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THREE ESSAYS IN CHOICE AND SOCIAL CHOICE THEORY

Protopapas Panagiotis Constantine

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FACULTÉ DES HAUTES ÉTUDES COMMERCIALES

DÉPARTEMENT D'ÉCONOMIE

**THREE ESSAYS IN CHOICE AND
SOCIAL CHOICE THEORY**

THÈSE DE DOCTORAT

présentée à la

Faculté des Hautes Études Commerciales
de l'Université de Lausanne

pour l'obtention du grade de
Docteur ès Sciences économiques, mention « économie politique »
En cotutelle avec l'Université de Maastricht

par

Panagiotis Constantine PROTOPAPAS

Co-directrice et co-directeur de thèse
Prof. Bettina Klaus
Prof. Hans Peters

Jury

Prof. Luis Pedro Santos Pinto, expert interne
Dr. Flip Klijn, expert externe
Prof. Jordi Masso, expert externe

LAUSANNE
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Sans se prononcer sur les opinions de l'auteur, la Faculté des Hautes Etudes Commerciales de l'Université de Lausanne autorise l'impression de la thèse de Monsieur Panagiotis Constantine PROTOPAPAS, titulaire d'un bachelor en Mathematics with Management du Imperial College London, d'un diplôme postgrade en Logistics, Trade, and Finance de la City, University of London et d'un master en Economie Politique de l'Université de Lausanne, en vue de l'obtention du grade de docteur ès Sciences Économiques, mention « Économie politique », en cotutelle avec l'Université de Maastricht.

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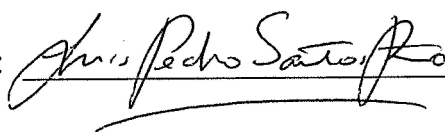
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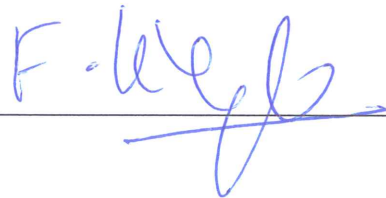
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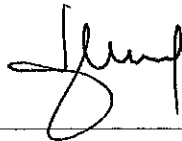
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Three Essays in Choice and Social Choice Theory

Panos Protopapas
University of Lausanne
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October 2018

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Introduction

Many situations in life require a decision to be made in order to resolve some issue that has arisen. Such situations are essentially cases where the decision must be chosen from a set of possible alternatives. For example, having to choose on a rainy day whether to take an umbrella, an anorak, or perhaps neither; or having to choose what to order at a restaurant, just the main course or the three course meal? How about a drink as well? Of course, the choice outcome in any of these issues depends on the preferences of the individual that this choice concerns. Some people do not mind getting a little wet if it rains, so perhaps they might opt to take neither an umbrella nor an anorak with them on a rainy day. Some other -very weird- people never have dessert, so for them choosing a three course meal is out of the question.

However, not all decision choices are made by just one person; some issues concern a group of people. In this case, a suitable “mechanism” must be used that will take into account the preferences of all members in the group before reaching a decision. For example, many countries use plurality voting when electing a new government. This mechanism chooses the party that received the highest number of votes, or in other words, the most preferred party according to the preferences of the plurality. As a second example, consider a book club where members of the club take turns every week in suggesting a book for everyone in the club to read. This kind of mechanism, where the decision is made by just one member of the group, but the decision maker alternates every week, is called serial dictatorship.

In this thesis, both cases where the decision is taken either by a single person or by a group of people are considered. In the first chapter, we study cases where the issue concerns a single person, henceforth, agent. Specifically, we are interested in whether the agent’s preferences, according to the choices he makes, should be considered “rationalizable”. For a brief (and not completely accurate) explanation of what is meant by the term rationalizability of preferences, consider the following example. An agent whose preferences are rationalizable has to decide what to order from a restaurant’s menu. The available choices are hamburger, salad, beer,

and coffee. The agent decides to order salad and beer; therefore, we can deduce that he prefers this combination over every other available combination on the menu (e.g., hamburger and beer or salad and coffee). Nevertheless, just before placing his order, the waiter informs him of the daily special, steak, which is not listed in the menu. Perhaps now the agent will change his order to steak and beer or steak and coffee; after all, neither combination was previously available, and therefore, such a change would be rational. However, changing his order to hamburger and beer would not be rational; the combination of hamburger and beer was also available initially, when the agent chose to order salad and beer, and we deduced that according to his rationalizable preferences, he prefers salad and beer over hamburger and beer.

In the second and third chapters, we study cases where the issue concerns a group of people, henceforth, agents, and a decision mechanism must be implemented in order to consider the preferences of all agents in the group before reaching a decision. Here, we are interested to find out how this mechanism might function when certain requirements, henceforth, properties, must be met. For example, perhaps it would be useful that all agents declare their true preferences instead of trying to manipulate (by lying) the decision chosen by the mechanism. Due to this, we could require that the mechanism does not “reward” liars by making sure that an agent would always get the same result or a more favorable one when telling the truth. Another property of the mechanism could be that all agents in the group are treated equally, irrespective of gender, race, social standing, or religious beliefs. Furthermore, in an environment with often-changing circumstances, a mechanism that would mitigate any positive or negative changes “fairly” among the group of agents would perhaps be welcome; therefore, the following property would perhaps be in order. Following a positive (negative) change in the circumstances, all agents get better off (worse off) compared to their initial situation. However, it is necessary to bear in mind that not all combinations of properties are always “compatible”. One of the first to point out this incompatibility was Kenneth J. Arrow with his famous impossibility theorem that states the following. In every voting situation with three or more candidates, there exists no electoral system that can be efficient,¹ independent over irrelevant alternatives

¹In a typical voting situation, efficiency essentially requires that the elected candidate was voted for by at least one voter.

(IIA),² and be non-dictatorial³ as well (Arrow, 1950).

We proceed by providing a more in-depth summary of each chapter.

Chapter 1: Set and revealed preference axioms for multi-valued choice

The first chapter was written in collaboration with Hans Peters. It is chronologically the last chapter of this thesis, but is presented first due to its more general nature of the topic in choice theory, relative to the other two chapters. The main part of the work in it took place during the six months I spent in Maastricht, spread over the last three years.

In this chapter, we consider situations where an issue has arisen with a number of alternative ways to deal with it, and some individual needs to choose one, or more, of these alternatives in order to deal with this situation. In the sequel, we refer to all the possible ways to deal with the issue by the term *choice set* and to the individual by the term *choice correspondence*; that is, given a choice set of alternatives, a choice correspondence will choose a subset of this choice set, the *chosen set*.

Specifically, we are interested in choice correspondences satisfying two properties. First, the property of independence of irrelevant alternatives (IIA), as well as a weaker version of it, and second, the weak axiom of revealed preference for sets (WARP)⁴.

We show the existence of connections between these properties and two particular collections of choice sets, called weak and strong sets, which in turn partially or completely determine the choice correspondences satisfying the above independence properties. In other words, if we were to refer to the restaurant example on page v, we find that by knowing what an agent will order at some restaurants, specifically the ones whose menus are included in weak and strong sets, we are able to determine what this agent will order at every restaurant, assuming the way he makes his choices is according to the two aforementioned conditions.

²Loosely speaking, IIA requires that the removal of non-winning candidates from an election should not affect the result. For example, if in an election between candidates a , b , and c , a is the winner, then IIA requires that in an election between just candidates a and b , a to be the winner as well, since the removal of non-winning candidate c is irrelevant.

³If in every voting situation a specific voter can dictate the result, then we say that this voter is a dictator. An electoral system is non-dictatorial if it does not allow the existence of dictators.

⁴Consider again the restaurant example on page v. Since salad and beer are chosen initially, the agent *reveals* his preference for salad and beer over any other available combination in the menu (e.g., salad and coffee). WARP requires that at some other choice set, where salad and beer are available, the agent will not select salad and coffee, and thus reveal that he prefers salad and coffee over salad and beer.

