

1 **Facies discrimination with ERT using a probabilistic methodology: effect of**
2 **sensitivity and regularization**

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21 **Abstract**

22 Electrical resistivity tomography (ERT) has become a standard geophysical method in the
23 field of hydrogeology, as it has the potential to provide important information regarding the
24 spatial distribution of facies. However, inverted ERT images tend to be grossly smoothed
25 versions of reality because of the regularization of the inverse problem. In this study, we use a
26 probabilistic methodology based upon co-located measurements to assess the utility of ERT to
27 identify hydrofacies in alluvial aquifers. With this methodology, ERT images are interpreted
28 in terms of the probability of belonging to pre-defined hydrofacies. We first analyze through a
29 synthetic study the ability of ERT to discriminate between different facies. As ERT data
30 suffer from a loss of sensitivity with depth, we find that low sensitivity regions are more
31 affected by misclassification. To counteract this effect, we adapt the probabilistic framework
32 to include the spatially varying data sensitivity. We then apply our learning to a field case. For
33 the latter, we consider two different regularization procedures. In contrast to the data
34 sensitivity which affects the facies probability to a limited amount, the regularization can
35 affect the probability maps more considerably because it has a strong influence on the spatial
36 distribution of inverted resistivity. We find that a regularization strategy based on the most
37 realistic prior information tends to offer the most reliable discrimination of facies. Our results
38 confirm the ability of ERT surveys, when properly designed, to detect facies variations in
39 alluvial aquifers. The method can be easily extended to other contexts.

40

41 **Keywords:** electrical resistivity tomography, alluvial aquifers, probability distribution,
42 sensitivity, regularization, inversion, facies discrimination.

43

44 INTRODUCTION

45 Over the past two decades, electrical resistivity tomography (ERT) has become a standard
46 geophysical technique in the field of hydrogeology (Binley et al., 2015). However, a relatively
47 high level of uncertainty always accompanies the interpretation of the corresponding
48 tomograms, which often renders the direct use of ERT images difficult. In particular, the
49 interpretation of complex and heterogeneous geological systems such as alluvial aquifers and
50 the quantitative integration of geophysical data into subsurface hydrological models require
51 consideration of a number of important issues such as the petrophysical relationships linking
52 geophysical and hydrological parameters (e.g., Doetsch et al., 2010), the spatially-dependent
53 resolution of tomograms (e.g., Day-Lewis et al. 2005), and the effect of regularization on the
54 resulting images (e.g., Caterina et al., 2014). To address these issues, several approaches have
55 been developed including using synthetic simulations to explore petrophysical relationships
56 (Moysey et al., 2005; Singha and Moysey, 2006), performing coupled hydrogeophysical
57 inversion (Hinnel et al., 2011; Irving and Singha, 2010), using image appraisal tools to
58 identify zones of the tomogram that can be reliably interpreted (Caterina et al. 2013, Beaujean
59 et al. 2014), the use of novel regularization approaches (e.g., Blaschek et al., 2008; Hermans
60 et al., 2012, Oware et al., 2013), and the incorporation of structural information into the
61 inversion (e.g., Caterina et al., 2014; Doetsch et al., 2012a).

62 The above-mentioned studies have enhanced the imaging capabilities of ERT and broadened
63 its range of applications, but they are generally not sufficient to answer the question of
64 reliability of the results for a specific purpose. Indeed, in many cases, one wishes to perform a
65 geological interpretation of the tomogram in terms of facies or hydrofacies. Given the limited
66 resolution of the ERT experiment, the typically restricted number of ground-truth data, and
67 the non-uniqueness of inverted geophysical models, carrying out such an interpretation is not
68 straightforward. It is therefore critical that we develop methodologies to quantify the ability of

69 ERT to detect facies; that is, to indicate what facies is present at each subsurface location
70 along with a corresponding uncertainty estimate.

71 To identify facies based on geophysical data, a number of studies have utilized multi-
72 parameter analysis and clustering to perform subsurface zonation. Relating the clusters to
73 facies through their geophysical parameters enables a straightforward classification. Fuzzy
74 clustering, through partial memberships, also allows for uncertainty assessment. Paasche et al.
75 (2006) proposed such a clustering approach to perform subsurface zonation based on georadar
76 and seismic data. Paasche and Tronicke (2007) even included the clustering approach in the
77 inversion procedure to obtain a common model of georadar and P-wave velocities with
78 zonation. Doetsch et al. (2010) performed joint inversion of GPR, seismic and ERT data to
79 obtain a three-facies zonation (gravel, sand, clay) in an alluvial aquifer. Although such
80 clustering approaches are highly useful, a significant drawback is that they require having
81 multi-method geophysical data, the latter of which are not always available.

82 In this paper, we focus on the ability of a single geophysical method (ERT) to provide a facies
83 classification. To this end, we rely on a Bayesian framework for post-processing the outcomes
84 of classical regularized inversion. The Bayesian framework offers an easy and straightforward
85 way to express geophysical parameters in terms of categories, deriving a probability
86 distribution for the sought parameters (here the facies or hydrofacies) instead of a single
87 “best” estimate (Ezzedine et al., 1999; Rubin and Hubbard, 2005). The corresponding
88 likelihood function can be estimated using co-located measurements of the inverted
89 geophysical parameter and the textural description. Such a relationship enables accounting for
90 the uncertainty resulting from the inversion process (regularization and noise) as well as data
91 sensitivity. It is also straightforward to integrate such a Bayesian relationship into stochastic
92 simulations involving Gaussian or multiple-point statistics. As an example, Ruggeri et al.
93 (2013, 2014) developed a methodology to integrate geophysical data into hydraulic

94 conductivity sequential simulations through a Bayesian relationship. They took into account
95 the variable resolution of the tomograms by adapting the likelihood function to the level of
96 uncertainty of their resistivity estimates. Hermans et al. (2015a) used a Bayesian framework
97 to transpose ERT inversions into soft probability maps used to constrain multiple-point
98 geostatistical simulations of an alluvial aquifer within the context of facies-based
99 hydrogeological inversion. However, they did not integrate sensitivity dependence nor did
100 they analyze the effect of regularization on the proposed probability maps.

101 Here, we assess the ability of ERT to identify facies in an alluvial aquifer. Alluvial aquifers
102 are generally composed of several facies and lithologies (clay, loam, sand, gravel) with
103 complex architectures and interconnections depending on the fluvial system (channels, bars,
104 point bars, crevasse splays, floodplains, levees, etc.). In this context, borehole logs and
105 classical hydrogeological tests (pumping, slug or tracer tests) may not be sufficient to capture
106 the complexity of the deposits and determine their influence on groundwater flow and solute
107 transport (e.g. Wildemeersch et al., 2014). ERT is a well-suited tool to study alluvial deposits
108 as it is sensitive to the texture of the deposits (porosity, tortuosity, clay content) and to the
109 pore-fluid. ERT has already been widely used to image deposits in alluvial aquifers and to
110 improve the understanding of the depositional model (Baines et al., 2002; Bowling et al.,
111 2005, 2007; Bersezio et al., 2007; Mastrocicco et al., 2010; Doetsch et al., 2010, 2012a). The
112 use of ERT is also common in time-lapse mode to monitor changes taking place in alluvial
113 deposits due to, for example, contaminant degradation (e.g., Chambers et al., 2010; Masy et
114 al., 2016), salt tracer experiments (e.g., Doetsch et al., 2012b), or thermal tracer experiments
115 (e.g., Hermans et al., 2015b).

116 The paper is organized as follows. First, the methods used in this study are described. Then,
117 we analyze through a synthetic study the ability of ERT to discriminate between different
118 facies. As ERT suffers from a loss of sensitivity with depth, low sensitivity regions are more

119 affected by misclassification. We therefore propose to adapt our Bayesian framework to
120 include the spatially varying sensitivity and counterbalance this effect. Next, we apply this
121 learning to a field case, where we consider two different regularization procedures to
122 investigate the role of the inversion method and its underlying assumptions on the different
123 facies probability maps.

