchange agreement ceases to exist, and $I_{1}$ continues on its own. It now pays dividends whenever its adjusted surplus is at $b_{1}$ (between times $t_{9}$ and $t_{10}$ ) and is ruined once its adjusted surplus drops negative (at time $t_{10}$ ).

One observes that money is now generally kept longer in the system of the two insurers, as it is only released to shareholders once the adjusted surpluses of both insurers run at their respective barriers. Intuitively one expects this to have a positive impact on the lifetime, while the impact on expected dividends is not so obvious. In particular, a weak capital-exchange partner would most likely have a negative impact on dividend payments, while a strong partner might help to lift one's adjusted surplus faster so that dividend payments might (re-)start at an earlier time.

While the setup of the dependence structure is fairly straightforward to introduce, the implied mathematics are found to be challenging. Practically, the capital-exchange feature of the presented model can be extended to the case of $n$ insurers, having in mind a holding company (HoldCo for example, a financial investor) that owns a number of separate insurance undertakings, where well-performing entities support underperforming ones. Dividend payments at the HoldCo level are then only made if all entities are sufficiently well capitalised (as defined by their respective barriers $\left.b_{i}\right)$. The HoldCo could then assess such a capital exchange strategy by balancing the effects on the default risk and the dividend income, depending on the risk willingness of its shareholders. Note that within a classical insurance group, dividend clawback rules and financial assistance requirements might restrict the choice of implementable capital-exchange mechanisms as outlined here.

## 3 The Expected Time of Ruin

We observe that the surplus process $U_{i}$ is bounded from above by the otherwise identical surplus process with income rate $c_{1}+c_{2}$, adjusted by a dividend barrier strategy with barrier $b_{i}$, and conclude from the fact that Cramér-Lundberg-type surplus processes under a barrier strategy with finite barrier $b$ have ruin probability one, that also $\mathbb{P}\left[\tau_{i}\left(x_{1}, x_{2} ; b_{1}, b_{2}\right)<\infty\right]=1$ for $i=1,2$. Hence, we turn to an alternative measure of risk. We assume the pay-out barriers $b_{1}$ and $b_{2}$ as fixed and
define the expected time of ruin of insurer $i$ as a function of the initial surplus levels

$$
\begin{equation*}
\gamma_{i}\left(x_{1}, x_{2}\right)=\mathbb{E}\left[\tau_{i}\left(x_{1}, x_{2}\right)\right] \tag{3}
\end{equation*}
$$

We restrict the support of $\gamma_{i}\left(x_{1}, x_{2}\right)$ to $0 \leq x_{i} \leq b_{i}, i=1,2$ (the situations $x_{1}>b_{1}$ or $x_{2}>b_{2}$ can be related to the considered case by defining how initial immediate lump sum payments are made to capital exchange partners and shareholders). Let us focus on the expected time of ruin for $I_{1}$ (by symmetry the situation of $I_{2}$ follows analogously).

Conditioning on the first arrival of a claim from either $S_{1}$ or $S_{2}$ within $h$ time units (for $h$ sufficiently small) and exploiting the Markov property of the bivariate process $\left(U_{1}, U_{2}\right)$ gives the following equations for $x_{i}, b_{i} \geq 0$. In particular, for the interior points, $x_{1}<b_{1}, x_{2}<b_{2}$ :

$$
\begin{align*}
\gamma_{1}\left(x_{1}, x_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h}\left(h+\gamma_{1}\left(x_{1}+c_{1} h, x_{2}+c_{2} h\right)\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{x_{1}+c_{1} t}\left(t+\gamma_{1}\left(x_{1}+c_{1} t-z, x_{2}+c_{2} t\right)\right) f_{Y_{1}}(z) d z\right. \\
& \left.+t \cdot\left(1-F_{Y_{1}}\left(x_{1}+c_{1} t\right)\right)\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{x_{2}+c_{2} t}\left(t+\gamma_{1}\left(x_{1}+c_{1} t, x_{2}+c_{2} t-z\right)\right) f_{Y_{2}}(z) d z\right. \\
& \left.+\left(t+\gamma_{1}^{(0)}\left(x_{1}+c_{1} t\right)\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}+c_{2} t\right)\right)\right) d t \tag{4}
\end{align*}
$$

where $\gamma_{1}^{(0)}(x)$ is the expected time of ruin of $I_{1}$ in the (classical) stand-alone case with initial surplus $x$.

Remark 1. In the case of exponential jump sizes with mean $\mathbb{E}\left[Y_{1}\right]=1 / \nu_{1}$, the expected time of ruin $\gamma_{1}^{(0)}(x)$ in the classical case is known explicitly (cf. Gerber (1979), p. 150) as

$$
\begin{equation*}
\left(c_{1}-\frac{\lambda_{1}}{\nu_{1}}\right) \cdot \gamma_{1}^{(0)}(x)=\frac{e^{R b_{1}}}{R}\left(\frac{\nu_{1}}{\nu_{1}-R}-e^{-R x}\right)-\frac{1}{\nu_{1}}-x \tag{5}
\end{equation*}
$$

where $R=\nu_{1}-\frac{\lambda_{1}}{c_{1}}$ is the adjustment coefficient.
Furthermore, we find for the boundary $x_{1}=b_{1}, x_{2}<b_{2}$ :

$$
\begin{align*}
\gamma_{1}\left(b_{1}, x_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h}\left(h+\gamma_{1}\left(b_{1}, x_{2}+\left(c_{1}+c_{2}\right) h\right)\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}}\left(t+\gamma_{1}\left(b_{1}-z, x_{2}+\left(c_{1}+c_{2}\right) t\right)\right) f_{Y_{1}}(z) d z\right. \\
& \left.+t \cdot\left(1-F_{Y_{1}}\left(b_{1}\right)\right)\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{x_{2}+\left(c_{1}+c_{2}\right) t}\left(t+\gamma_{1}\left(b_{1}, x_{2}+\left(c_{1}+c_{2}\right) t-z\right)\right) f_{Y_{2}}(z) d z\right. \\
& \left.+\left(t+\gamma_{1}^{(0)}\left(b_{1}\right)\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}+\left(c_{1}+c_{2}\right) t\right)\right)\right) d t \tag{6}
\end{align*}
$$