Chapter 2: Solidarity for public goods under single-peaked preferences: Characterizing target set correspondences

The second chapter was written in collaboration with Bettina Klaus and is chronologically the first chapter of this thesis. It has been presented in conferences at Istanbul's Bilgi University, Budapest's Corvinus University, Tbilisi State University, Maastricht University, the University of Zurich, Lund University, the University of Southern Denmark, and the University of Lausanne. Moreover, a poster of it has been presented at Grenoble Alps University.

Here, we consider the problem that a city planner might face when having to choose a group of locations where an identical public good will be provided to the citizens of the city in question. For example, choosing the locations of public parking positions, or in other words, choosing the location of a public parking zone. In addition, the city planner's choice needs to take into account the preferences of the citizens, who are the ones to use this parking zone. Loosely speaking, said preferences are single-peaked.⁵

Similarly to the first chapter, the city planner making the choice will be referred to as a choice correspondence and we will be interested that this choice correspondence satisfies certain properties. However, in contrast with the previous chapter, these properties are now related with the citizens' preferences and moreover, two of them require a notion of solidarity among the citizens. Namely, the three properties are efficiency,⁶ population-monotonicity,⁷ and (a version of) replacement-dominance,⁸ with the two latter ones requiring the aforementioned notion of solidarity.

We show that if efficiency and either population-monotonicity or replacement-dominance are to be satisfied by a choice correspondence, then this choice correspondence belongs to a particular class of correspondences, that of target set correspondences. Loosely speaking, this result implies the following. If the city planner's choice has to satisfy these properties, then he should first choose alone

⁵Single peakedness of preferences implies the following. Each citizen has a single most favorite location (his peak) when parking his car, for example, right outside his home; moreover, if this location is taken, then he would prefer to park as closely as possible to his most favorite location.

⁶When a parking zone is chosen, efficiency guarantees that no other parking zone could have been chosen instead and would have made some citizens better off, and no citizen worse off.

⁷If following the addition of some new citizens, a parking zone change is in order, then all citizens, excluding the newcomers, must be affected in the same way; either nobody gets worse off, or nobody gets better off.

⁸If following a citizen's change of preferences (e.g., after moving to a new home), a parking zone change is in order, then all other citizens must be affected in the same way; either nobody gets worse off, or nobody gets better off.

where the parking zone should be, then ask the citizens about their preferences, and finally, only change his initial choice if all citizens unanimously agree with this change.

Chapter 3: On strategy-proofness and single-peakedness: median-voting over intervals

The third chapter was single-authored and was chronologically the second chapter of this thesis; it was written under the close supervision and guidance of Bettina Klaus. It has been presented in conferences at the University of Lausanne, the University of Zurich, the University of York, Paris Dauphine University, and the University of Innsbruck.

The problem considered here is in some ways similar to the one considered in the previous chapter. Specifically, the problem is the following. A city planner has to choose a set of (tax) policies which will affect all citizens/voters, with the possible choices spanning from extreme left-wing choice to extreme right-wing choices. For example, the decision to increase the tax rate of high earners and decrease that of low earners would be a left-wing policy, while on the other hand, abolishing health-related taxes all together and having citizens pay for their health insurance through the private sector would be a right-wing policy. All voters have their own preferences about policy choices, which they announce to the city planner by voting. These preferences are again “based on” single-peaked preferences; for example, if a voter’s most favorite policy (peak) is a left-wing one, then he also prefers policies closer to his peak over policies further away. Therefore, he would also prefer central policies over right-wing policies.

Similarly to the previous chapter, we will refer to the city planner using the term choice correspondence and will be interested that this choice correspondence satisfies certain properties, all of which related with the citizens’ announced preferences, i.e., the citizens’ votes. To be more precise, the main three properties we are interested in are strategy-proofness,⁹ peaks-onliness,¹⁰ and anonymity.¹¹

Our two main results are as follows. First, if strategy-proofness and peaks-onliness are to be satisfied by a choice correspondence, then this choice correspondence belongs to a particular class of correspondences, that of generalized median correspondences. Second, if anonymity is also to be satisfied, then this choice cor-

⁹When a voter lies and does not announce his true preferences, the result cannot improve in his favor. In other words, a voter cannot strategize in order to improve the result in his favor.

¹⁰All voters are only allowed to declare, by voting, their most favorite policy. They cannot also declare their second most favorite, third most favorite, etc.

¹¹All voters have equal rights in the decision, in other words, all voters get one vote each.

respondence belongs to a sub-class of generalized median correspondences, called the class of median correspondences. Loosely speaking, the second result implies the following.¹² If during an election, the city planner's choice has to satisfy these properties, then he should first stuff the ballot box with a number of votes of his choice, then ask the citizens to cast their votes, and finally after combining all stuffed and cast votes, choose the policy favored by the median vote (in a sense, the central vote).

At first, this seems as an unwanted situation giving the voters no say in the outcome; however, this is not entirely true. Although a high number of stuffed votes implies that indeed, voters cannot influence the outcome, a low number of stuffed votes achieves a different effect. Specifically, depending on how "low" this number is, the voters might have complete control on the outcome, in the case of zero stuffed votes, or have some degree of control on the outcome, with this degree depending on the number of stuffed votes.¹³

¹²The first result, which does not include anonymity, is a little more general and due to this, difficult to explain concisely in an informal way.

¹³For an example where voters only have some degree of control over the outcome, consider the following. In many countries, a supermajority of the parliament is required to agree with proposed constitutional amendments, in order for these to take place. In such cases, the stuffed votes could be thought of as favoring the status-quo, i.e., no change in the constitution.

Chapter 1

Set and revealed preference axioms for multi-valued choice

Abstract

We consider choice correspondences for arbitrary sets of alternatives, and focus on the condition of independence of irrelevant alternatives and on a weaker version of it, as well as on the weak axiom of revealed preference for sets. We establish connections between these conditions and their relations with collections of choice sets, called weak and strong sets, that partially or completely determine the choice correspondences satisfying the above independence properties.

1.1 Introduction

1.1.1 Background

This chapter contributes to a question with a long history. For single-valued choice functions the condition of Independence of Irrelevant Alternatives (IIA) requires that if the alternative chosen from a choice set is still available in a subset, then it should be chosen in that subset. This condition already occurs in Nash (1950) as condition no. 7 in Nash's axiomatic bargaining model. For collections of choice sets that are closed under a nonempty intersection – as is the case in the present paper – and (single-valued) choice functions IIA is equivalent to the Weak Axiom of Revealed Preference; the latter requiring the revealed preference relation to admit no cycles of length two. The question is how to extend the IIA condition to (multi-valued) choice correspondences.

The probably most obvious extension was also proposed by Nash in an informal note in 1950 – see Shubik (1982, p. 420): if F is the choice correspondence choosing a subset of every choice set, X is a choice set, and $F(X)$ has a nonempty intersection with Y , a subset of X , then $F(Y)$ should be equal to this intersection.

This condition also appears as Postulate 6 in Chernoff (1954) and Condition C4 in Arrow (1959). The most common and obvious interpretation is that the set of alternatives chosen by a choice correspondence should be viewed as the set of best alternatives (in some sense or another) among the available ones: that is, each of these alternatives is also best in any subset of available alternatives to which it belongs.

A second possible extension would say that in such a situation, $F(Y)$ should at least contain the intersection of $F(X)$ and Y . In terms of the interpretation above, it could be that additional best alternatives become available in the smaller set. For instance, the first preferred choice of wine from a restaurant's menu is no longer available, making the second preferred choice a best alternative (additional to the still available best menu choices). This condition was first proposed as Postulate 4 in Chernoff (1954), and has consequently been referred to as the Chernoff property (e.g., Moulin, 1985, 1988). It appears as Property α in Sen (1971).