124 **METHODS**

125 **ERT inversion**

126 The ERT forward problem is non-linear and non-unique, typically characterized by a large
127 number of subsurface model parameters and relatively few data (e.g., Aster et al., 2005). To
128 address the issue of non-uniqueness in the corresponding inverse problem, regularization is
129 normally used (e.g., Tikhonov and Arsenin, 1977) whereby prior information regarding the
130 model parameters is considered in order to obtain a single solution. The basic idea of
131 deterministic inversion is to minimize an objective function of the form

$$132 \quad \psi(\mathbf{m}) = \psi_d(\mathbf{m}) + \lambda \psi_m(\mathbf{m}) \quad (1)$$

133 where the first term on the right-hand side of equation (1) expresses the data misfit and the
134 second term quantifies some undesired characteristic of the model, for example its
135 “roughness” as measured by a first or second derivative operator. The regularization
136 parameter λ then controls the balance between minimizing these two terms in the inversion
137 procedure. In this paper, we consider two regularization operators. The “smoothness
138 constraint” regularization operator, used in the vast majority of geophysical inversions, is
139 used for both the synthetic and field cases. For the field case only, we also consider
140 geostatistical regularization (Hermans et al., 2012), which is based on a prior definition of the
141 model parameter covariance matrix.

142 To invert ERT data in this study, we used the finite-element inversion code CRTomo (Kemna,
 143 2000) which seeks to iteratively minimize equation (1) until the root-mean-square of the
 144 weighted data misfit, $\varepsilon_{RMS} = \sqrt{\frac{\psi_d(\mathbf{m})}{N}}$ with N representing the number of data, reaches a
 145 value of 1. The overall aim is to fit the data to its assumed level of error under the condition
 146 that the model functional is minimized. Parameter λ is optimized during each iteration through
 147 a line search to minimize the data misfit.

148 **Data sensitivity**

149 Data sensitivity is commonly used as an image appraisal tool for ERT inversions (e.g.,
 150 Caterina et al., 2013). As with resolution, the sensitivity of a tomogram varies spatially,
 151 generally showing a decreasing trend with depth for surface arrays. In this study, we use the
 152 error-weighted cumulative sensitivity as an indicator of the quality of an inversion result,
 153 which is defined as (Kemna, 2000)

$$154 \quad \mathbf{S} = \text{diag}\{\mathbf{J}^T \mathbf{W}_d^T \mathbf{W}_d \mathbf{J}\}, \quad (2)$$

155 where \mathbf{W}_d is the data weighting matrix, \mathbf{J} is the Jacobian matrix and T denotes the transpose
 156 operator. Values of \mathbf{S} depend on the distribution of resistivity in the subsurface and data
 157 errors. We normalize \mathbf{S} by its maximum value so that its values are lower or equal to one and
 158 we express it on a logarithmic scale. A high value means a strong influence of the
 159 corresponding model parameter on the predicted data and is therefore a favoring factor for a
 160 good resolution. Hereafter, we will use the term “sensitivity” to denote this normalized
 161 cumulative sensitivity.

162 **Bayesian facies probability**

163 To discriminate hydrofacies based on inverted ERT images, we use co-located ERT and
 164 facies description data to first determine the distribution of inverted resistivity $f(\rho|A_i)$
 165 corresponding to each facies A_i as well as the facies proportion $P(A_i)$. We also consider
 166 sensitivity-dependent resistivity distributions $f(\rho|A_i, S_j)$, where S_j denotes model cells having a
 167 given sensitivity class. The latter is defined on a logarithmic scale by decade (i.e., from 1 to
 168 10^{-1} , 10^{-1} to 10^{-2} , etc.). For the field case, co-located data correspond to borehole locations,
 169 where observations of facies can be compared with the ERT-derived resistivities. For the
 170 synthetic case, we have access to the facies distribution at all locations throughout the model
 171 space. Using Bayes' rule, we can then compute the conditional probability of observing a
 172 facies given the resistivity and sensitivity values as follows:

$$173 \quad P(A_i | \rho, S_j) = \frac{f(\rho | A_i, S_j)P(A_i)}{\sum_i f(\rho | A_i, S_j)P(A_i)}. \quad (3)$$

174 **Performance indicators**

175 Equation (3) can be applied to an inverted resistivity profile and the resulting facies
 176 probabilities can be used to assess the ability of ERT to identify those facies. In this regard,
 177 we define two indicators of performance in this paper:

178 1) The classification performance (expressed in %). Each cell of the tomogram is
 179 assigned the facies having the highest probability and the number of correctly
 180 classified cells is counted.

181 2) The probability performance (expressed in %), which is calculated using

$$182 \quad \xi = 100 \times \frac{1}{n} \sum_{k=1}^n \omega_k \max_i \{P(A_i | \rho, S)\} \quad (4)$$

183 where n is the number of cells in the tomogram and ω_k is a weight equal to 1 if the cell
 184 is correctly classified according to the classification performance indicator, i.e. when

185 the correct facies has the highest probability, and -1 otherwise. The philosophy of this
186 indicator is to reward when a facies is correctly identified as the most probable and to
187 penalize otherwise. In contrast with the classification performance indicator, it takes
188 into account, through the maximum conditional probability $P(A_i|\rho,S)$, the uncertainty
189 of the estimate. The final score is between -100 and +100%, the latter of which is
190 obtained if all cells have a probability of 100% for the correct facies. A negative value
191 indicates that the method is not appropriate to detect facies since it would provide in
192 average more bad than correct information.

193 **STUDY SITE**

194 The study site for our field case is located in the alluvial aquifer of the Meuse River, in
195 Hermalle-sous-Argenteau (Belgium) near the Dutch-Belgian border (Figure 1A and B),
196 between the Meuse River and the Albert Canal. This is an experimental site of the University
197 of Liege used for hydrogeophysical field experiments (e.g., Wildemeersch et al., 2014;
198 Hermans et al., 2015b). A detailed description can be found in Hermans et al. (2015a, 2015b).

199 Alluvial deposits at the site are 10-m thick and mostly composed of sandy gravel with large
200 zones of clean gravel (and pebbles) having a higher hydraulic conductivity and zones
201 composed of loam, clay and clayey gravel of lower hydraulic conductivity. A total of 23
202 boreholes are available at the site with a corresponding textural description (Figure 1C and 2).
203 Based on the observed heterogeneity, we chose to describe the deposits using three
204 hydrofacies. The first facies is composed of low hydraulic conductivity deposits (clay and
205 loam). The second facies is composed of clean gravel with high hydraulic conductivity.
206 Finally, the third facies is made up of sand/sandy gravel and has an intermediate hydraulic
207 conductivity. The respective facies proportions from borehole logs are 18%, 42% and 40%.

208 Clay deposits are mostly limited to the surface, and gravel is generally found below sand in
209 the bottom part of the aquifer. The thickness of the sand is variable (Figure 2).

210 We conducted 12 parallel ERT profiles at the site (Figure 1C) using 64 electrodes spaced
211 every 2 m (total length of 126 m) except for the northern profile which is only 102 m long.
212 We used a dipole-dipole configuration to collect the data with dipole lengths from 2 to 18 m
213 and dipole separations from 1 to 6 dipole lengths. We used reciprocal measurements to assess
214 the quality of the data. A linear error model was deduced to weight the data during the
215 inversion (\mathbf{W}_d in equation 2) having the form (Slater et al., 2000)

$$216 \quad |e| = a + bR \quad (5)$$

217 where $|e|$ is the absolute reciprocal error (in Ohm), a is the absolute error equal to 0.002 Ohm,
218 b is the relative error equal to 0.26%, and R is the mean resistance (in Ohm).

219 **SYNTHETIC VALIDATION**

220 In this section, we use synthetic simulations to assess the ability of ERT to discriminate facies
221 and we examine the effect of the varying data sensitivity on the classification and probability
222 performance metrics. In the next section, a similar approach is applied to the Meuse River
223 field data.

224 **Description of the set-up**

225 The synthetic benchmark is based on 96 synthetic models simulating alluvial deposits as they
226 could be expected at the study site described in Section 3. The considered model domain is
227 126 m wide by 10 m deep, which was discretized into 1 m x 0.5 m cells to yield a total of
228 2540 model parameters. Below 10 m, we simulated the presence of resistive (300 Ohm.m)
229 bedrock, which is not considered in our interpretations.