for the boundary $x_{1}<b_{1}, x_{2}=b_{2}$ :

$$
\begin{align*}
\gamma_{1}\left(x_{1}, b_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h}\left(h+\gamma_{1}\left(x_{1}+\left(c_{1}+c_{2}\right) h, b_{2}\right)\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}+\left(c_{1}+c_{2}\right) t}\left(t+\gamma_{1}\left(x_{1}+\left(c_{1}+c_{2}\right) t-z, b_{2}\right)\right) f_{Y_{1}}(z) d z\right. \\
& \left.+t \cdot\left(1-F_{Y_{1}}\left(x_{1}+\left(c_{1}+c_{2}\right) t\right)\right)\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{b_{2}}\left(t+\gamma_{1}\left(x_{1}+\left(c_{1}+c_{2}\right) t, b_{2}-z\right)\right) f_{Y_{2}}(z) d z\right. \\
& \left.+\left(t+\gamma_{1}^{(0)}\left(x_{1}+\left(c_{1}+c_{2}\right) t\right)\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) d t \tag{7}
\end{align*}
$$

and in the corner point $x_{1}=b_{1}, x_{2}=b_{2}$ :

$$
\begin{aligned}
\gamma_{1}\left(b_{1}, b_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h}\left(h+\gamma_{1}\left(b_{1}, b_{2}\right)\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}}\left(t+\gamma_{1}\left(b_{1}-z, b_{2}\right)\right) f_{Y_{1}}(z) d z+t \cdot\left(1-F_{Y_{1}}\left(b_{1}\right)\right)\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{b_{2}}\left(t+\gamma_{1}\left(b_{1}, b_{2}-z\right)\right) f_{Y_{2}}(z) d z\right. \\
& \left.+\left(t+\gamma_{1}^{(0)}\left(b_{1}\right)\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) d t .
\end{aligned}
$$

The function $\gamma_{1}$ is continuous in the interior of $\left[0, b_{1}\right] \times\left[0, b_{2}\right]$, which can be seen by approaching $x_{1}, x_{2}$ from arbitrary directions by taking $x_{1}=x_{1}+j \cdot h$ and $x_{2}=x_{2}+k \cdot h$, with $j, k \in \mathbb{R}$, and letting $h \rightarrow 0$ in (4) in each case. Comparison of (6) and (7) with (4) furthermore shows continuity at the boundaries $x_{1}=b_{1}$ and $x_{2}=b_{2}$.

Differentiating (4) w.r.t. $h$, we observe by symmetry that $\gamma_{1}$ is also differentiable w.r.t. $x_{1}, x_{2}$ in the interior. Applying the operator $\frac{d}{d h}$ to all of the above conditions and taking the limit $h \rightarrow 0$, we obtain a system of integro-differential equations,

$$
\begin{align*}
x_{1}<b_{1}, x_{2}<b_{2}: & 0=-\left(\lambda_{1}+\lambda_{2}\right) \gamma_{1}\left(x_{1}, x_{2}\right)+1+c_{1} \frac{\partial \gamma_{1}}{\partial x_{1}}\left(x_{1}, x_{2}\right)+c_{2} \frac{\partial \gamma_{1}}{\partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +\lambda_{1} \int_{0}^{x_{1}} \gamma_{1}\left(x_{1}-z, x_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{x_{2}} \gamma_{1}\left(x_{1}, x_{2}-z\right) f_{Y}(z) d z+\gamma_{1}^{(0)}\left(x_{1}\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}\right)\right)\right)  \tag{8}\\
x_{1}=b_{1}, x_{2}<b_{2}: \quad & 0=-\left(\lambda_{1}+\lambda_{2}\right) \gamma_{1}\left(b_{1}, x_{2}\right)+1+\left(c_{1}+c_{2}\right) \cdot \frac{\partial \gamma_{1}}{\partial x_{2}}\left(b_{1}, x_{2}\right) \\
& +\lambda_{1} \cdot \int_{0}^{b_{1}} \gamma_{1}\left(b_{1}-z, x_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{x_{2}} \gamma_{1}\left(b_{1}, x_{2}-z\right) f_{Y_{2}}(z) d z+\gamma_{1}^{(0)}\left(b_{1}\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}\right)\right)\right)  \tag{9}\\
x_{1}<b_{1}, x_{2}=b_{2}: \quad & 0=-\left(\lambda_{1}+\lambda_{2}\right) \gamma_{1}\left(x_{1}, b_{2}\right)+1+\left(c_{1}+c_{2}\right) \cdot \frac{\partial \gamma_{1}}{\partial x_{1}}\left(x_{1}, b_{2}\right) \\
& +\lambda_{1} \int_{0}^{x_{1}} \gamma_{1}\left(x_{1}-z, b_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{b_{2}} \gamma_{1}\left(x_{1}, b_{2}-z\right) f_{Y_{2}}(z) d z+\gamma_{1}^{(0)}\left(x_{1}\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) \tag{10}
\end{align*}
$$

and again an equation in the corner point $\left(b_{1}, b_{2}\right)$,

$$
\begin{align*}
0 & =-\left(\lambda_{1}+\lambda_{2}\right) \gamma_{1}\left(b_{1}, b_{2}\right)+1 \\
& +\lambda_{1} \cdot \int_{0}^{b_{1}} \gamma_{1}\left(b_{1}-z, b_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2} \cdot\left(\int_{0}^{b_{2}} \gamma_{1}\left(b_{1}, b_{2}-z\right) f_{Y_{2}}(z) d z+\gamma_{1}^{(0)}\left(b_{1}\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) \tag{11}
\end{align*}
$$