In a similar vein, a third extension is to require that the intersection of $F(X)$ and Y should contain $F(Y)$, hence $F(Y)$ is a subset of $F(X)$. In other words, F still chooses among the best elements, but not necessarily all available ones. Think of choosing a committee within a society: for a subset of the society one may need to choose a strictly smaller committee, even if more members of the original committee are still available. Or, in terms of the restaurant's menu choice, the lunch menu may be a subset of the dinner menu, but also lunch itself may be lighter than dinner: one may want to consume wine of just one brand instead of several, even if more brands are still available. This extension appears as condition W2 in Schwartz (1976).

In this chapter the focus is on the first and third extensions, to be called IIA and Weak IIA (WIIA). A still weaker version of the latter condition is the following (e.g., Fishburn, 1973) if $F(X)$ is contained in Y , then $F(Y)$ should be contained in $F(X)$. This condition, studied in Aizerman and Malishevski (1981), is referred to as the Aizerman condition; it is implied by Condition W3 in Schwartz (1976).

Following a tradition initiated for consumer theory by Samuelson (1938) and Houthakker (1950), and continued for general choice problems by – among others – Arrow (1959) and Richter (1966), most of the literature focuses on rationalizability: when does a choice correspondence always pick the set composed by those alternatives that are maximal for some binary relation on the set of alternatives? For instance, Arrow (1959) shows that a choice correspondence is rationalizable by a complete and transitive binary relation if and only if it satisfies IIA. Sen (1971) shows that a choice correspondence is rationalizable by a binary relation if

and only if it satisfies the Chernoff condition and a condition proposed as Property γ^1 but later also referred to as the Expansion condition (e.g., Moulin, 1985). Adding to this the condition of Aizerman results in the choice correspondence being rationalizable by an ordering which is complete and has a transitive strict part (Schwartz, 1976; Moulin, 1988). Finally, Aizerman and Malishevski (1981) show that a choice correspondence satisfies both the Chernoff and the Aizerman condition if and only if it is pseudo-rationalizable by a collection of single-valued, complete, and transitive orderings; that is, if in each choice set, the choice correspondence picks the maximal elements of all the orderings in this collection.

1.1.2 Our focus

As mentioned, we focus on IIA as initiated by Nash (Shubik, 1982) and considered by Arrow (1959), as well as on its weaker version, WIIA, appearing as condition W2 in Schwartz (1976). We assume no structure on the set of alternatives – it can be any finite or infinite set, and we study IIA and WIIA choice correspondences with respect to two closely related questions.

The first question is that of rationalizability. This concerns the existence of a binary relation on the collection of choice sets, thus, sets of alternatives rather than only single alternatives, which rationalizes a given choice correspondence. The usual approach in the literature is to consider revealed preference relations on alternatives instead of sets, with the exception of Brand and Harrenstein (2011). Specifically, they consider set-versions of Chernoff’s and Expansion conditions² and obtain a characterization (their Theorem 2) of ‘set-rationalizable’ choice correspondences. Their set-rationalizability condition is what we call WARP (Weak Axiom of Revealed Preference). We characterize WARP by a different condition and show that this condition is indeed equivalent to the condition of Brand and Harrenstein (2011) – see Lemmas 1.1 and 1.2. We further show that WARP is implied by WIIA if the choice correspondence F is a projection, i.e., $F \circ F = F$ – the latter is implied by WARP, as also observed in Brandt and Harrenstein (2011). In Theorem 1.1 we characterize IIA by WARP combined with another axiom on the revealed preference relation (‘Preference Axiom’, PA); this is in contrast to the single-valued choice case, where IIA and WARP are equivalent. Finally, we show that IIA implies that the revealed preference relation on choice sets is transitive

¹Property γ : for all choice sets X and Y , the intersection of $F(X)$ and $F(Y)$ is contained in $F(X \cup Y)$.

²Note that Brand and Harrenstein (2011) use the nomenclature of Sen (1971), i.e., α - and γ -properties instead of Chernoff’s and Expansion conditions respectively.

and therefore, in view of WARP, acyclic.

The second question is that of identifying collections of choice sets that, as much as possible, determine the choice correspondence satisfying WIIA or IIA. Given a choice correspondence F , a choice set S is called a ‘weak set’ if, for every choice set X , it contains $F(X)$ whenever $F(X)$ has a nonempty intersection with it, and is equal to $F(X)$ whenever $S \subseteq X$. Our main result here is that if F satisfies WIIA and is a projection, then these weak sets partition the sets of alternatives and the restriction of the revealed preference relation to the weak sets is complete and acyclic (Theorem 1.3). A choice set S is called a ‘strong set’ if $F(X)$ is equal to the intersection of X and S whenever $F(X)$ has a nonempty intersection with S . Here, we show that if F satisfies IIA, then these strong sets partition the sets of alternatives and the restriction of the revealed preference relation to the strong sets is complete and acyclic (Theorem 1.4). In this case, the strong sets determine a unique IIA choice correspondence.

In Section 1.2, we introduce the model and the three main conditions on a choice correspondence that we consider (WARP, WIIA, and IIA), establishing relations or lack thereof between them. Section 1.3 introduces the collections of weak sets and strong sets, and establishes some properties of these collections. In Section 1.4 we derive Theorems 1.3 and 1.4 mentioned above. Section 1.5 concludes with a summary of the results of the paper.

1.2 Model and properties

1.2.1 Model and basic definitions

Let A be a finite or infinite *set of alternatives* and let \mathcal{A} denote the class of its nonempty subsets, i.e., $\mathcal{A} = 2^A \setminus \{\emptyset\}$. A *choice correspondence* is a map $F : \mathcal{A} \rightarrow \mathcal{A}$ such that $F(X) \subseteq X$ for every $X \in \mathcal{A}$. A choice correspondence F induces an irreflexive binary relation $R_F \subseteq \mathcal{A} \times \mathcal{A}$ by

$$(X, Y) \in R_F \Leftrightarrow \text{there exist } Z \in \mathcal{A} \text{ with } X = F(Z) \text{ and } Y \subseteq Z$$

for all distinct $X, Y \in \mathcal{A}$. In this case we say that X is *revealed preferred to* Y by F and call R_F the *revealed preference relation of* F .

Later on we also use the following definitions and notations. A binary relation R on a set Ω is *transitive* if $(\omega^1, \omega^2), (\omega^2, \omega^3) \in R$ implies $(\omega^1, \omega^3) \in R$ for all distinct $\omega^1, \omega^2, \omega^3 \in \Omega$. The binary relation R has a *cycle* of length n , where

$n \in \mathbb{N} \setminus \{1\}$, if there are $\omega^1, \dots, \omega^n \in \Omega$ such that $(\omega^i, \omega^{i+1}) \in R$ for all $i \in \{1, \dots, n-1\}$ and $(\omega^n, \omega^1) \in R$; R is *acyclic* if it has no cycles of any length.

For a choice correspondence F , we use the notation $F^n(X)$ as shorthand for $F \circ (F \circ (\dots (F(X))))$, that is, the n -fold composition of F with itself.

In the sequel, we denote a generic choice correspondence by F and consequently, its revealed preference relation by R_F .

1.2.2 Weak axiom of revealed preference

The following definition is the standard notion of revealed preference adapted to our model.

Weak axiom of revealed preference (WARP). *For all $X, Y \in \mathcal{A}$, if $(X, Y) \in R_F$, then $(Y, X) \notin R_F$.*

In conformity with the literature, in the revealed preference relation, WARP excludes cycles of length two but not longer cycles (among others, Rose, 1958; Peters and Wakker, 1994; Bossert and Peters, 2009). For completeness, we provide the following example, which contains a cycle of length three, but cycles of arbitrary length can be easily constructed in similar examples.