230 The alluvial deposits are composed of three hydrofacies corresponding to those observed at
231 the field site. The sand facies is considered as the background and was prescribed a resistivity
232 of 250 Ohm.m. The clay (100 Ohm.m) and gravel (140 Ohm.m) facies were simulated
233 respectively as lenses and channels of various sizes using 3D Boolean simulations (Maharaja,
234 2008) with proportions similar to the ones observed at the field site. The resistivity values
235 chosen for each facies were based on values observed in the field. A number of 2D sections
236 were randomly selected from the 3D models (Figure 3A and D).

237 A dipole-dipole ERT data set was then simulated for each model and contaminated by noise
238 having a similar level to that observed in the field. The data sets were subsequently inverted
239 using the standard smoothness constraint. Facies probabilities were estimated after inversion
240 in order to determine the classification and performance indicators for each model, both with
241 and without taking the data sensitivity into account.

242 **Inversion of synthetic models and sensitivity dependence**

243 Figure 3 shows two examples of synthetic facies models along with their respective inverted
244 resistivity tomograms and sensitivity distributions. It can be seen from the resistivity
245 tomograms (Figure 3A-B and 3D-E) that ERT is able to qualitatively locate overall the clay
246 and gravel facies, which correspond to low resistivity values inside the sand facies. However,
247 smaller clay lenses are not detected and facies discrimination in the bottom part of the images
248 is more challenging. Both of these effects are expected; the first is related to the resolution
249 capabilities of ERT, whereas the second is related to the decrease of sensitivity with depth, as
250 clearly illustrated by Figure 3C and F.

251 The presence of three different facies is also challenging in this case. Clay lenses and gravel
252 channels both represent low resistivity anomalies compared to the background sand facies.
253 Therefore, their juxtaposition among the deposits is difficult to resolve. More precisely, clay

254 lenses in the bottom part of the deposits tend to display resistivity values close to those of the
255 gravel facies.

256 The synthetic benchmark allows the comparison of the inverted resistivity value and facies
257 identity for about 250,000 cells, thus providing a good test of the ability of ERT to detect
258 facies as well as allowing us to analyze the dependency of the results upon data sensitivity.
259 Figure 4A shows the mean and 95% interval of inverted resistivity for each facies as a
260 function of the value of relative cumulative sensitivity, as well as the global values for the
261 case where sensitivity is not taken into account (Total). We see that for high sensitivity values
262 above 10^{-3} , which correspond to a maximum depth of about 5 m (Figure 3), the facies
263 resistivities are well separated. In particular, sand and gravel show no overlap, meaning that
264 ERT is able to almost unequivocally identify the presence of sand in high sensitivity regions
265 (Figure 4B). It is more difficult to discriminate between clay and gravel due to their close
266 resistivity values. For sensitivities between 10^{-3} and 10^{-5} , the sensitivity-dependent
267 distributions are relatively close to the global distributions, although with smaller ranges of
268 variation because they are not affected by the shallow cells like the total distribution. As a
269 result, the corresponding conditional probability distributions computed from equation 3
270 (Figure 4B) are flatter and thus less discriminating. For sensitivity values below 10^{-5} , the
271 sensitivity-dependent resistivity distributions are superimposed upon one another, which
272 means that the resolving power of ERT for facies discrimination is weak or non-existent.
273 Those sensitivity values are limited to the bottom corners of the grid or to the deep cells
274 (bedrock) not considered here.

275 Overall, we see that the means of the sensitivity-dependent inverted resistivity distributions
276 follow a clear trend towards a similar value when sensitivity decreases, which results from the
277 decreasing resolution of ERT with depth. This value is related to the starting or reference
278 model used for the inversion, which in this case is the mean apparent resistivity of the data.

279 Conversely, the 95% bounds do not follow a clear trend, but they are smaller than the ones
280 from the global distributions.

281 The conditional probabilities (Figure 4B) can be used to transform each resistivity distribution
282 into three probability maps, one for each considered facies. For a given cell, the three
283 probabilities sum to 1. We illustrate the process in Figure 5 for the second model presented in
284 Figure 3D, where we show the probability maps for gravel, sand, and clay that were obtained
285 using the global probability distributions (Figures 5A to 5C) as well as the sensitivity-
286 dependent distributions (Figures 5D to F). Gravel is the most challenging facies in our
287 example since it corresponds to intermediate resistivity values, and will therefore never reach
288 a probability equal to 1. We see in Figure 5 that high resistivities correspond to high
289 probability values for sand whereas low resistivities correspond to high probability values for
290 clay. In contrast, intermediate resistivities (around 160 Ohm.m) signify a higher probability
291 for the gravel facies. Using sensitivity-dependent distributions, the values of the probability
292 maps are more discriminant near the surface (first 5 m). Indeed, low values tend to be closer
293 to zero and high values tend to be slightly closer to 1. This trend can be observed for all
294 facies. Below 5 m, fewer changes are visible. We can detect a few locations where the
295 probability of gravel, although relatively high, decreases when the sensitivity-dependent
296 distributions are considered. The reason for this is that in low sensitivity regions, the
297 sensitivity-dependent distributions are less discriminant than the global ones (e.g. Figure 5D,
298 $X = 30\text{m}$ and $Y = 9\text{m}$), which means that even if the inverted resistivity seems to correspond
299 to gravel, we are less confident in this estimation and therefore attribute a lower probability to
300 it. In turn, the probability of sand or clay increases.

301 Note that we do not see strong differences in the probability maps when taking into account
302 the sensitivity-dependent distributions.. The reason for this is that the design of the survey is
303 such that the sensitivity values at 10 m depth are still reasonable (around 10^{-4} , see Figures 3C

304 and F). For those sensitivity values, the sensitivity-dependent distributions are still at least as
305 discriminant as the global ones (Figure 4). If we tried to interpret models below 10 m depth,
306 we would observe a clear decrease in the probability. This illustrates the crucial importance of
307 survey design if the sensitivity is not taken into account during interpretation. The
308 comparison of global and sensitivity-dependent results with the probabilistic methodology for
309 synthetic models can be used to assess the validity of survey design choices and estimate the
310 depth of investigation; as long as the probability maps from the sensitivity-dependent
311 relationships are more discriminant than the global distributions, the sensitivity can be
312 considered as sufficient for interpretation. Global distributions will lead to conservative
313 interpretations. For lower sensitivities, ignoring the sensitivity-dependence bears the risk of
314 over-interpretation of the ERT images.

315 **Facies discrimination performance**

316 The more discriminant behavior of the sensitivity-dependent probabilistic relationship near
317 the surface indicates that it will provide sharper probability estimates and better facies
318 discrimination. We now quantify the benefit of using the sensitivity-dependent relationships
319 with the performance indicators of Section 2.4.

320 For facies classification, the facies with the highest probability is assigned to each cell. An
321 example is shown in Figure 6 for the model corresponding to Figure 3D. We use transparency
322 to indicate the probability corresponding to the most probable facies. That is a fully
323 transparent (white) cell corresponds to a maximum probability of 33%, i.e. for which all of
324 the facies have the same probability and the classification is impossible. A completely opaque
325 cell, on the other hand, corresponds to a facies probability of 100%. In comparison with the
326 true facies (Figure 6A), we see that the classification of the sand facies is relatively accurate
327 (Figure 6C), especially in the upper part of the model. Figure 6D is an indicator map of

328 misclassification. Most misclassifications occur between the gravel and clay facies. This is
329 expected given their respective resistivity. In the case of only two facies, ERT would
330 therefore be more discriminating (Table 1).

331 Note in Figures 6E and 6F that there are few differences in the classification when sensitivity
332 is taken into account. Globally, the same structures are observed. Even though sensitivity
333 plays a role in the discrimination of facies, it remains the inverted resistivity value which
334 orientates the classification. Indeed, with sensitivity dependence, a facies may have a higher
335 or lower probability, but it may not always be sufficient to modify the order between facies
336 and thus the classification.