Continuity of $\gamma_{1}\left(x_{1}, x_{2}\right)$ on the boundaries $x_{1}=b_{1}$ or $x_{2}=b_{2}$ and comparing (8) to (9) and (10), gives the boundary conditions

$$
\begin{align*}
& \frac{\partial \gamma_{1}}{\partial x_{1}}\left(b_{1}, x_{2}\right)=\frac{\partial \gamma_{1}}{\partial x_{2}}\left(b_{1}, x_{2}\right) \quad \forall 0 \leq x_{2}<b_{2}  \tag{12}\\
& \frac{\partial \gamma_{1}}{\partial x_{1}}\left(x_{1}, b_{2}\right)=\frac{\partial \gamma_{1}}{\partial x_{2}}\left(x_{1}, b_{2}\right) \quad \forall 0 \leq x_{1}<b_{1} . \tag{13}
\end{align*}
$$

Similarly, approaching $\left(b_{1}, b_{2}\right)$ from interior points gives
$c_{1} \frac{\partial \gamma_{1}}{\partial x_{1}}\left(b_{1}, b_{2}\right)+c_{2} \frac{\partial \gamma_{1}}{\partial x_{2}}\left(b_{1}, b_{2}\right)=0$, so that we have $\frac{\partial \gamma_{1}}{\partial x_{1}}\left(b_{1}, b_{2}\right)=\frac{\partial \gamma_{1}}{\partial x_{2}}\left(b_{1}, b_{2}\right)=0$.

Altogether $\gamma_{1}\left(x_{1}, x_{2}\right)$ is characterised as the solution to the equation system (8) with boundary conditions (12) and (13).

Exponential claims. Assume that the claim sizes of $I_{1}$ are i.i.d. $\operatorname{Exp}\left(\nu_{1}\right)$ distributed, and the claim sizes of $I_{2}$ are $\operatorname{Exp}\left(\nu_{2}\right)$ distributed. Applying the operator $\left(\frac{d}{d x_{1}}+\nu_{1}\right)$ followed by the operator $\left(\frac{d}{d x_{2}}+\nu_{2}\right)$ to (8) yields a third-order PDE with constant coefficients,

$$
\begin{align*}
0 & =\nu_{1} \nu_{2}+\nu_{2} c_{1} \nu_{1}\left(1-\frac{\lambda_{1}}{c_{1} \nu_{1}}\right) \frac{\partial \gamma_{1}}{\partial x_{1}}\left(x_{1}, x_{2}\right)+\nu_{1} c_{2} \nu_{2}\left(1-\frac{\lambda_{2}}{c_{2} \nu_{2}}\right) \frac{\partial \gamma_{1}}{\partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +\left[c_{1} \nu_{1}\left(1-\frac{\lambda_{1}}{c_{1} \nu_{1}}\right)+c_{2} \nu_{2}\left(1-\frac{\lambda_{2}}{c_{2} \nu_{2}}\right)\right] \frac{\partial^{2} \gamma_{1}}{\partial x_{1} \partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +c_{1} \nu_{2} \frac{\partial^{2} \gamma_{1}}{\partial x_{1}^{2}}\left(x_{1}, x_{2}\right)+c_{2} \nu_{1} \frac{\partial^{2} \gamma_{1}}{\partial x_{2}^{2}}\left(x_{1}, x_{2}\right) \\
& +c_{1} \frac{\partial^{3} \gamma_{1}}{\partial x_{1}^{2} \partial x_{2}}\left(x_{1}, x_{2}\right)+c_{2} \frac{\partial^{3} \gamma_{1}}{\partial x_{1} \partial x_{2}^{2}}\left(x_{1}, x_{2}\right), \tag{14}
\end{align*}
$$

so that the dynamics in the interior are now described locally. One observes that $\gamma_{p}\left(x_{1}, x_{2}\right)=$ $A_{1} x_{1}+A_{2} x_{2}$ with the condition $1=\left(\frac{\lambda_{1}}{\nu_{1}}-c_{1}\right) A_{1}+\left(\frac{\lambda_{2}}{\nu_{2}}-c_{2}\right) A_{2}$ is a particular solution to this inhomogeneous PDE. Terms of the form $e^{-r x_{1}} e^{-s x_{2}}$ can appear in the solution to the homogeneous
problem if they fulfil the characteristic equation

$$
\begin{align*}
0= & -\nu_{2} c_{1} \nu_{1}\left(1-\frac{\lambda_{1}}{c_{1} \nu_{1}}\right) r-\nu_{1} c_{2} \nu_{2}\left(1-\frac{\lambda_{2}}{c_{2} \nu_{2}}\right) s \\
& +\left[c_{1} \nu_{1}\left(1-\frac{\lambda_{1}}{c_{1} \nu_{1}}\right)+c_{2} \nu_{2}\left(1-\frac{\lambda_{2}}{c_{2} \nu_{2}}\right)\right] r s \\
& +c_{1} \nu_{2} r^{2}+c_{2} \nu_{1} s^{2}-c_{1} r^{2} s-c_{2} r s^{2} . \tag{15}
\end{align*}
$$

A plot of (15) for a particular choice of parameters is shown in Figure 2.


Figure 2: Plot of the implicit equation (15), with $c_{1}=c_{2}=6, \lambda_{1}=\lambda_{2}=5$ and $\nu_{1}=\nu_{2}=1$.

While it turns out to be mathematically intricate to obtain an explicit solution for $\gamma_{1}\left(x_{1}, x_{2}\right)$ (which must also match the original IDE (8) - note that some terms cancelled when applying the differential operator, which now need to be recalibrated by a suitable combination of homogeneous solutions - and the boundary conditions), the above characterisation may be useful for setting up a numerical solution procedure or also a hybrid numerical procedure, where finite-difference methods are applied after simulating the boundaries, with the aim of achieving an improvement in run time over crude Monte Carlo simulation.

## 4 The Expected Sum of Discounted Dividends

Apart from the prolonging effect of the capital-exchange agreement on the expected time until ruin, we are interested in how the expected sum of discounted dividends until ruin is affected. We hence define

$$
\begin{equation*}
V_{i}\left(x_{1}, x_{2} ; b_{1}, b_{2}\right) \tag{16}
\end{equation*}
$$

as the expectation of the sum of discounted dividends until ruin paid to the shareholders of $I_{i}$, where we use a constant force of interest $\delta>0$ for discounting. In the following we will assume that the pay-out barriers have been set and, thus, use the shortened notation $V_{1}\left(x_{1}, x_{2}\right)=V_{1}\left(x_{1}, x_{2} ; b_{1}, b_{2}\right)$.