Example 1.1. Let $A = \{a, b, c\}$ and define F by

$$F(X) = \begin{cases} \{a, b, c\} & \text{if } X = \{a, b, c\} \\ \{a\} & \text{if } X \in \{\{a, b\}, \{a\}\} \\ \{b\} & \text{if } X \in \{\{b, c\}, \{b\}\} \\ \{c\} & \text{if } X \in \{\{a, c\}, \{c\}\}. \end{cases}$$

Since $F(a, b, c) = \{a, b, c\}$, it follows that for all $X \subsetneq \{a, b, c\}$, $(\{a, b, c\}, X) \in R_F$. Moreover, $F(a, b) = F(a) = \{a\}$ implies that $(\{a\}, \{a, b\}), (\{a\}, \{b\}) \in R_F$, $F(b, c) = F(b) = \{b\}$ implies that $(\{b\}, \{b, c\}), (\{b\}, \{c\}) \in R_F$, and finally $F(a, c) = F(c) = \{c\}$ implies that $(\{c\}, \{a, c\}), (\{c\}, \{a\}) \in R_F$. Therefore, F satisfies WARP but R_F contains a cycle of length three, i.e., $(\{a\}, \{b\}), (\{b\}, \{c\}), (\{c\}, \{a\}) \in R_F$.

The following lemma characterizes WARP.

Lemma 1.1. *F satisfies WARP if and only if for all $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, $F(X) = F(Y \cup F(X))$.*

Proof. Let F satisfy WARP and let $X, Y \in \mathcal{A}$ with $Y \subseteq X$. Suppose that $F(X) \neq F(Y \cup F(X))$. Since $F(Y \cup F(X)) \subseteq X$, the definition of R_F implies $(F(X), F(Y \cup F(X))) \in R_F$; and since $F(X) \subseteq Y \cup F(X)$, we similarly obtain $(F(Y \cup F(X)), F(X)) \in R_F$. This violates WARP, and therefore, $F(X) = F(Y \cup F(X))$.

Next, let for all $X \in \mathcal{A}$ and all $Y \subseteq X$, $F(X) = F(Y \cup F(X))$. Let distinct $V, W \in \mathcal{A}$ such that $(V, W), (W, V) \in R_F$. We derive a contradiction as follows. Since $(V, W) \in R_F$, there exists $Z \in \mathcal{A}$ such that $F(Z) = V$ and $W \subseteq Z$. Similarly, since $(W, V) \in R_F$, there exists $Z' \in \mathcal{A}$, such that $F(Z') = W$ and $V \subseteq Z'$. Therefore, $W \subseteq Z$ and $V \subseteq Z'$ imply $F(Z) = F(W \cup F(Z)) = F(W \cup V) = F(F(Z') \cup V) = F(Z')$; thus $V = W$, a contradiction. \square

An immediate consequence of Lemma 1.1 is that if F satisfies WARP then it is a projection, a fact also established in Brand and Harrenstein (2011).

Corollary 1.1. *Let F satisfy WARP. Then, for all $X \in \mathcal{A}$, $F^2(X) = F(X)$.*

Proof. By Lemma 1.1, for all pairs $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, $F(X) = F(Y \cup F(X))$. Choosing $Y = F(X)$ implies $F^2(X) = F(X)$. \square

Notice that the reverse is not true, as illustrated in the following example.

Example 1.2. Let $A = [0, 1]$ and define F as follows.

$$F(X) = \begin{cases} \{1\} & \text{if } X = [0, 1] \\ X & \text{otherwise.} \end{cases}$$

Clearly $F^2(X) = F(X)$. Next, consider sets $[0, 1]$ and $[\frac{1}{2}, 1]$. Since $[\frac{1}{2}, 1] \subseteq [0, 1]$ and $F([0, 1]) = \{1\}$, $(\{1\}, [\frac{1}{2}, 1]) \in R_F$; in addition, since $\{1\} \subseteq [\frac{1}{2}, 1]$ and $F([\frac{1}{2}, 1]) = [\frac{1}{2}, 1]$, $([\frac{1}{2}, 1], \{1\}) \in R_F$. Therefore, F violates WARP. Note that a similar example with a finite A can easily be constructed.

Brand and Harrenstein (2011) use the expression ‘set-rationalizability’ instead of WARP and show that this is equivalent to a set-valued version of Chernoff’s condition, which we now define.

Condition $\hat{\alpha}$. *For all $X, Y \in \mathcal{A}$, if $F(X \cup Y) \subseteq X \cap Y$, then $F(X \cup Y) = F(X)$.*

It follows that condition $\hat{\alpha}$ is equivalent to the condition in Lemma 1.1. This is not hard to show directly, witnessing the following lemma, which together with Lemma 1.1 provides an alternative proof of Theorem 2 in Brand and Harrenstein (2011).

Lemma 1.2. *F satisfies condition $\hat{\alpha}$ if and only if for all $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, $F(X) = F(Y \cup F(X))$.*

Proof. Let F satisfy condition $\hat{\alpha}$ and $X, Y \in \mathcal{A}$ with $Y \subseteq X$. Let $X' = X$ and $Y' = Y \cup F(X)$. Then $F(X' \cup Y') = F(X) \subseteq X' \cap Y'$ and condition $\hat{\alpha}$ imply $F(X' \cup Y') = F(Y')$. Therefore, $F(X) = F(Y \cup F(X))$.

Next, let $X, Y \in \mathcal{A}$ with $F(X \cup Y) \subseteq X \cap Y$. In addition, let $X' = X \cup Y$ and $Y' = X \setminus F(X \cup Y)$. Then, assuming that for all $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, $F(X) = F(Y \cup F(X))$, implies that $F(X \cup Y) = F(X') = F(Y' \cup F(X')) = F((X \setminus F(X \cup Y)) \cup F(X \cup Y)) = F(X)$, where the last equality follows since $F(X \cup Y) \subseteq X \cap Y \subseteq X$. Therefore, condition $\hat{\alpha}$ is satisfied. \square

1.2.3 Weak independence of irrelevant alternatives

The next property requires, for each set X and for every subset of X that has a nonempty intersection with $F(X)$, only alternatives from $F(X)$ to be chosen.

Weak independence of irrelevant alternatives (WIIA). *For all $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, if $F(X) \cap Y \neq \emptyset$, then $F(Y) \subseteq F(X)$.*

Example 1.3 below shows that WIIA does not imply WARP. The reverse does not hold either, as shown in Example 1.4 that follows.

Example 1.3. Let $A = \mathbb{N}$ and define F by

$$F(X) = \begin{cases} X & \text{if } |X| = 1 \text{ or } X \text{ is infinite} \\ X \setminus \{\max(X)\} & \text{if } 1 < |X| < \infty. \end{cases}$$

Let $Y \subseteq X$ such that $F(X) \cap Y \neq \emptyset$. If X is infinite, then trivially $F(Y) \subseteq X = F(X)$. If X is finite and $|Y| = 1$, then $F(Y) = Y \cap F(X) = Y$. Otherwise, $F(Y) \subseteq Y \cap F(X)$. Hence, F satisfies WIIA. However, let $X = \{1, 2, 3\}$ and $Y = \{1, 2\}$. Then $F(X) = \{1, 2\}$ implies $(\{1, 2\}, \{1\}) \in R_F$, while $F(Y) = \{1\}$ implies $(\{1\}, \{1, 2\}) \in R_F$. Hence, F does not satisfy WARP. Note that these statements also hold for finite $A = \{1, 2, \dots, n\}$ with $n \geq 3$.

Example 1.4. Let $A = [0, 1]$ and define F by

$$F(X) = \begin{cases} X \setminus \{0\} & \text{if } X \subseteq [0, 1] \text{ with } X \cap (\frac{1}{2}, 1] \neq \emptyset \\ X & \text{otherwise.} \end{cases}$$

Then $F([0, 1]) = (0, 1]$ whereas $F([0, \frac{1}{2}]) = [0, \frac{1}{2}]$; hence, F does not satisfy WIIA. By using Lemma 1.1 it is straightforward that F satisfies WARP. The example can be easily adapted to a finite A .

Thus, there is no direct logical relation between WIIA and WARP. However, if F satisfies WIIA then the restriction of R_F to singletons has no cycles of length two. This is not surprising since WIIA reduces to the classical IIA for single-valued choice correspondences. For completeness, we provide the simple proof. Let r_F denote this restriction, i.e., $(\{x\}, \{y\}) \in r_F$ for distinct $x, y \in A$ if there is $Z \subseteq A$ such that $F(Z) = \{x\}$ and $y \in Z$.