337 The overall performance of the classification procedure is summarized in Table 1. On average
338 for all of the models, 65% of the cells are correctly classified whatever method is used. The
339 average risk of misclassification is therefore 35%. Within the 96 synthetic models, the
340 minimum classification performance is about 50% and the maximum is 79%. As observed in
341 Figure 6, misclassified cells are mainly between clay and gravel. If such misclassifications are
342 disregarded, the average performance increases up to 79%. This means that increasing the
343 number of facies to detect will inevitably degrade the performance. In our case, this is
344 however mandatory because clay and gravel have opposite hydrogeological behaviors. Other
345 misclassifications occur at the transition between facies.

346 Table 2 examines in greater detail the ability to classify cells according to sensitivity. Below
347 values of 10^{-5} , less than 50% of the cells are correctly classified. Those cells generally
348 correspond to low Bayesian probabilities, close to the prior probability, meaning that
349 classification should be avoided because uncertainty is high. Interestingly, the sensitivity-
350 dependent approach performs better at each sensitivity level, but the greatest improvement is
351 observed for very low sensitivity values. At those levels, the sensitivity-dependent approach is

352 more conservative and avoids cell misclassification. Misclassification above the bedrock also
353 occurs because the resistivity at this depth is influenced by the more resistive bedrock,
354 favoring classification into the more resistive sand facies. This aspect is discussed later in our
355 field application.

356 The use of the transparency scale in Figure 6 indicates how the probability can be used to gain
357 important information regarding the uncertainty of the classification. We see that, globally,
358 classification into the sand facies is linked to a low uncertainty (opaque value), whereas
359 classification into the gravel facies is less certain. Therefore, a misclassification within the
360 gravel facies is less prejudicial because it is informed by a lower probability.

361 The transparency as an uncertainty estimate is directly linked to the probability performance
362 indicator. Using the sensitivity-dependent approach, the probability performance indicator
363 (Table 1) increases more significantly than the classification performance indicator. With
364 sensitivity dependency, high-sensitivity correctly classified cells will contribute to higher
365 rewards, and low-sensitivity poorly classified cells to less penalization. In contrast, high-
366 sensitivity poorly classified cells will contribute to higher penalization, and low-sensitivity
367 correctly classified cells to less reward. In the upper 5 m of the subsurface in Figure 6F, many
368 correctly classified cells have a higher probability for the most probable facies compared to
369 Figure 6D. This explains the increase of the probability indicator for the sensitivity-dependent
370 case.

371 The probability performance metrics show that an increase in performance is observed when
372 sensitivity-dependent distributions are used. The average performance increases from 24.5%
373 to 27%, which corresponds well with the mean relative performance increase of 10%. The
374 increase in performance is observed for 92 of the 96 tested models. In this specific case, few

375 cells are located in very low sensitivity regions. For less favorable cases, the increase in
376 performance could be more significant due to less penalization.

377 Our results show that the probabilistic approach, without sensitivity-dependence, is already
378 relatively efficient when an ERT survey and corresponding goals are well-designed; that is, if
379 we do not attempt to classify cells that have too low sensitivities or are located too deep. If
380 only limited depths are considered, the global probabilistic framework can be considered as
381 conservative.

382 **FIELD RESULTS**

383 We now apply the proposed methodology to field measurements. To this end, we consider
384 one of the 12 ERT profiles acquired at the Meuse River site. We also demonstrate the effect
385 of regularization on the resulting facies probability maps, as prior assumptions made during
386 the ERT inversion have a large effect on the inverted resistivity distribution and, therefore, are
387 expected to influence the facies probabilities.

388 **Effect of sensitivity**

389 Working with a field case is more difficult than our synthetic benchmark because we do not
390 have access to many co-located measurements. Indeed, deriving directly sensitivity-dependent
391 distributions from co-located measurements would require an unrealistically high number of
392 boreholes in order to have reliable distributions. To overcome this limitation, we tried to
393 reproduce the behavior observed for the synthetic cases in order to build a sensitivity-
394 dependent relationship (Figure 7). To this end, we assumed linear trends for the mean of the
395 distribution towards a common value at low sensitivity and 95% bounds equal to 80% of the
396 ones observed for the global distribution. We acknowledge that this assumption is debatable,
397 but it is made to propose a relatively straightforward way to apply the method in field
398 conditions.

399 The large range observed for clay in the field is related to the geometry of the deposits at the
400 Meuse River site. A layer of clayey loam is seen in almost all the boreholes; however, its
401 thickness is small at some locations (0.5 to 1 m) compared to the electrode spacing (2 m),
402 which makes it rather difficult to image. Inversion tends to show higher resistivity at these
403 locations due to the presence of sand below the clay. In this section, we focus on the
404 interpretation of the gravel facies, which is the most challenging to image given its
405 intermediate resistivity.

406 The application of the methodology to the field case shows a behavior similar to the one
407 observed for synthetic cases (Figure 8). Since the sensitivity values observed for the alluvial
408 deposits are greater than 10^{-5} (Figure 8B), there is everywhere a tendency towards a more
409 discriminant behavior of ERT when the sensitivity-dependency is used (Figure 8C and D).
410 Zones of intermediate resistivity values see their probability of gravel increasing from 70% to
411 approximately 80%, and a number of cells near the surface and near the bedrock have their
412 probability decreasing to almost zero. This signifies that, if used as conditioning data for a
413 hydrogeological model, ERT would give a stronger constraint on the geometry of the
414 deposits. However, the global distributions already identify most trends in the deposits. Given
415 the uncertainty in the chosen sensitivity-dependent relationship, we may conclude that, as was
416 the case for our synthetic study, ignoring the sensitivity-dependence is a conservative
417 approach because the choice of electrode spacing is sufficient to image the deposits down to a
418 depth of about 10 m.

419 **Effect of regularization**

420 The probability maps obtained in Figure 8C and 8D are direct transforms of the resistivity
421 values that were obtained through deterministic inversion of the ERT data. The solution of
422 this inverse problem is non-unique and depends on the assumptions made about the

423 subsurface resistivity distribution, which are expressed through the second term of the right
424 hand side of equation 1. Here, we test the effect of changing the regularization operator for
425 ERT inversion on the probability maps. To this end, we consider geostatistical regularization
426 which uses the model parameter covariance matrix instead of a roughness matrix as the model
427 constraint (Hermans et al., 2012; Caterina et al., 2014). To estimate the covariance matrix, we
428 computed the variogram from borehole electromagnetic logs and found that a Gaussian model
429 having vertical and horizontal correlation lengths of 4.4 m and 11 m, respectively, offered an
430 acceptable fit (Hermans et al., 2015a). In addition, the known position (10 m depth) of the
431 bedrock was imposed during the inversion. For the smoothness constraint regularization, a
432 ratio of 2.5 between horizontal and vertical smoothing was used, which represents the same
433 amount of anisotropy as the geostatistical constraint. Our objective is not to demonstrate that
434 one inversion method is better than the other, which is clearly site or case specific, but rather
435 to illustrate how regularization can modify our interpretation of the results. Therefore, the use
436 of field data is more appropriate for this purpose.

437 The inverted resistivity distributions obtained using the two regularization methods are quite
438 different, except near the surface (Figure 9A and B) where the inversion is mainly influenced
439 by the data and not by the regularization operator. With the geostatistical regularization, the
440 thickness of more resistive zones is limited and the decrease in resistivity corresponding to the
441 presence of gravel above the bedrock is more pronounced. Globally, geostatistical
442 regularization reproduces more satisfactorily the resistivity distribution measured with the
443 electromagnetic log (Figure 10) in this specific case. This confirms how the incorporation of
444 appropriate prior information into the inversion can improve the reconstruction of the
445 resistivity distribution.

446 The different inverted resistivity values yield different resistivity distributions for each facies
447 as well. The histograms obtained (based on the 12 ERT profiles) exhibit clear differences

448 (Figure 9C and D). For the smoothness constraint, the distributions of sand and gravel are
449 close to each other, which makes the discrimination between these facies more difficult. With
450 the geostatistical regularization, the mean value of the gravel facies is smaller. In both cases,
451 the distribution for the clay facies is rather similar, because clay is mainly limited to the
452 surface where both inversions yield similar results.