Proceeding as in Section 3, one can again condition on the occurrence of a jump event within $h$ time units, $h$ sufficiently small, to find that for the interior points $x_{1}<b_{1}, x_{2}<b_{2}$ :

$$
\begin{align*}
V_{1}\left(x_{1}, x_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h} e^{-\delta h} V_{1}\left(x_{1}+c_{1} h, x_{2}+c_{2} h\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{x_{1}+c_{1} t} e^{-\delta t} V_{1}\left(x_{1}+c_{1} t-z, x_{2}+c_{2} t\right) f_{Y_{1}}(z) d z\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{x_{2}+c_{2} t} e^{-\delta t} V_{1}\left(x_{1}+c_{1} t, x_{2}+c_{2} t-z\right) f_{Y_{2}}(z) d z\right. \\
& \left.+e^{-\delta t} V_{1}^{(0)}\left(x_{1}+c_{1} t\right)\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}+c_{2} t\right)\right) d t \tag{17}
\end{align*}
$$

where $V_{1}^{(0)}\left(x_{1}\right)$ is the stand-alone expectation of the sum of discounted dividends.

Remark 2. In the exponential claim size case with $\mathbb{E}\left[Y_{1}\right]=1 / \nu_{1}$, the expectation of the sum of discounted dividends in the classical case has an explicit form (cf. [8], p. 183),

$$
\begin{equation*}
V_{1}^{(0)}\left(x_{1}, b_{1}\right)=\frac{\left(\nu_{1}+r_{1}\right) e^{r_{1} x_{1}}-\left(\nu_{1}+r_{2}\right) e^{r_{2} x_{1}}}{r_{1}\left(\nu_{1}+r_{1}\right) e^{r_{1} b}-r_{2}\left(\nu_{1}+r_{2}\right) e^{r_{2} b}} \tag{18}
\end{equation*}
$$

where $r_{1}$ and $r_{2}$ are the solutions to the equation

$$
\begin{equation*}
\xi^{2}+\left(\nu_{1}-\frac{\lambda_{1}+\delta}{c_{1}}\right) \xi-\frac{\nu_{1} \delta}{c_{1}}=0 . \tag{19}
\end{equation*}
$$

Similarly it follows for the boundary $x=b_{1}, x_{2}<b_{2}$ :

$$
\begin{align*}
V_{1}\left(b_{1}, x_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h} e^{-\delta h} V_{1}\left(b_{1}, x_{2}+\left(c_{1}+c_{2}\right) h\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}} e^{-\delta t} V_{1}\left(b_{1}-z, x_{2}+\left(c_{1}+c_{2}\right) t\right) f_{Y_{1}}(z) d z\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{x_{2}+\left(c_{1}+c_{2}\right) t} e^{-\delta t} V_{1}\left(b_{1}, x_{2}+\left(c_{1}+c_{2}\right) t-z\right) f_{Y_{2}}(z) d z\right. \\
& \left.+e^{-\delta t} V_{1}^{(0)}\left(b_{1}\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}+\left(c_{1}+c_{2}\right) t\right)\right)\right) d t, \tag{20}
\end{align*}
$$

for the boundary $x_{1}<b_{1}, x_{2}=b_{2}$ :

$$
\begin{align*}
V_{1}\left(x_{1}, b_{2}\right) & =e^{-\left(\lambda_{1}+\lambda_{2}\right) h} e^{-\delta h} V_{1}\left(x_{1}+\left(c_{1}+c_{2}\right) h, b_{2}\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}+\left(c_{1}+c_{2}\right) t} e^{-\delta t} V_{1}\left(x_{1}+\left(c_{1}+c_{2}\right) t-z, b_{2}\right) f_{Y_{1}}(z) d z\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{b_{2}} e^{-\delta t} V_{1}^{(0)}\left(x_{1}+\left(c_{1}+c_{2}\right) t, b_{2}-z\right) f_{Y_{2}}(z) d z\right. \\
& \left.+e^{-\delta t} V_{1}^{(0)}\left(x_{1}+\left(c_{1}+c_{2}\right) t\right)\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right) d t \tag{21}
\end{align*}
$$

and in the corner point we obtain

$$
\begin{align*}
& V_{1}\left(b_{1}, b_{2}\right)=e^{-\left(\lambda_{1}+\lambda_{2}\right) h}\left(v_{1}(h)+e^{-\delta h} V_{1}\left(b_{1}, b_{2}\right)\right) \\
& +\int_{0}^{h} e^{-\lambda_{2} t} \lambda_{1} e^{-\lambda_{1} t}\left(\int_{0}^{b_{1}}\left(v_{1}(t)+e^{-\delta t} V_{1}\left(b_{1}-z, b_{2}\right)\right) f_{Y_{1}}(z) d z+v_{1}(t) \cdot\left(1-F_{Y_{1}}\left(b_{1}\right)\right)\right) d t \\
& +\int_{0}^{h} e^{-\lambda_{1} t} \lambda_{2} e^{-\lambda_{2} t}\left(\int_{0}^{b_{2}}\left(v_{1}(t)+e^{-\delta t} V_{1}\left(b_{1}-z, b_{2}\right)\right) f_{Y_{2}}(z) d z\right. \\
& \left.+\left(v_{1}(t)+e^{-\delta t} V_{1}^{(0)}\left(b_{1}\right)\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) d t, \tag{22}
\end{align*}
$$

where $v_{1}(t)=\int_{0}^{t} c_{1} e^{-\delta s} d s=\frac{c_{1}}{\delta}\left(1-e^{-\delta t}\right)$ is the present value of the discounted dividends paid at rate $c_{1}$ over $[0, t)$.