Lemma 1.3. *Let F satisfy WIIA. Then r_F has no cycles of length two.*

Proof. Let distinct $\{x\}, \{y\} \in \mathcal{A}$ and assume that $(\{x\}, \{y\}) \in r_F$ and $(\{y\}, \{x\}) \in r_F$ to derive a contradiction. Since $(\{x\}, \{y\}) \in r_F$, there exists $X \in \mathcal{A}$ such that $F(X) = \{x\}$ and $y \in X$. Similarly, there exists $Y \in \mathcal{A}$ such that $x \in Y$ and $F(Y) = \{y\}$. Since $\{x, y\} \subseteq X$ and $F(X) \cap \{x, y\} \neq \emptyset$, WIIA implies $F(x, y) \subseteq F(X) \cap \{x, y\} = \{x\}$; hence, $F(x, y) = \{x\}$. Similarly, one obtains $F(x, y) = \{y\}$. Since $x \neq y$ this is a contradiction. \square

If we add the condition that F be a projection, i.e. $F^2 = F$, then WIIA implies WARP.

Lemma 1.4. *Let F satisfy WIIA and $F^2 = F$. Then, F satisfies WARP.*

Proof. Let $X, Y, Z, Z' \in \mathcal{A}$ such that $X, Y \subseteq Z$, $X, Y \subseteq Z'$, $F(Z) = X$, and $F(Z') = Y$. By WIIA we have both $F(X \cup Y) \subseteq F(Z') = Y$ and $F(X \cup Y) \subseteq F(Z) = X$, so that $F(X \cup Y) \subseteq X \cap Y$. This implies $X \cap Y = F(Z) \cap F(Z') \neq \emptyset$. Hence, by Lemma 1.11, $F(Z) \cup F(Z') = F(F(Z) \cup F(Z'))$, and therefore $X \cup Y = F(X \cup Y) \subseteq X \cap Y$, which implies $X = Y$. We conclude that F satisfies WARP. \square

The converse of Lemma 1.4 does not hold. If F satisfies WARP then by Corollary 1.1 it is a projection, but Example 1.4 shows that WIIA does not have to hold.

The following result shows that if F satisfies WIIA, then so does every n -fold composition of F with itself. It will be useful later on.

Lemma 1.5. *Let F satisfy WIIA and let $n \in \mathbb{N}$ with $n \geq 2$. Then F^n satisfies WIIA.*

Proof. The proof is based on induction: $F^1 = F$ satisfies WIIA, and assume that F^k satisfies WIIA for every $k = 2, \dots, n-1$. Let $X, Y \in \mathcal{A}$ with $Y \subseteq X$ and $F^n(X) \cap Y \neq \emptyset$. We have to show that $F^n(Y) \subseteq F^n(X)$.

Note that for every $k \in \{1, \dots, n-1\}$, $F^k(X) \cap Y \neq \emptyset$ and the induction assumption imply that $F^k(Y) \subseteq F^k(X)$ and thus, that

$$F^\ell(X) \cap F^m(Y) \neq \emptyset \text{ for all } \ell, m \in \{1, \dots, n-1\}. \quad (1.1)$$

We now first prove that

$$F^n(X) \cap F^k(Y) \neq \emptyset \text{ for every } k = 0, \dots, n-1 \quad (1.2)$$

where $F^0(Y) = Y$. The proof of (1.2) is by induction. By assumption, $F^n(X) \cap F^0(Y) = F^n(X) \cap Y \neq \emptyset$. Let $1 \leq \ell \leq n-1$ and assume that $F^n(X) \cap F^k(Y) \neq \emptyset$ for every $k = 1, \dots, \ell-1$. We show that $F^n(X) \cap F^\ell(Y) \neq \emptyset$. First, since $\emptyset \neq F^{n-1}(X) \cap F^{\ell-1}(Y) \subseteq F^{n-1}(X)$ by (1.1), and $F^n(X) \cap (F^{n-1}(X) \cap F^{\ell-1}(Y)) = F^n(X) \cap F^{\ell-1}(Y) \neq \emptyset$ by the induction assumption for this part, WIIA of F implies

$$F(F^{n-1}(X) \cap F^{\ell-1}(Y)) \subseteq F^n(X). \quad (1.3)$$

Second, since $\emptyset \neq F^{n-1}(X) \cap F^{\ell-1}(Y) \subseteq F^{\ell-1}(Y)$ by (1.1), and $F^\ell(Y) \cap (F^{n-1}(X) \cap F^{\ell-1}(Y)) = F^\ell(Y) \cap F^{n-1}(X) \neq \emptyset$ by (1.1), WIIA of F implies

$$F(F^{n-1}(X) \cap F^{\ell-1}(Y)) \subseteq F^\ell(Y). \quad (1.4)$$

By (1.3) and (1.4), $F^n(X) \cap F^\ell(Y) \neq \emptyset$, which completes the proof of (1.2).

Now, since $F^{n-1}(X) \cap Y \neq \emptyset$, the assumed WIIA of F^{n-1} implies $F^{n-1}(Y) \subseteq F^{n-1}(X)$. Since by (1.2) we have $F^n(X) \cap F^{n-1}(Y) \neq \emptyset$, WIIA of F implies $F^n(Y) \subseteq F^n(X)$. This completes the proof of the lemma. \square

If A is finite, then there exists $n \in \mathbb{N}$ such that $F^\ell = F^n$ for all $\ell \geq n$. In this case, Lemma 1.5 implies that if F satisfies WIIA, then so does F^n . If A is infinite, such an n does not necessarily exist. However, we may define F^∞ by $F^\infty(X) = \bigcap_{n \in \mathbb{N}} F^n(X)$ for every $X \in \mathcal{A}$, assuming that this set is nonempty for every $X \in \mathcal{A}$. The following example shows that this condition is not necessarily satisfied if F satisfies WIIA.

Example 1.5. Let $A = [0, 1]$ and for every $X \in \mathcal{A}$, let x be the maximal number in $\mathbb{N} \cup \{0\}$ such that $X \subseteq [0, \frac{1}{2^x}]$. We define F by

$$F(X) = \begin{cases} X \setminus (\frac{1}{2^{x+1}}, \frac{1}{2^x}] & \text{if } X \setminus (\frac{1}{2^{x+1}}, \frac{1}{2^x}] \neq \emptyset \\ X & \text{otherwise.} \end{cases}$$

It is easy to check that F satisfies WIIA. However, $\bigcap_{n \in \mathbb{N}} F^n(A \setminus \{0\}) = \bigcap_{n \in \mathbb{N}} (0, \frac{1}{2^n}] = \emptyset$.

Remark 1.1. If F satisfies WIIA and F^∞ is well defined, then it follows from Lemma 1.5 that F^∞ satisfies WIIA.

1.2.4 Independence of irrelevant alternatives

The next property was first proposed by Nash (cf. Shubik, 1982), and also appears in Chernoff (1954) and Arrow (1959).

Independence of irrelevant alternatives (IIA). *For all $X, Y \in \mathcal{A}$ such that $Y \subseteq X$, if $F(X) \cap Y \neq \emptyset$, then $F(Y) = F(X) \cap Y$.*

For single-valued choice, IIA is equivalent to WARP as long as the domain of choice sets is closed under intersection, more precisely, if every nonempty intersection is in the domain. In the present context, this is no longer true: IIA implies WARP, as shown by the lemma below, but not the other way around, as shown by the example that follows.