453 Using the corresponding histograms, the probability maps of gravel were computed (Figure
454 9E and F). A side-effect of regularization when attempting to identify three facies is that the
455 transition between the low and high resistivity facies will almost always create a zone where
456 the probability of the intermediate facies is high. This appears for example between $X=80$ m
457 and $X=120$ m at 1.5 m depth. The patterns of high and low probability of gravel are relatively
458 similar. The differences in the resistivity tomograms are partly counterbalanced by the
459 probabilistic approach because they are taken into account in the conditional probability
460 relationship, through the use of the co-located measurements histograms. However, some
461 differences remain visible in the shape, amplitude, and position of some low-probability
462 zones. In particular, the low probability of gravel observed at $X = 60$ m for the smoothness
463 constraint is not in accordance with borehole data (Pz3, Figure 2). This results from the
464 smoothness constraint, which is not able to image the decrease in resistivity at this location
465 due to the presence of the underlying resistive bedrock, is a side-effect of using only three
466 facies. Since the bedrock is not considered in our probabilistic analysis, this zone has a high
467 probability of sand and would be deterministically classified as sand, with some uncertainty.
468 However, if the bedrock were considered, this zone of low gravel probability would have a
469 high probability of belonging to the bedrock, thereby decreasing the probability of sand. In
470 this case, the misclassification is related to the uncertainty of the bedrock depth. This
471 inconvenience is avoided in the geostatistical regularization because the position of the
472 bedrock, known from boreholes, has been fixed during the inversion. The inversion process

473 therefore identified that alluvial deposits could display a lower resistivity for which the most
474 probable facies is gravel.

475 It is thus preferable to use the inversion method which gives the best estimate of the
476 resistivity. In this case, the incorporation of prior information is helpful to discriminate facies
477 more reliably. However, the choice of the regularization method is not related to the decision
478 of using a probabilistic framework to interpret ERT images. Although the geostatistical
479 regularization identifies a zone where the highest probability is for the gravel facies, the
480 probabilistic framework provides probabilities around 0.7. This shows that this zone is
481 uncertain with resistivity values that could correspond to gravel, sand or even clay.

482 The comparison of Figures 8 (C and D) and 9 (E and F) illustrates that the effect of
483 regularization may dominate the effect of sensitivity-dependence on the derived probabilistic
484 facies estimate, if very-low sensitivity zones are not considered. Indeed, the sensitivity-
485 dependence, in contrast to the regularization, impacts the probability values but not the spatial
486 resistivity distribution.

487 **DISCUSSION AND CONCLUSIONS**

488 In this paper, we have assessed the ability of electrical resistivity tomography to discriminate
489 facies in alluvial aquifers. We propose to use a probabilistic relationship based on co-located
490 facies and resistivity measurements to derive the resistivity distribution for each facies. Then,
491 Bayes' rule is used to estimate the conditional probability of observing a facies given the
492 resistivity. Our methodology has the advantage of integrating the uncertainty related to data
493 noise and the inversion method into the estimate since it compares observed facies with post-
494 inversion results.

495 We applied the methodology on a synthetic benchmark to verify the ability of ERT to
496 correctly classify alluvial deposits into facies. The performance is quite good (on average,

497 65% correct classification) given the challenging task of determining three facies. Indeed,
498 when only two facies are considered, the performance increases to 80%. Those results depend
499 on the chosen synthetic models and resistivity values assigned to each facies. It is therefore
500 necessary to be as close as possible to the actual field case to derive interesting guidelines.
501 From our examples, it clearly appears that the classification ability decreases rapidly with
502 depth. It is thus preferable to keep the Bayesian probabilities, which give additional
503 information on the uncertainty of the estimates and can be further used in stochastic
504 simulations, rather than classification for interpretation purposes. This can be done by either
505 using probability maps for the interpretation, or by using a transparency scale related to the
506 probability of the most probable facies for classification. The latter solution has the advantage
507 of being able to express the results on a single figure.

508 The decrease of resolution and sensitivity of surface-based ERT data with depth is a well-
509 known effect; the results of inversion become less certain with depth, whereas close to the
510 surface ERT is more discriminant. We used the synthetic benchmark to analyze the influence
511 of sensitivity on the performance of ERT to detect facies by adapting the probabilistic
512 framework in order to account for the sensitivity-dependence. This did not appear to improve
513 classification performance but it did allow us to increase confidence in the results by
514 attributing, on average, higher probabilities to the correct facies. However, the approach using
515 the global distributions already performs relatively well when the survey is properly designed
516 (i.e., electrode spacing adapted to the desired depth of investigation).

517 Although determining the sensitivity-dependence of the resistivity distribution based on
518 limited measurements was a challenge in our field case, we modeled this dependence based
519 on the synthetic benchmark. However, the probabilistic approach is not designed to
520 counterbalance all errors related to the inversion method. In this particular example, an
521 increase of resistivity due to the presence of the bedrock was observed in the bottom part of

522 the alluvial deposits, leading to the identification of a high probability of sand instead of
523 gravel. This effect was avoided by using an appropriate inversion method integrating prior
524 information regarding the position of the bedrock and a geostatistical constraint. The
525 resistivity distribution obtained was closer to the true resistivity measured by a logging
526 device. The probabilistic framework allows to associate an uncertainty estimate to the
527 presence of a given facies.

528 The proposed methodology, using a large number of synthetic models, could be used to assess
529 the ability of ERT to image various features in different contexts and to analyze the influence
530 of other effects known to modify the inverted resistivity distribution such as the electrode
531 configuration (Dahlin and Zhou, 2004) or the regularization trade-off parameter (Audebert et
532 al., 2014). It can also be directly applied in Bayesian framework where geophysical
533 measurements are used to update the probability of a given properties, an obvious example
534 being soft conditioning of facies-based multiple-point geostatistical simulations (Hermans et
535 al., 2015a).

536 The methodology can also be used as an alternative, probabilistic framework to identify if the
537 survey is correctly designed regarding the objectives of the study and estimate the depth of
538 investigation: as long as the sensitivity-dependent probabilities are similar to, or more
539 discriminant than, the global ones, the survey will not systematically overestimates the ability
540 of ERT to detect specific features in the subsurface.

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655

656

657 **TABLES**

658

Estimator	Without sensitivity	Sensitivity- dependent
Mean classification performance (%)	65.26	65.32
Minimum classification performance (%)	49.29	50.31
Maximum classification performance (%)	79.17	78.94
Mean classification performance 2 facies (%)	78.92	78.87
Minimum classification performance 2 facies (%)	63.82	63.90
Maximum classification performance 2 facies (%)	90.43	90.55
Mean probability performance (%)	24.52	27.01
Minimum probability performance (%)	4.49	8.24
Maximum probability performance (%)	47.78	51.17
Mean relative performance increase (%)		10.15

659 **Table 1. Classification and probability performances. The term “2 facies” means that**
660 **misclassification between clay and gravel was disregarded.**