By the same line of argument as in Section 3, one sees that $V_{1}\left(x_{1}, x_{2}\right)$ is continuous for all $\left(x_{1}, x_{2}\right) \in$ $\left[0, b_{1}\right] \times\left[0, b_{2}\right]$. Given differentiability w.r.t. $h$, by symmetry we can establish differentiability of $V_{1}$ w.r.t $x_{1}, x_{2}$. Applying again the operator $\frac{d}{d h}$ to each equation and letting $h \rightarrow 0$ yields,

$$
\begin{align*}
x_{1}<b_{1}, x_{2}<b_{2}: & 0=-\left(\lambda_{1}+\lambda_{2}+\delta\right) V_{1}\left(x_{1}, x_{2}\right)+c_{1} \frac{\partial V_{1}}{\partial x_{1}}\left(x_{1}, x_{2}\right)+c_{2} \frac{\partial V_{1}}{\partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +\lambda_{1} \int_{0}^{x_{1}} V_{1}\left(x_{1}-z, x_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{x_{2}} V_{1}\left(x_{1}, x_{2}-z\right) f_{Y_{2}}(z) d z+V\left(x_{1}\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}\right)\right)\right),  \tag{23}\\
x_{1}=b_{1}, x_{2}<b_{2}: \quad & 0=-\left(\lambda_{1}+\lambda_{2}+\delta\right) V_{1}\left(b_{1}, x_{2}\right)+\left(c_{1}+c_{2}\right) \cdot \frac{\partial V_{1}}{\partial x_{2}}\left(b_{1}, x_{2}\right) \\
& +\lambda_{1} \cdot \int_{0}^{b_{1}} V_{1}\left(b_{1}-z, x_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{x_{2}} V_{1}\left(b_{1}, x_{2}-z\right) f_{Y_{2}}(z) d z+V\left(b_{1}\right) \cdot\left(1-F_{Y_{2}}\left(x_{2}\right)\right)\right),  \tag{24}\\
x_{1}<b_{1}, x_{2}=b_{2}: & 0=-\left(\lambda_{1}+\lambda_{2}+\delta\right) V_{1}\left(x_{1}, b_{2}\right)+\left(c_{1}+c_{2}\right) \cdot \frac{\partial V_{1}}{\partial x_{1}}\left(x_{1}, b_{2}\right) \\
& +\lambda_{1} \int_{0}^{x_{1}} V_{1}\left(x_{1}-z, b_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2}\left(\int_{0}^{b_{2}} V_{1}\left(x_{1}, b_{2}-z\right) f_{Y_{2}}(z) d z+V\left(x_{1}\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right), \tag{25}
\end{align*}
$$

and we obtain an equation in the corner point $x_{1}=b_{1}, x_{2}=b_{2}$,

$$
\begin{align*}
0 & =-\left(\lambda_{1}+\lambda_{2}+\delta\right) V_{1}\left(b_{1}, b_{2}\right)+c_{1} \\
& +\lambda_{1} \cdot \int_{0}^{b_{1}} V_{1}\left(b_{1}-z, b_{2}\right) f_{Y_{1}}(z) d z \\
& +\lambda_{2} \cdot\left(\int_{0}^{b_{2}} V_{1}\left(b_{1}, b_{2}-z\right) f_{Y_{2}}(z) d z+V\left(b_{1}\right) \cdot\left(1-F_{Y_{2}}\left(b_{2}\right)\right)\right) . \tag{26}
\end{align*}
$$

As in Section 3, one can compare (23) to (24) and (25) to produce the following boundary conditions using the continuity of $V_{1}\left(x_{1}, x_{2}\right)$,

$$
\begin{align*}
& \frac{\partial V_{1}}{\partial x_{1}}\left(b_{1}, x_{2}\right)=\frac{\partial V_{1}}{\partial x_{2}}\left(b_{1}, x_{2}\right) \forall 0 \leq x_{2}<b_{2},  \tag{27}\\
& \frac{\partial V_{1}}{\partial x_{1}}\left(x_{1}, b_{2}\right)=\frac{\partial V_{1}}{\partial x_{2}}\left(x_{1}, b_{2}\right) \forall 0 \leq x_{1}<b_{1}, \tag{28}
\end{align*}
$$

and comparing (23) to (26) finally yields in $\left(b_{1}, b_{2}\right): c_{1} \frac{\partial V_{1}}{\partial x_{1}}\left(b_{1}, b_{2}\right)+c_{2} \frac{\partial V_{1}}{\partial x_{2}}\left(b_{1}, b_{2}\right)=c_{1}$. The system of equations (23), (27) and (28) is solved by $V_{1}\left(x_{1}, x_{2}\right)$.

Exponential claims. Again we consider the exponential claim size case with $Y_{1} \sim \operatorname{Exp}\left(\nu_{1}\right)$ and $Y_{2} \sim \operatorname{Exp}\left(\nu_{2}\right)$, and applying $\left(\frac{d}{d x_{1}}+\nu_{1}\right)$, followed by the operator $\left(\frac{d}{d x_{2}}+\nu_{2}\right)$, transforms (23) into the PDE

$$
\begin{align*}
0 & =-\delta \nu_{1} \nu_{2} V_{1}\left(x_{1}, x_{2}\right)+\left(c_{1} \nu_{1} \nu_{2}-\nu_{2}\left(\delta+\lambda_{1}\right)\right) \frac{\partial V_{1}}{\partial x_{1}}\left(x_{1}, x_{2}\right) \\
& +\left(c_{2} \nu_{1} \nu_{2}-\nu_{1}\left(\delta+\lambda_{2}\right)\right) \frac{\partial V_{1}}{\partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +\left(c_{1} \nu_{1}+c_{2} \nu_{2}-\delta-\lambda_{1}-\lambda_{2}\right) \frac{\partial^{2} V_{1}}{\partial x_{1} \partial x_{2}}\left(x_{1}, x_{2}\right) \\
& +c_{1} \nu_{2} \frac{\partial^{2} V_{1}}{\partial x_{1}^{2}}\left(x_{1}, x_{2}\right)+c_{2} \nu_{1} \frac{\partial^{2} V_{1}}{\partial x_{2}^{2}}\left(x_{1}, x_{2}\right) \\
& +c_{1} \frac{\partial^{3} V_{1}}{\partial x_{1}^{2} \partial x_{2}}\left(x_{1}, x_{2}\right)+c_{2} \frac{\partial^{3} V_{1}}{\partial x_{1} \partial x_{2}^{2}}\left(x_{1}, x_{2}\right) . \tag{29}
\end{align*}
$$

In analogy to the expected time of ruin case, the dynamics of the function $V_{1}\left(x_{1}, x_{2}\right)$ are now defined locally in the interior of $\left[0, b_{1}\right] \times\left[0, b_{2}\right]$. The explicit solution of (29) together with the corresponding IDE and boundary conditions is of similar complexity as for $\gamma_{1}$.