Lemma 1.6. *Let F satisfy IIA. Then F satisfies WARP.*

Proof. Let $X, Y \in \mathcal{A}$ such that $(X, Y) \in R_F$. Then there is $Z \in \mathcal{A}$ such that $F(Z) = X$ and $Y \subseteq Z$. We have to show that $(Y, X) \notin R_F$. This is true if $F(V) = Y$ for no $V \in \mathcal{A}$ with $X \subseteq V$. Now suppose $F(V) = Y$ for some $V \in \mathcal{A}$ with $X \subseteq V$. If $X \subseteq V$ then by IIA applied to $Z \cap V$ we have both $F(Z \cap V) = X$ and $F(Z \cap V) = Y$, an impossibility since $X \neq Y$. Therefore, $X \not\subseteq V$, which completes the proof. \square

Example 1.6. Let $A = \{a, b, c\}$ and define F by

$$F(X) = \begin{cases} \{a\} & \text{if } X \in \{\{a, b\}, \{a, c\}\} \\ \{b\} & \text{if } X = \{b, c\} \\ X & \text{otherwise.} \end{cases}$$

It can be easily checked that F satisfies WARP. However, since $\{a, b\} \subseteq \{a, b, c\}$ and $\{a, b\} \cap F(\{a, b, c\}) \neq \emptyset$, it follows that $F(\{a, b\}) = \{a\}$ violates IIA. By partitioning a set in three nonempty subsets, the example can be easily adapted to an infinite A .

In order to obtain a characterization of IIA we introduce the following condition on the revealed preference relation of a choice correspondence: if X is revealed preferred to Y , then every subset of X that includes all alternatives in $X \cap Y$, is also revealed preferred to Y .

Preference Axiom (PA) For all distinct $X, Y, Z \in \mathcal{A}$ such that $X \cap Y \subseteq Z \subseteq X$, if $(X, Y) \in R_F$, then $(Z, Y) \in R_F$.

This axiom can be interpreted as expressing that what really makes X (revealed) preferred to Y is the intersection of X and Y . Indeed, the axiom implies that if X is preferred to Y then $X \cap Y$, if nonempty, is preferred to Y .

We have the following characterization of IIA.

Theorem 1.1. *F satisfies IIA if and only if it satisfies WARP and PA.*

Proof. (only if part) Let F satisfy IIA. Then F satisfies WARP by Lemma 1.6. We show that F satisfies PA. Let distinct $X, Y, Z \in \mathcal{A}$ such that $X \cap Y \subseteq Z \subseteq X$ and $(X, Y) \in R_F$. By IIA of F and $(X, Y) \in R_F$, $F(X \cup Y) = X$. Since $Z \cup Y \subseteq X \cup Y$ and $F(X \cup Y) \cap (Z \cup Y) = X \cap (Z \cup Y) = (X \cap Z) \cup (X \cap Y) = Z \neq \emptyset$, IIA of F implies $F(Z \cup Y) = Z$. Therefore, $(Z, Y) \in R_F$.

(if part) Let F satisfy WARP and PA. We show that F satisfies IIA. Let $X, Y \in \mathcal{A}$ with $Y \subseteq X$ and $F(X) \cap Y \neq \emptyset$. Suppose that $F(Y) \neq F(X) \cap Y$. Since $F(Y) \subseteq Y \subseteq X$, it follows that $(F(X), F(Y)) \in R_F$. In addition, $(F(X) \cap F(Y)) \subseteq (F(X) \cap Y) \subseteq F(X)$, so that by PA, $(F(X) \cap Y, F(Y)) \in R_F$. But also, $F(Y) \subseteq Y$ and $F(X) \cap Y \subseteq Y$ imply $(F(Y), F(X) \cap Y) \in R_F$. This violates WARP; therefore $F(Y) = F(X) \cap Y$. Thus, F satisfies IIA. \square

In Example 1.6, F satisfies WARP but not IIA. Hence it follows from Theorem 1.1 that F does not satisfy PA either. This can also be easily established directly. E.g., let $X = \{a, b, c\}$, $Y = \{b\}$, and $Z = \{a, b\}$, then $(X, Y) \in R_F$ but $(Z, Y) \notin R_F$.

The next example shows that PA does not imply IIA or WARP.

Example 1.7. Let $A = \{a, b, c, d\}$ and define F by

$$F(X) = \begin{cases} \{a, b\} & \text{if } X = \{a, b, c, d\} \\ \{a\} & \text{if } X \subsetneq \{a, b, c, d\} \text{ and } a \in X \\ \{b\} & \text{if } X \subseteq \{b, c, d\} \text{ and } b \in X \\ \{c\} & \text{if } X \subseteq \{c, d\} \text{ and } c \in X \\ \{d\} & \text{if } X = \{d\}. \end{cases}$$

It is straightforward to show that F satisfies PA. Since $\{a, b\} \subseteq \{a, b, c, d\}$, $\{a, b\} \cap F(\{a, b, c, d\}) \neq \emptyset$, and $F(\{a, b\}) = \{a\}$, it follows that F does not satisfy IIA and by Theorem 1.1, it also does not satisfy WARP.

In Section 1.2.3 we have already seen that WIIA and WARP are logically independent. The same is true for WIIA and PA since in Example 1.3, F satisfies WIIA but not PA. The following example shows that PA does not imply WIIA.

Example 1.8. Let $A = \{a, b, c\}$ and define F by

$$F(X) = \begin{cases} \{a\} & \text{if } X = A \\ X & \text{otherwise.} \end{cases}$$

In this case, F does not satisfy WIIA since $F(\{a, b\}) = \{a, b\} \not\subseteq \{a\} = F(A) \cap \{a, b\}$. To show that F satisfies PA, let X, Y, Z as in the statement of PA and $V \in \mathcal{A}$ such that $F(V) = X$ and $Y \subseteq V$. If $|X| = 1$ then either $V = X$ and then $Z = X = Y$, a contradiction since $Z \neq Y$; or $V = A$, which implies $X = \{a\}$ and therefore $Z = \{a\} = X$, so that $(Z, Y) \in R_F$. If $|X| = 2$, then $V = X$ and $Y \subseteq X$ with $|Y| = 1$; this implies $Z = X$ and thus $(Z, Y) \in R_F$.

Theorem 1.2. *Let F satisfy IIA. Then R_F is transitive and acyclic.*

Proof. By Theorem 1.1, F satisfies WARP. It is sufficient to prove that R_F is transitive, since with WARP this implies acyclicity. Let distinct $X_1, X_2, X_3 \in \mathcal{A}$ with $(X_1, X_2), (X_2, X_3) \in R_F$. We prove that $(X_1, X_3) \in R_F$. Let $Z = X_1 \cup X_2 \cup X_3$. We consider two cases for $F(Z)$.

If $F(Z) \cap X_3 = \emptyset$ then $F(Z) \subseteq X_1 \cup X_2$. If $F(Z) \neq X_1$ then $(F(Z), X_1) \in R_F$. On the other hand, since $(X_1, X_2) \in R_F$ there is $Z_1 \in \mathcal{A}$ such that $F(Z_1) = X_1$ whereas $X_2 \subseteq Z_1$; in particular, this implies $(X_1, F(Z)) \in R_F$, so that WARP is violated. Hence, in this case, $F(Z) = X_1$ and therefore $(X_1, X_3) \in R_F$.

If $F(Z) \cap X_3 \neq \emptyset$ then $F(X_2 \cup X_3) = F(Z) \cap (X_2 \cup X_3)$ by IIA, hence $F(X_2 \cup X_3) \cap X_3 \neq \emptyset$. This implies $(F(X_2 \cup X_3), X_2) \in R_F$. On the other hand, by a similar argument as in the first case, $(X_2, X_3) \in R_F$ implies $(X_2, F(X_2 \cup X_3)) \in R_F$, violating WARP. Hence, in this case, $(X_1, X_3) \in R_F$, which concludes the proof of the theorem. \square

For (single-valued) choice functions on a domain that is closed under nonempty intersection, *IIA* and *WARP* are equivalent, but do not necessarily imply acyclicity of the revealed preference relation (e.g., Gale, 1960; Peters and Wakker, 1994).³ In our case, IIA is stronger than WARP (cf. Theorem 1.1), and implies transitivity and acyclicity of the revealed preference relation.