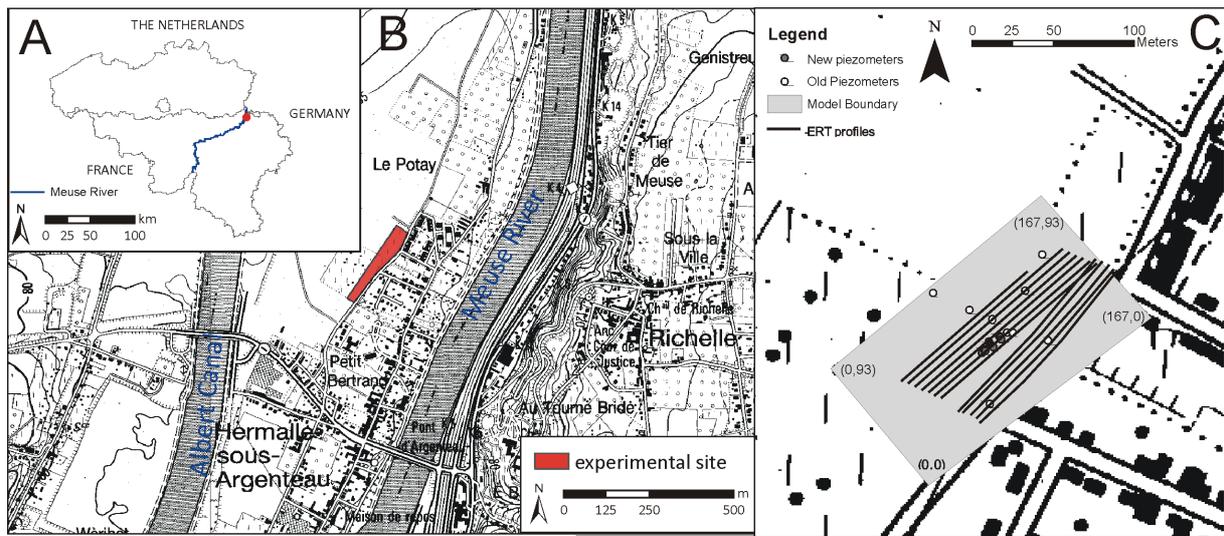
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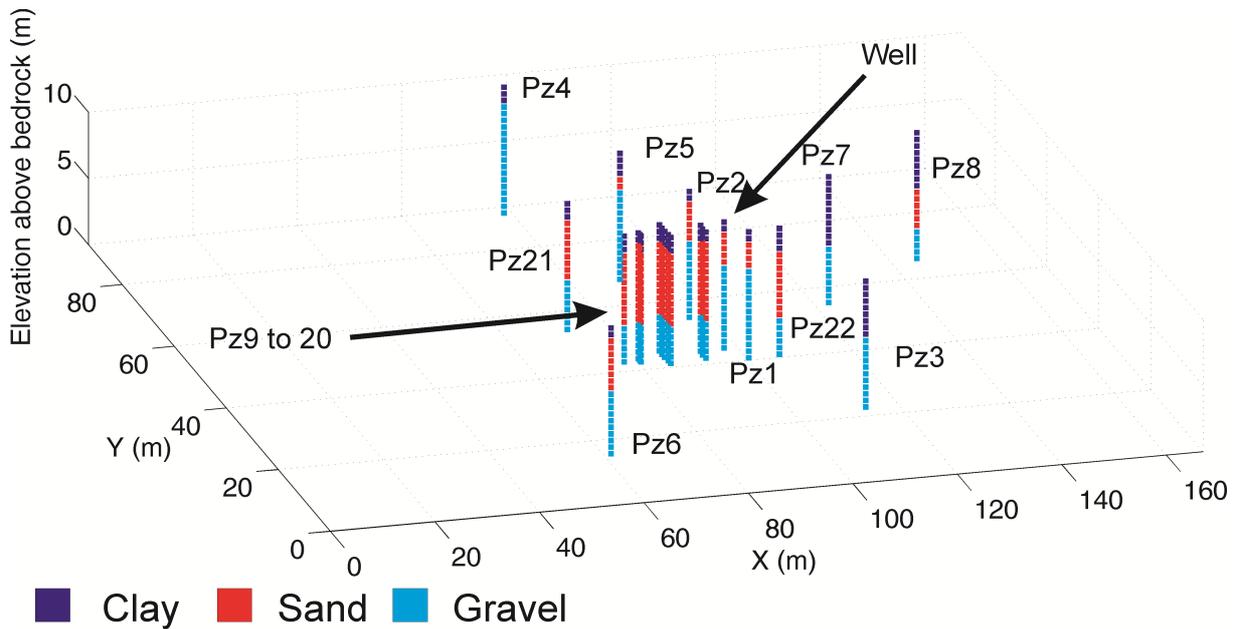
Sensitivity classes	Number of cells	Without sensitivity (%)	Sensitivity-dependent (%)
$0 > S > 10^{-1}$	22825	84.21	84.61
$10^{-1} > S > 10^{-2}$	31066	84.18	84.48
$10^{-2} > S > 10^{-3}$	49633	71.19	71.33
$10^{-3} > S > 10^{-4}$	79928	59.28	59.40
$10^{-4} > S > 10^{-5}$	54329	52.33	52.50
$10^{-5} > S > 10^{-6}$	5696	43.43	45.05
$10^{-6} > S$	363	37.74	51.79

663 **Table 2. Classification performance according to data sensitivity.**

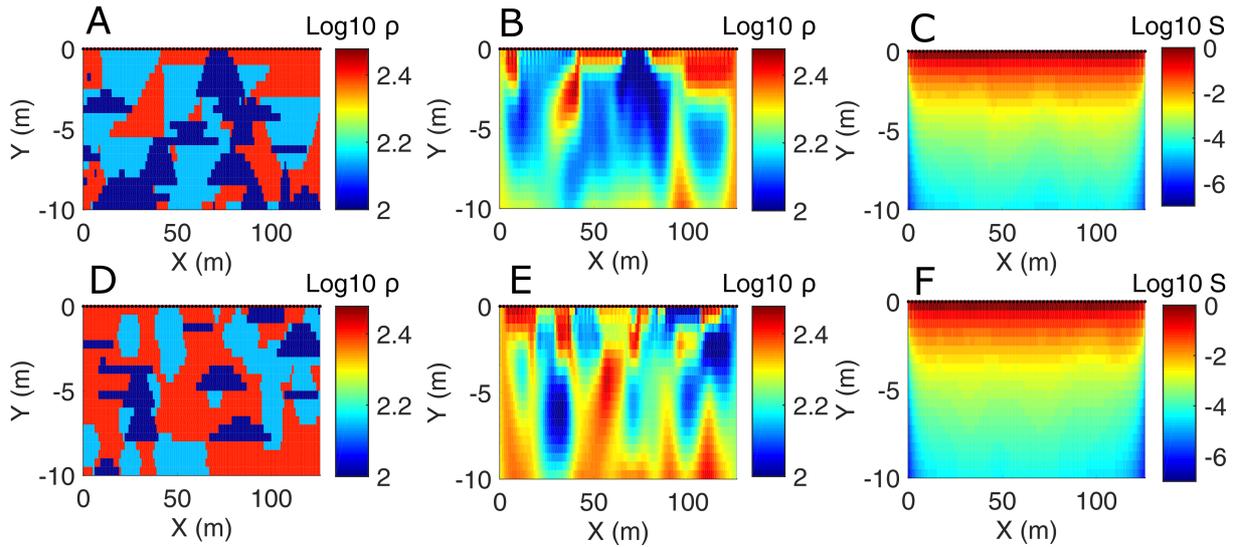
664



666
 667 **Figure 1.** Location of the field site in the Meuse River alluvial aquifer (A and B) and of the
 668 boreholes used for facies description (C). The black lines show the position of 12 ERT
 669 profiles carried out on the site to study the resistivity distribution of the deposits.

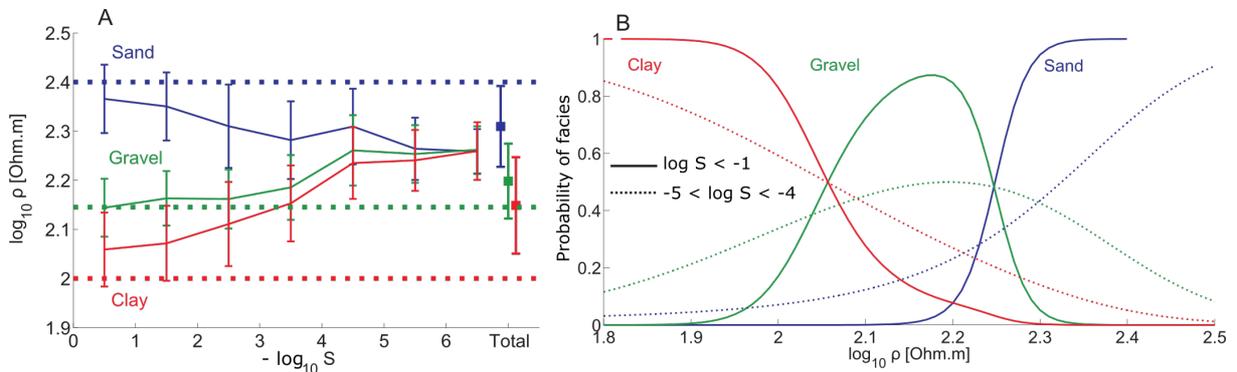


670
 671 **Figure 2.** Interpretation of the borehole textural description data in terms of hydrofacies.