## 5 A Simulation Study

In the following we suggest an efficient Monte Carlo algorithm to numerically compute $\gamma_{1}\left(x_{1}, x_{2}\right)$ and $V_{1}\left(x_{1}, x_{2}\right)$. We will then compare the results with the ones for the stand-alone case, for which explicit formulas are available for exponential claim sizes (cf. Remarks 1 and 2). The aim is to identify decision-theoretical aspects for the justification of a capital-exchange agreement, as compared to the performance in the stand-alone situation.

### 5.1 A Monte Carlo Algorithm

To set up an efficient algorithm for producing MC estimates of $\gamma_{1}\left(x_{1}, x_{2}\right)$ and $V_{1}\left(x_{1}, x_{2}\right)$, we observe the following:

- $U_{1}$ can only drop negative at a jump time of $S_{1}(t)$, hence we only have to check the surplus at jump times to see when to stop the process.
- In between any two claim arrivals (from either $S_{1}$ or $S_{2}$ ), the surplus processes grow at constant rates $\tilde{c}_{1} \in\left\{0, c_{1}, c_{1}+c_{2}\right\}$ and $\tilde{c}_{2} \in\left\{0, c_{2}, c_{1}+c_{2}\right\}$, respectively.

The Expected Time of Ruin. The two aggregate claim processes can be combined into one compound Poisson process with intensity $\lambda_{1}+\lambda_{2}$ and a claim $\tilde{Y}_{i}$ comes with probability $\lambda_{1} /\left(\lambda_{1}+\right.$ $\lambda_{2}$ ) from $I_{1}$ with distribution function $F_{Y_{1}}(y)$ and with probability $\lambda_{2} /\left(\lambda_{1}+\lambda_{2}\right)$ from $I_{2}$ with distribution function $F_{Y_{2}}(y)$. In the implementation, we hence generate jump times and jump sizes for this combined process. The triples $Z_{j}=\left(t_{j}, \eta_{j}, \tilde{Y}_{j}\right)$ reflect the claim arrival times $t_{j}$, a marker $\eta_{j}=1$ if the claim is from $I_{1}$ and $\eta_{j}=0$ otherwise, and the corresponding claim sizes $\tilde{Y}_{j}$.

Conditioning on $\left\{Z_{j}\right\}_{j \geq 1}$ we can write

$$
\begin{equation*}
\gamma_{1}\left(x_{1}, x_{2}\right)=\mathbb{E}\left[\inf \left\{t_{j} \mid U_{1}\left(t_{j}\right)<0,\left\{Z_{j}\right\}_{j \geq 1}\right\}\right], \tag{30}
\end{equation*}
$$

with $U_{1}(0)=x_{1}, U_{2}(0)=x_{2}$ and the recursions conditional on no prior ruin of the respective process can be written as

$$
\begin{align*}
U_{1}\left(t_{j+1}\right) & =\min \left[b_{1}, U_{1}\left(t_{j}\right)+c_{1}\left(t_{j+1}-t_{j}\right)\right. \\
& \left.+1_{\left\{\tau_{2}>t_{j}\right\}} \cdot c_{2}\left(\left(t_{j+1}-t_{j}\right)-\min \left(t_{j+1}-t_{j}, \frac{b_{2}-U_{2}\left(t_{j}\right)}{c_{2}}\right)\right)\right]-\eta_{j+1} \cdot \tilde{Y}_{j+1},  \tag{31}\\
U_{2}\left(t_{j+1}\right) & =\min \left[b_{2}, U_{2}\left(t_{j}\right)+c_{2}\left(t_{j+1}-t_{j}\right)\right. \\
& \left.+1_{\left\{\tau_{1}>t_{j}\right\}} \cdot c_{1}\left(\left(t_{j+1}-t_{j}\right)-\min \left(t_{j+1}-t_{j}, \frac{b_{1}-U_{1}\left(t_{j}\right)}{c_{1}}\right)\right)\right]-\left(1-\eta_{j+1}\right) \cdot \tilde{Y}_{j+1} . \tag{32}
\end{align*}
$$

For a set of samples $\left\{z_{j}^{(k)}\right\}_{j \geq 1}, 1 \leq j \leq N$, of $\left\{Z_{j}\right\}_{j \geq 1}$, we then simply compute the MC estimate of $\gamma_{1}\left(x_{1}, x_{2}\right)$ as

$$
\begin{equation*}
\hat{\gamma}_{1}\left(x_{1}, x_{2}\right)=\frac{1}{N} \sum_{k=1}^{N}\left[\inf \left\{t_{j} \mid U_{1}\left(t_{j}\right)<0,\left\{Z_{j}\right\}_{j \geq 1}=\left\{z_{j}^{(k)}\right\}_{j \geq 1}\right\}\right], \tag{33}
\end{equation*}
$$

using the recursions (31) and (32).