The converse of Theorem 1.2 does not hold: the revealed preference relation R_F of the choice correspondence F in Example 1.7 is transitive and acyclic, but F does not satisfy IIA.

1.3 Weak and strong sets

In this section we introduce two collections of choice sets in relation to a given choice correspondence. We will show, in this section and the next one, that these collections are relevant for choice correspondences satisfying *WIIA* and *IIA*, respectively.

1.3.1 Weak sets

A set $S \in \mathcal{A}$ is a *weak set* if the following holds. For all sets where some alternatives of S are chosen, only alternatives of S are chosen; and in addition, if all alternatives of S are available, then all alternatives of S are chosen.

Weak sets. $S \in \mathcal{A}$ is a *weak set* at F if for all $X \in \mathcal{A}$ for which $F(X) \cap S \neq \emptyset$, we have:

- (i) $F(X) \subseteq S$
- (ii) if $S \subseteq X$, then $F(X) = S$.

The set of weak sets at F is denoted by \mathcal{S}_F . By $R_{\mathcal{S}_F} = \{(X, Y) \in R_F \mid X, Y \in \mathcal{S}_F\}$ we denote the restriction of R_F to \mathcal{S}_F .

We show below that the elements of \mathcal{S}_F are pairwise disjoint and then, in Lemma 1.8 which follows, that $R_{\mathcal{S}_F}$ behaves well if F satisfies *WIIA*.

³That is, they do not necessarily imply that F satisfies the so-called Strong Axiom of Revealed Preference.

Lemma 1.7. *Let distinct $S, T \in \mathcal{S}_F$. Then, $S \cap T = \emptyset$.*

Proof. Let $Z = S \cup T$. Without loss of generality assume that $F(Z) \cap S \neq \emptyset$. Then $S \in \mathcal{S}_F$ and $S \subseteq Z$ imply $F(Z) = S$. If $S \cap T \neq \emptyset$, then $F(Z) \cap T \neq \emptyset$; hence $T \in \mathcal{S}_F$ and $T \subseteq Z$ imply $F(Z) = T = S$. This contradicts $S \neq T$. Consequently, $S \cap T = \emptyset$. \square

Lemma 1.8. *Let F satisfy WIIA. Then $R_{\mathcal{S}_F}$ is complete and acyclic.*

Proof. Let $S, T \in \mathcal{S}_F$ with $S \neq T$. By the definition of \mathcal{S}_F , $F(S \cup T) \in \{S, T\}$; hence, $R_{\mathcal{S}_F}$ is complete. Without loss of generality assume that $F(S \cup T) = S$. We show that $(T, S) \notin R_{\mathcal{S}_F}$, which implies that $R_{\mathcal{S}_F}$ has no cycles of length 2. To show this, let $Z \in \mathcal{A}$ with $S \cup T \subseteq Z$. If $(S \cup T) \cap F(Z) \neq \emptyset$, then by WIIA, $S = F(S \cup T) \subseteq (S \cup T) \cap F(Z)$. Since $S \in \mathcal{S}_F$, this implies that $F(Z) = S$. Since Z was arbitrary, we have $(T, S) \notin R_{\mathcal{S}_F}$.

In order to show that $R_{\mathcal{S}_F}$ has also no cycles of length larger than 2, let $n \geq 2$ and $S^0, \dots, S^n \in \mathcal{S}_F$ with $(S^i, S^{i+1}) \in R_{\mathcal{S}_F}$ for each $i = 0, \dots, n-1$. Since $R_{\mathcal{S}_F}$ has no cycles of length 2, it is sufficient to show that $(S^0, S^n) \in R_{\mathcal{S}_F}$. Since $S^i \in \mathcal{S}_F$ for every $i = 0, \dots, n$, we have $F(\cup_{i=0}^n S^i) = S^j$ for some $j \in \{0, \dots, n\}$. If $j \neq 0$, then $(S^{j-1}, S^j), (S^j, S^{j-1}) \in R_{\mathcal{S}_F}$, so that we have a cycle of length 2. Hence, $j = 0$, which implies in particular $(S^0, S^n) \in R_{\mathcal{S}_F}$. \square

1.3.2 Strong sets

A set $S \in \mathcal{A}$ is a *strong set* (of alternatives) if the following holds. For all sets where some alternatives of S are chosen, all the available alternatives of S are chosen, and only these.

Strong sets. $S \in \mathcal{A}$ is a *strong set* at F if for all $X \in \mathcal{A}$ for which $F(X) \cap S \neq \emptyset$, we have $F(X) = S \cap X$. The set of strong sets induced by F is denoted by $\tilde{\mathcal{S}}_F$. By $R_{\tilde{\mathcal{S}}_F} = \{(X, Y) \in R_F \mid X, Y \in \tilde{\mathcal{S}}_F\}$ we denote the restriction of R_F to $\tilde{\mathcal{S}}_F$.

Since, clearly, $\tilde{\mathcal{S}}_F \subseteq \mathcal{S}_F$, Lemmas 1.7 and 1.8 also hold for the set of strong sets. For easy reference we formulate the following lemma.

Lemma 1.9. *The elements of $\tilde{\mathcal{S}}_F$ are pairwise disjoint, and $R_{\tilde{\mathcal{S}}_F}$ is complete and acyclic.*

1.4 Partitions induced by WIIA and IIA

In this section we discuss partitions of the set of alternatives related to WIIA and IIA of a choice correspondence. These are the sets of weak and strong sets introduced in the preceding section.

1.4.1 Weak sets and WIIA

Before proceeding with our main result, we first present to lemmas that are used in its proof. Specifically, given a choice correspondence F , Lemma 1.10 shows some consequences for sets of choice sets (i.e., some $\mathcal{Z} \subseteq \mathcal{A}$) with common chosen alternatives in all these choice sets, if WIIA or IIA are satisfied by F . Then, Lemma 1.11 strengthens this result in the case where $F^2 = F$.

Lemma 1.10. *Let F be a choice correspondence and $\emptyset \neq \mathcal{Z} \subseteq \mathcal{A}$ such that $\cap_{Z \in \mathcal{Z}} F(Z) \neq \emptyset$. Then the following statements hold:*

- (i) *If F satisfies WIIA then $\cup_{Z \in \mathcal{Z}} F(Z) \subseteq F(\cup_{Z \in \mathcal{Z}} Z)$.*
- (ii) *If F satisfies IIA then $\cup_{Z \in \mathcal{Z}} F(Z) = F(\cup_{Z \in \mathcal{Z}} Z)$.*

Proof. (i) Let $x \in \cap_{Z \in \mathcal{Z}} F(Z)$. Since $F(\cup_{Z \in \mathcal{Z}} Z) \subseteq \cup_{Z \in \mathcal{Z}} Z$, there is $Z' \in \mathcal{Z}$ such that $Z' \cap F(\cup_{Z \in \mathcal{Z}} Z) \neq \emptyset$, so that $F(Z') \subseteq F(\cup_{Z \in \mathcal{Z}} Z)$ by WIIA. Hence, $x \in F(\cup_{Z \in \mathcal{Z}} Z)$, so that $Z' \cap F(\cup_{Z \in \mathcal{Z}} Z) \neq \emptyset$ for all $Z' \in \mathcal{Z}$, and hence $F(Z') \subseteq F(\cup_{Z \in \mathcal{Z}} Z)$ for all $Z' \in \mathcal{Z}$ by WIIA. This proves part (i).