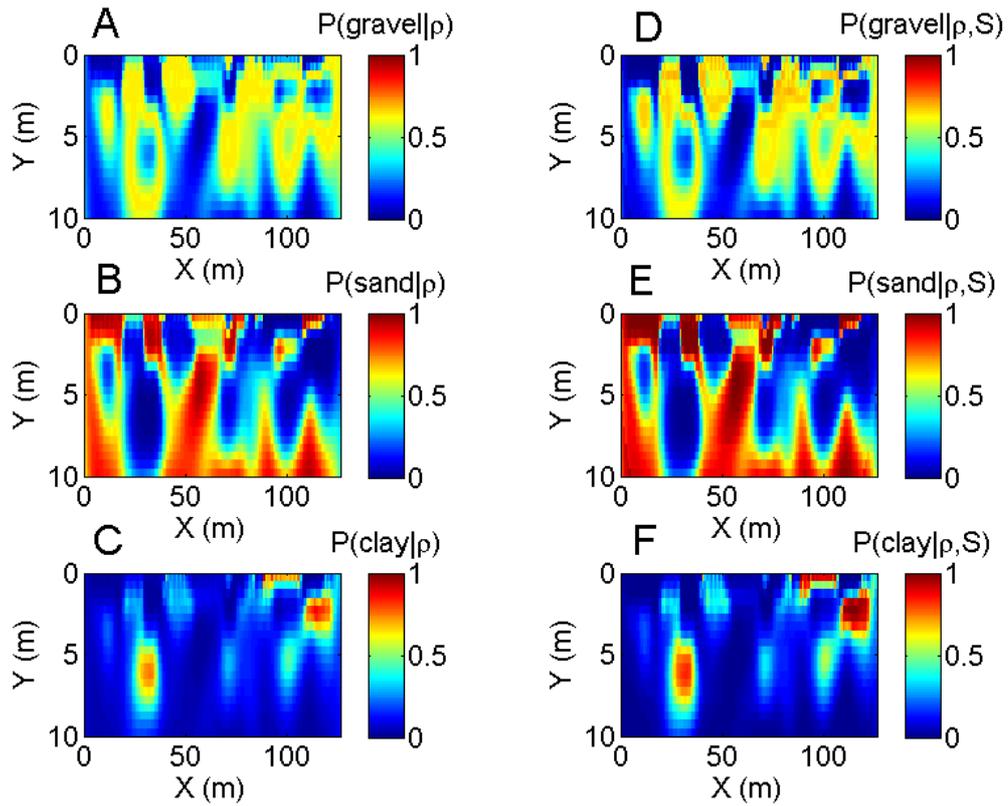
672

673 **Figure 3.** Two alluvial aquifer synthetic models (A and D) along with their respective
 674 inverted resistivity (B and E) and sensitivity distributions (C and F). The color of the
 675 resistivity of the facies is similar to the color scale used in Figure 2. The scale of the vertical
 676 axis is exaggerated.



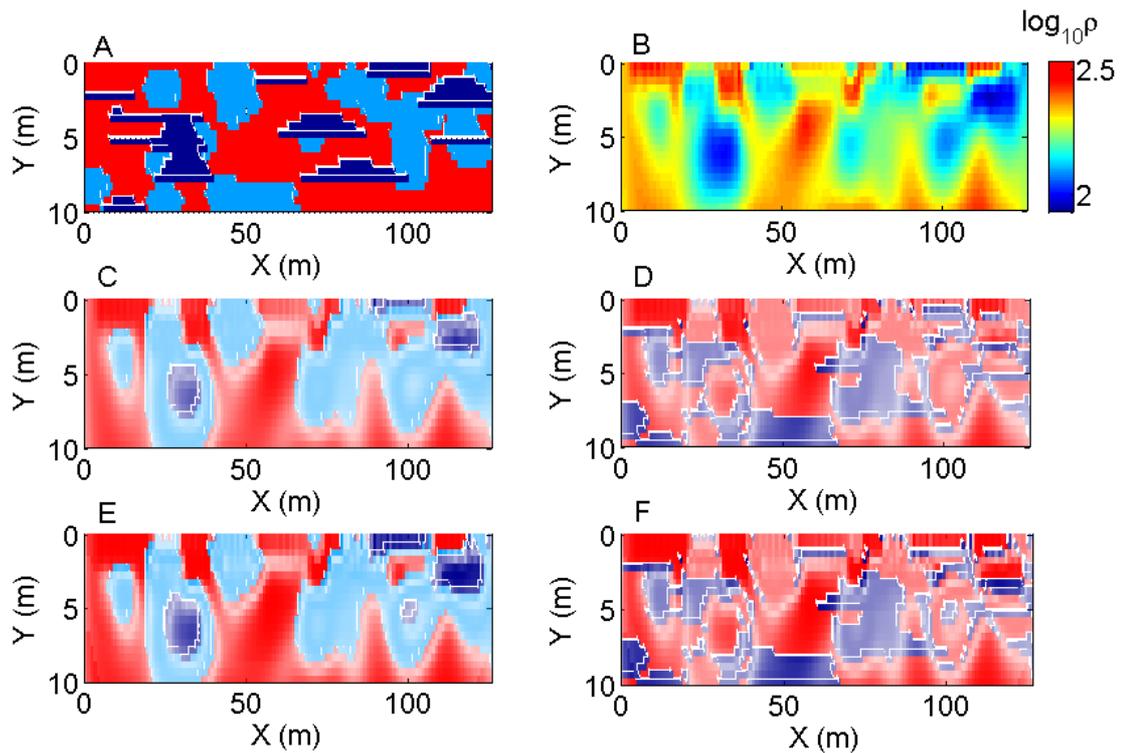
677

678 **Figure 4.** (A) Sensitivity-dependent resistivity distribution for the three considered facies
 679 (mean and 95% interval) for the synthetic benchmark, based on analysis of all 96 inverted
 680 models. The dotted lines correspond to the true value for each facies. (B) Conditional
 681 probability of the different facies given the inverted resistivity value for two different
 682 sensitivity classes, calculated using equation 3.



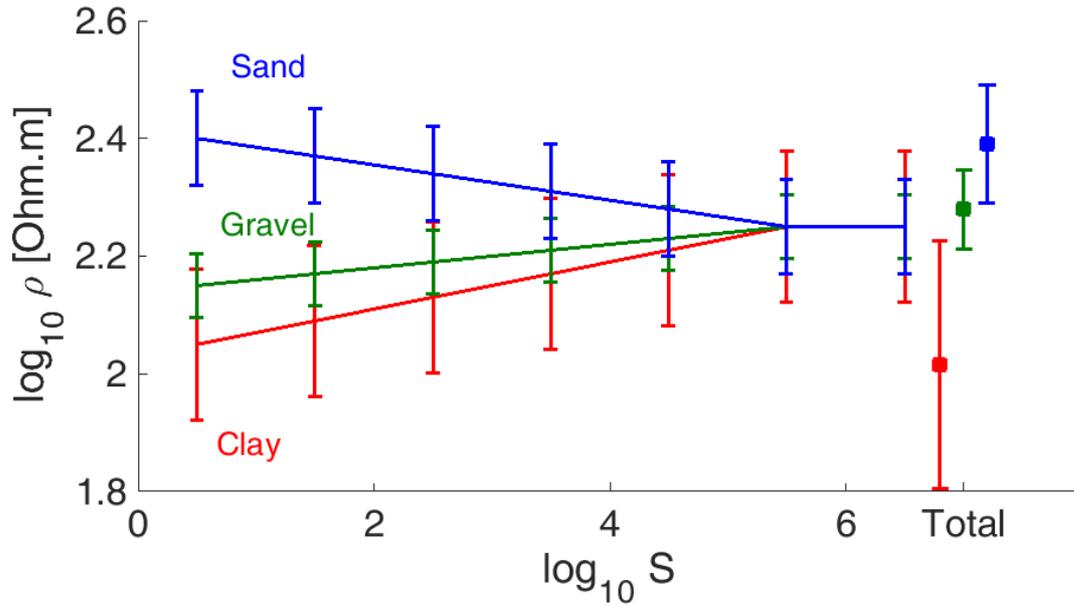
683

684 **Figure 5.** Probability of the three facies for the second model shown in Figure 3D, without
 685 (A, B and C) and with (D, E and F) the sensitivity-dependence taken into account. The scale
 686 of the vertical axis is exaggerated.