The Expected Discounted Dividends. We realise that no dividends are paid immediately after any claim arrival at $t_{j}$, since either the first or the second surplus process will drop below its pay-out barrier due to the claim. Hence, over the time interval $\left(t_{j}, t_{j+1}\right]$ in between two claim arrivals, either no dividends are paid or dividends are paid from a certain time $t_{j}^{\text {in }}$ over the rest of that interval. Furthermore, we note that for $t_{j}^{\text {in }}<t_{j+1}$, one can write that

$$
\begin{equation*}
\int_{t_{j}^{\text {in }}}^{t_{j+1}} c_{1} e^{-\delta s} d s=\frac{c_{1}}{\delta}\left(e^{-\delta t_{j}^{\text {in }}}-e^{-\delta t_{j+1}}\right) \tag{34}
\end{equation*}
$$

Conditioning on the claim arrivals and sizes leads to

$$
\begin{align*}
V_{1}\left(x_{1}, x_{2}\right) & =\mathbb{E}\left[\int_{0}^{\tau_{1}} c_{1} \cdot 1_{\{A\}} \cdot e^{-\delta s} d s \mid U_{1}(0)=x_{1}, U_{2}(0)=x_{2}\right] \\
& =\mathbb{E}\left[\left.\sum_{j=1}^{n-1} \frac{c_{1}}{\delta}\left(e^{-\delta t_{j}^{\text {in }}}-e^{-\delta t_{j+1}}\right) \right\rvert\, t_{0}=0, t_{n}=\tau_{1},\left\{Z_{j}\right\}_{j \leq 1}\right] \tag{35}
\end{align*}
$$

with the event $A=\left\{\left[U_{1}(s)=b_{1}, U_{2}(s)=b_{2}, \tau_{2}>s\right] \cup\left[U_{1}(s)=b_{1}, \tau_{2}<s\right]\right\}$, the payment start times

$$
t_{j}^{\text {in }}= \begin{cases}\min \left(t_{j}+\max \left(\left(b_{1}-U_{1}\left(t_{j}\right)\right) / c_{1},\left(b_{2}-U_{2}\left(t_{j}\right)\right) / c_{2}\right), t_{j+1}\right) & \text { if } \tau_{2}>t_{j} \\ \min \left(t_{j}+\left(b_{1}-U_{1}\left(t_{j}\right)\right) / c_{1}, t_{j+1}\right) & \text { if } \tau_{2} \leq t_{j}\end{cases}
$$

and $U_{1}\left(t_{j}\right)$ and $U_{2}\left(t_{j}\right)$ are defined as in (31) and (32). For a set of samples $\left\{z_{j}^{(k)}\right\}_{k \geq 1}$ of $\left\{Z_{j}\right\}_{j \geq 1}$, $1 \leq j \leq N$, we compute the MC estimate of $V_{1}\left(x_{1}, x_{2}\right)$ as

$$
\begin{equation*}
\hat{V}_{1}\left(x_{1}, x_{2}\right)=\frac{1}{N} \sum_{k=1}^{N}\left[\left.\sum_{j=1}^{n-1} \frac{c_{1}}{\delta}\left(e^{-\delta t_{j}^{\text {in }}}-e^{-\delta t_{j+1}}\right) \right\rvert\,\left\{Z_{j}\right\}_{j \geq 1}=\left\{z_{j}^{(k)}\right\}_{j \geq 1}\right] \tag{36}
\end{equation*}
$$

### 5.2 Specification and Results of the Simulation Study

We now consider the example where $I_{1}$ and $I_{2}$ have a similar insurance portfolio. We choose the income rate $c_{1}=c_{2}=6$ and claims are produced according to $\lambda_{1}=\lambda_{2}=5$ and $\nu_{1}=\nu_{2}=1$. For $I_{1}$ we specify the barrier level $b_{1}=5$, while for $I_{2}$ we will test the behavior under a low, medium or high barrier, i.e. $b_{2}=1,5$ or 20 . Initially we consider the functions $\gamma_{1}\left(x_{1}, x_{2}\right)$ and $V_{1}\left(x_{1}, x_{2}\right)$, with $0 \leq x_{1} \leq b_{1}$ and $0 \leq x_{2} \leq b_{2}$. Due the symmetry reason, we only present the plots for $I_{1}$.

First, consider Figure 3 for the expected time of ruin of $I_{1}$. We observe that $\gamma_{1}\left(x_{1}, x_{2}\right)$ is monotonically increasing in both $x_{1}$ and $x_{2}$. This is as expected, since possible recapitalisation payments


Figure 3: The $\gamma_{1}\left(x_{1}, x_{2}\right)$ surface for $b_{1}=5$, and $b_{2}=1,5,20$ (for $N=50,000$ simulation runs).
from the partner increase the likelihood of survival, and a higher initial surplus of the partner leads to a higher probability of such payments being made in the future. In the case of the expectation of the sum of discounted dividends, as depicted in Figure 4, the plots are of a different shape. As $b_{2}$ increases, the expected discounted dividends become large as $x_{2}$ is either small or large. This reflects that dividend payments are blocked as long as $U_{2}$ moves within $\left[0, b_{2}\right)$. Early ruin of the partner brings a relative improvement as own profits lead to immediate dividend payments, and the other favorable situation is where $I_{2}$ has high surplus and reaches its barrier $b_{2}$ early. Otherwise we note that upon fixing $x_{2}, V_{1}$ is naturally an increasing function in $x_{1}$. Altogether, $V_{1}$ appears to generally decrease as $b_{2}$ grows.


Figure 4: The $V_{1}\left(x_{1}, x_{2}\right)$ surface for $b_{1}=5$ and $b_{2}=1,5,20$, and $\delta=0.1$ (for $N=50,000$ simulation runs).

Comparison to the stand-alone case. We now compare the above results to the stand-alone case by considering the plots $\gamma_{1}\left(x_{1}, x_{2}\right)-\gamma_{1}^{(0)}\left(x_{1}\right)$ and $V_{1}\left(x_{1}, x_{2}\right)-V_{1}^{(0)}\left(x_{1}\right)$, in order to reason in what situations it would turn out profitable to enter into the capital-exchange agreement for the given barrier combinations.

Figure 5 confirms that an increase in the expected time of ruin is achieved across all $\left(x_{1}, x_{2}\right)$ combinations. In the top left graph where $b_{2}$ is low, the effect is strongest when $x_{1}$ is small and $x_{2}$ is relatively high. However, note that $x_{2} \leq 1$ is low due to $b_{2}=1$, so that the benefit from possible recapitalisation payments decreases as $x_{1}$ becomes larger relative to $x_{2}$. This features becomes


Figure 5: The $\gamma_{1}\left(x_{1}, x_{2}\right)-\gamma_{1}^{(0)}\left(x_{1}\right)$ surface for $b_{1}=5$, and $b_{2}=1,5,20$ (for $N=50,000$ simulation runs).
less and less pronounced as $b_{2}$ increases., and we observe in those cases that the gain is naturally largest when $x_{2}$ is high. Figure 6 then shows the change in the expected discounted dividends. In the case $b_{2}=1$, the gain is highest where $x_{1}$ is low and $x_{2}$ is close to $b_{2}$. This is justified, as $I_{2}$ is more likely to recapitalise $I_{1}$ so that it may reach its barrier faster. As $x_{1}$ approaches its own barrier $b_{1}$, the change in expected discounted dividends from the agreement drops negative, as now the risk of having to support $I_{2}$ instead paying early dividends becomes more pronounced. This notion of possibly having to support $I_{2}$ rather than paying dividends becomes so strong for $b_{2}=5$ and $b_{2}=20$, that the effect on the expected discounted dividends is negative for almost all cases, and large surplus levels $x_{1}$ produce the worst outcomes.


Figure 6: The $V_{1}\left(x_{1}, x_{2}\right)-V_{1}^{(0)}\left(x_{1}\right)$ surface for $b_{1}=5$ and $b_{2}=1,5,20$, and $\delta=0.1$ (for $N=50,000$ simulation runs).

Note that as $b_{2} \rightarrow \infty, V_{1}\left(x_{1}, x_{2}\right)$ will tend to zero as excess capital will only go to the partner. We conclude that for low own surplus levels and low barriers $b_{2}$ of the partner, the capital-exchange agreement can appear attractive in certain situations, while for larger own surplus levels, the possibility of having to recapitalise the partner clearly outweighs the effect from possible incoming support payments.

As the effects of the agreement on the expected time of ruin and the expectation of the discounted dividends are in opposite directions across most of the here considered cases, one will generally


Figure 7: Balancing dividends and ruin time: $w=0.2,0.5$ and 0.8 , with $b_{1}=5$ and $b_{2}=1$, and $\delta=0.1$ (for $N=50,000$ simulation runs).
have to balance the wish for a long lifetime against the desire to receive early dividends. This is illustrated in Figures 7 to 9, where low, medium or high weight is given to the expected time of ruin. It is especially for high barriers $b_{2}$ of the partner and high own surplus levels, that the preference for an expected increase in lifetime must be strong in order to justify entering the agreement, which becomes particularly clear from Figure 9.

Effect on the system of the two insurers. Finally, we investigate the effect of the capitalexchange agreement on the system of the two insurers against the stand-alone case. Hereby, we choose to compare the sums of the expected ruin times (one could also choose a different


Figure 8: Balancing dividends and ruin time: $w=0.2,0.5$ and 0.8 , with $b_{1}=5$ and $b_{2}=5$, and $\delta=0.1$ (for $N=50,000$ simulation runs).
criterion, such as the maximum time of ruin of the two) and the expected discounted dividends, respectively. In particular, we evaluate $\gamma_{1}\left(x_{1}, x_{2}\right)+\gamma_{2}\left(x_{1}, x_{2}\right)-\gamma_{1}^{(0)}\left(x_{1}\right)-\gamma_{2}^{(0)}\left(x_{2}\right)$ and $V_{1}\left(x_{1}, x_{2}\right)+V_{2}\left(x_{1}, x_{2}\right)-V_{1}^{(0)}\left(x_{1}\right)-V_{2}^{(0)}\left(x_{2}\right)$.

Regarding the system gains for the expected ruin times, as depicted in Figure 10, naturally all cases return positive results. In the case where one barrier is larger than the other (i.e. $b_{1}=5, b_{2}=1$ and $b_{1}=5, b_{2}=20$ ) the positive effect appears to be largest in those cases where the process with the lower barrier starts close to the barrier while the process with the larger barrier has little initial surplus. For the expectation of the sum of the discounted dividends, as shown in Figure


Figure 9: Balancing dividends and ruin time: $w=0.2,0.5$ and 0.8 , with $b_{1}=5$ and $b_{2}=20$, and $\delta=0.1$ (for $N=50,000$ simulation runs).

11, a negative effect from the agreement is observed throughout, with the highest relative impact when both initial surplus levels are high. Again, it seems that in view of the whole system of the two insurers, putting a capital-exchange agreement in place must mostly be justified by a strong preference of extending the expected lifetimes of the insurers.

## 6 Concluding Remarks

In this paper we investigated the impact of a capital-exchange agreement on the expected time of ruin and the expected discounted dividends of insurers. Such an agreement could for example


Figure 10: System gains in the expected ruin time for $b_{1}=5$, and $b_{2}=1,5,20$ (for $N=50,000$ simulation runs).
exist among entities within an insurance group, as they recapitalise each other until the surplus processes of all subsidiaries run at some satisfactory levels; only then dividends are released to the shareholders. We have characterised the expected ruin time and the expected discounted dividends in this setup by deriving a set of equations in each case. The results of a Monte Carlo simulation study finally illustrated that the agreement naturally improves the expected time of ruin. This is the case from the viewpoint of each insurer that has assumed the agreement, and hence, also improves the expected ruin time across the system of the participating insurers. The effect on the dividends is found to be twofold. For low barrier levels of the partner, a positive effect is observed if one's own initial surplus is low. As either the partner's barrier increases, or the insurer own initial


Figure 11: System gains in the expectation of total dividends for $b_{1}=5$ and $b_{2}=1,5,20$, and $\delta=0.1$ (for $N=50,000$ simulation runs).
surplus is close to its barrier level, the effect on the expected discounted dividends appears negative. Asymptotically for some $b_{i} \rightarrow \infty$, the expected discounted dividends of all participating companies tends to zero, as dividend payments are blocked due to their recapitalisation obligation for insurer $i$. We conclude that in many situations a strong preference for an increase in the expected lifetime is required to justify entering the capital-exchange agreement. This effect is observed for single insurers, as well as from a systemic point of view.

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