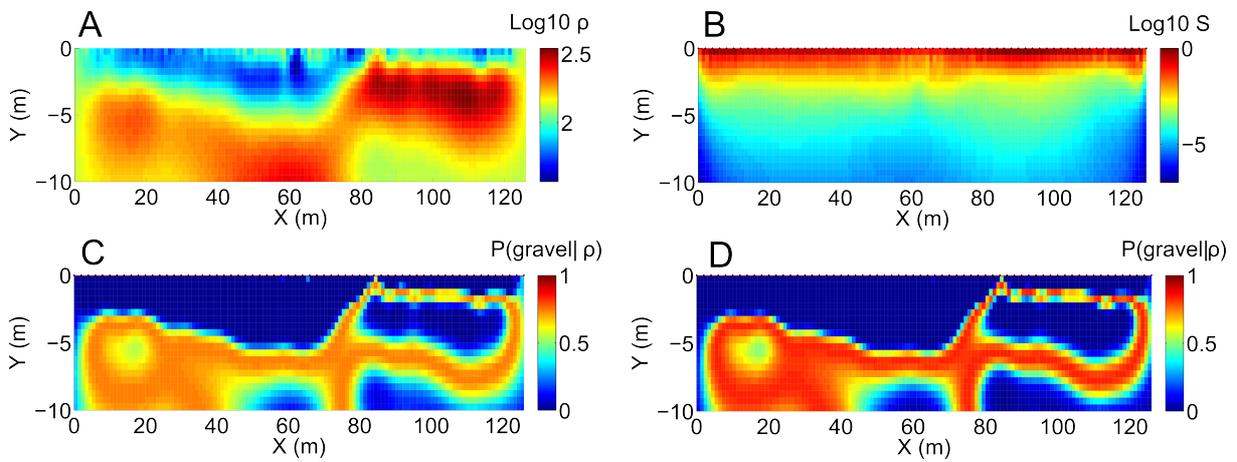
687

688 **Figure 6.** True model (A) from Figure 3D, inverted resistivity distribution (B), classifications
 689 based on the probability maps of Figure 5 without (C) and with (E) sensitivity dependence
 690 and corresponding misclassification indicator maps (D and F). Red is correct classification,
 691 blue corresponds to misclassification. The transparency scale in C-F is based on the
 692 probability of the most probable facies. Total opacity corresponds to a probability of 100%,
 693 total transparency to the minimum possible probability for the most probable facies: 33%. The
 694 color of the facies is similar to the color scale used in Figure 2. The scale of the vertical axis is
 695 exaggerated.



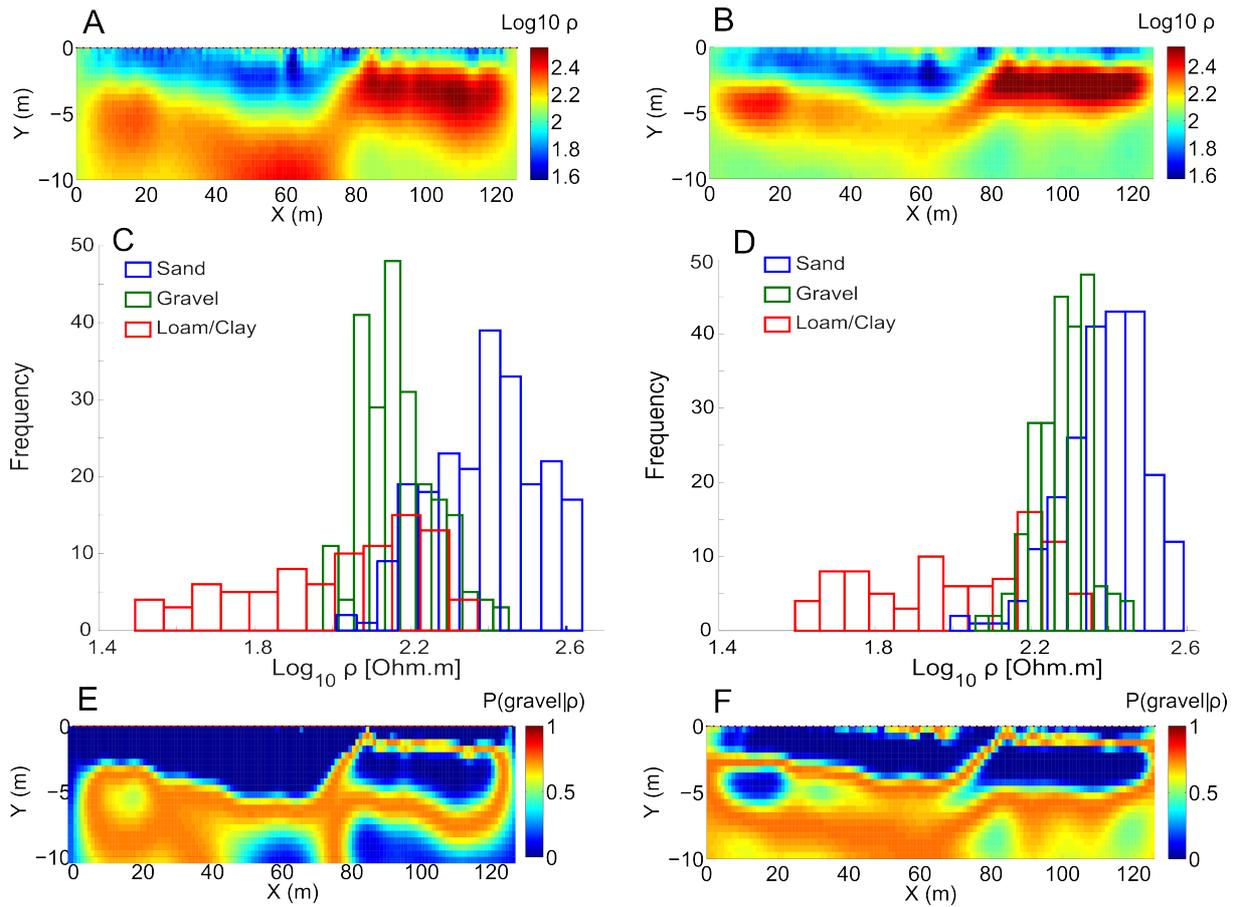
696

697 **Figure 7.** Assumed sensitivity-dependent resistivity distribution for the three considered
 698 facies (mean and 95% interval) for the field case.



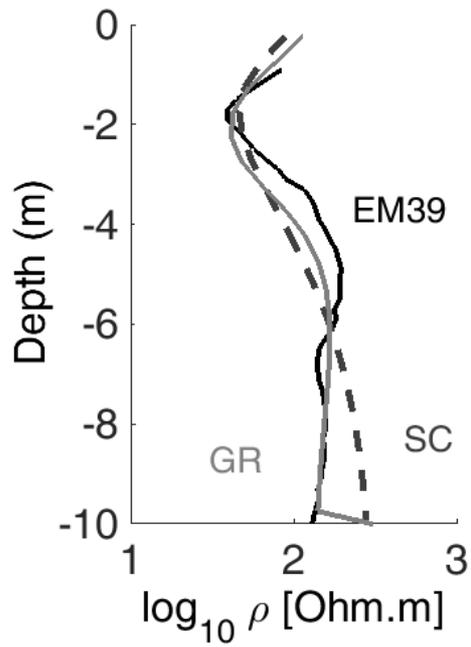
699

700 **Figure 8.** Smoothness constraint inversion of a field profile (A), the corresponding sensitivity
 701 distribution (B), and probability maps without (C) and with (D) taking sensitivity into
 702 account.



703

704 **Figure 9.** Effect of regularization on the gravel facies probability map. ERT inversions
 705 obtained using smoothness constraint inversion (A) and geostatistical inversion (B),
 706 respective histograms of resistivity for each facies (C and D) deduced from borehole logs, and
 707 corresponding probability map for gravel (E and F).



708

709 **Figure 10.** Comparison of inversion results with electromagnetic log in the middle of the
 710 profile of Figure 9 (GR = geostatistical regularization, SC = smoothness constraint).

711 Geostatistical regularization is able to reproduce the decrease of resistivity above the bedrock.