(ii) Let F satisfy IIA. Using similar arguments as in part (i) now implies that $F(Z') = F(\cup_{Z \in \mathcal{Z}} Z) \cap Z'$ for all $Z' \in \mathcal{Z}$ by IIA. This proves part (ii). \square

Lemma 1.11. *Let F be a choice correspondence satisfying WIIA and $F^2 = F$. Let $\emptyset \neq \mathcal{Z} \subseteq \mathcal{A}$ such that $\cap_{Z \in \mathcal{Z}} F(Z) \neq \emptyset$. Then $\cup_{Z \in \mathcal{Z}} F(Z) = F(\cup_{Z \in \mathcal{Z}} F(Z))$.*

Proof. Let $x \in \cap_{Z \in \mathcal{Z}} F(Z)$. We first show that $x \in F(\cup_{Z \in \mathcal{Z}} F(Z))$. Since $F(\cup_{Z \in \mathcal{Z}} F(Z)) \subseteq \cup_{Z \in \mathcal{Z}} F(Z)$, there is a $Z' \in \mathcal{Z}$ such that $F(Z') \cap F(\cup_{Z \in \mathcal{Z}} F(Z)) \neq \emptyset$. Then WIIA and $F^2 = F$ imply $x \in F(Z') = F^2(Z') \subseteq F(\cup_{Z \in \mathcal{Z}} F(Z))$.

Since, thus, $x \in F(\cup_{Z \in \mathcal{Z}} F(Z))$ it follows that $F(Z') \cap F(\cup_{Z \in \mathcal{Z}} F(Z)) \neq \emptyset$ for all $Z' \in \mathcal{Z}$ and hence by WIIA and $F^2 = F$ that $F(Z') = F^2(Z') \subseteq F(\cup_{Z \in \mathcal{Z}} F(Z))$ for all $Z' \in \mathcal{Z}$. Hence, $\cup_{Z \in \mathcal{Z}} F(Z) \subseteq F(\cup_{Z \in \mathcal{Z}} F(Z))$. \square

Our main result follows.

Theorem 1.3. *Let F satisfy WIIA and let $F = F^2$. Then \mathcal{S}_F is a partition of A and $R_{\mathcal{S}_F}$ is complete and acyclic.*

Proof. Let $x \in A$. In view of Lemmas 1.7 and 1.8 we only still have to prove that there is an $S \in \mathcal{S}_F$ such that $x \in S$. Define $\mathcal{Z} = \{Z \in \mathcal{A} \mid x \in F(Z)\}$ and $S = \cup_{Z \in \mathcal{Z}} F(Z)$. It is sufficient to prove that $S \in \mathcal{S}_F$. To this end, let $X \in \mathcal{A}$ such that $F(X) \cap S \neq \emptyset$. This implies, in particular, that there is $Z' \in \mathcal{Z}$ such that $F(X) \cap F(Z') \neq \emptyset$. By Lemma 1.10(i) we obtain $F(X) \cup F(Z') \subseteq F(X \cup Z')$, which implies $x \in F(X \cup Z')$ and therefore $X \cup Z' \in \mathcal{Z}$. Hence $F(X) \subseteq F(X \cup Z') \subseteq S$. Finally, assume additionally that $S \subseteq X$. We show that $F(X) = S$, which then completes the proof. By Lemma 1.11, $S = \cup_{Z \in \mathcal{Z}} F(Z) = F(\cup_{Z \in \mathcal{Z}} F(Z)) = F(S)$. Since $S \subseteq X$ and $F(X) \cap S \neq \emptyset$, WIIA implies $F(S) \subseteq F(X)$ and therefore $S \subseteq F(X)$. Together with $F(X) \subseteq S$, this implies $F(X) = S$. \square

Theorem 1.3 thus states that a WIIA choice correspondence that is, moreover, a projection, induces a partition of the set of alternatives such that the alternatives assigned to every choice set lie in exactly one element of this partition. Moreover, if the choice set contains that partition element, then that element is assigned completely.

However, the converse of this result does not hold. Example 1.10 exhibits a projection F , where \mathcal{S}_F is a partition of A and $R_{\mathcal{S}_F}$ is complete and acyclic, that violates WIIA.

Two particular applications that follows from Theorem 1.3 are collected in the following corollary.

Corollary 1.2. *Let F satisfy WIIA.*

(i) *If A is finite and $m = |A| - 1$, then \mathcal{S}_{F^m} is a partition of A and $R_{\mathcal{S}_{F^m}}$ is complete and acyclic.*

(ii) *If F^∞ is well-defined and $F^\infty = F^\infty \circ F^\infty$, then \mathcal{S}_{F^∞} is a partition of A and $R_{\mathcal{S}_{F^\infty}}$ is complete and acyclic.*

Proof. Statement (i) follows from Lemma 1.5 and Theorem 1.3. Statement (ii) follows from Remark 1.1 and Theorem 1.3. \square

The condition in Corollary 1.2(ii) that F^∞ is a projection is not redundant as is illustrated by the following example.

Example 1.9. Let $A = \{-1, 0\} \cup \{\frac{1}{2^n} \mid n \in \mathbb{N}\}$. Define F by

$$F(X) = \begin{cases} X \setminus \{\max\{x : x \in X\}\} & \text{if } |X| > 1 \\ X & \text{otherwise.} \end{cases}$$

Then F^∞ is well-defined, and both F and F^∞ satisfy WIIA. Since $F^\infty(A) = \{-1, 0\}$ and $F^\infty(\{-1, 0\}) = \{-1\}$, we have $F^\infty \circ F^\infty(A) = \{-1\} \neq F^\infty(A)$. Hence, $F^\infty \circ F^\infty \neq F^\infty$.

The following lemma concludes our study of WIIA in this chapter.

Lemma 1.12.

(i) For finite A , let F be a projection and satisfy WIIA, $S_0 = \emptyset$, and $S_i = F(A \setminus \cup_{k=0}^{i-1} S_k)$. Then, $\mathcal{S}_F = \{S_1, \dots, S_\ell\}$ and $(S_j, S_i) \in R_{\mathcal{S}_F}$ whenever $j < i$.

(ii) For general A , let \mathcal{T} be a partition of A completely and acyclically ordered by R , and suppose moreover that for every $X \in \mathcal{A}$, the collection $\{S \in \mathcal{T} \mid S \cap X \neq \emptyset\}$ has a maximal element S_X according to R . Then, there exists a (not necessarily unique) projection F satisfying WIIA, where $\mathcal{S}_F = \mathcal{T}$ and $R_{\mathcal{S}_F} = R$.

Proof. We prove statement (i) as follows: we first propose a partition \mathcal{T} of A , then we show that $\mathcal{S}_F = \mathcal{T}$, and finally we show that $R_{\mathcal{S}_F}$ is complete and acyclic. The proof of statement (ii) is much simpler.

(i) Since A is finite and for all $X \in \mathcal{A}$, $F(X) \subseteq X$ and $F(X) \neq \emptyset$, there exists a (finite) integer ℓ , where $S_\ell = F(A \setminus \cup_{k=0}^{\ell-1} S_k) = A \setminus \cup_{k=0}^{\ell-1} S_k$. Let $\mathcal{T} = \{S_1, \dots, S_\ell\}$; it follows that \mathcal{T} partitions A .

Next, since \mathcal{T} partitions A , for all $X \in \mathcal{A}$, there exists $\hat{k} \in \{1, \dots, \ell\}$ such that $X \subseteq A \setminus \cup_{k=0}^{\hat{k}-1} S_k$ and $X \cap S_{\hat{k}} \neq \emptyset$; hence, WIIA implies $F(X) \subseteq S_{\hat{k}}$. Moreover, notice that F being a projection implies $F(S_{\hat{k}}) = S_{\hat{k}}$; hence, if in addition $S_{\hat{k}} \subseteq X$, then it follows by WIIA that $F(X) = S_{\hat{k}}$. Therefore, $\mathcal{S}_F = \mathcal{T}$.

Finally, since $j < i \leq \ell$ implies that $S_j = F(A \setminus \cup_{k=0}^{j-1} S_k)$ and $S_i \subseteq A \setminus \cup_{k=0}^{i-1} S_k$, it follows that $(S_j, S_i) \in R_F$ which completes the proof.

(ii) Define F such that for all $X \in \mathcal{A}$, $F(X) = X \cap S_X$. It is easy to verify that F is a projection and satisfies WIIA (in fact it satisfies IIA). Moreover, it is clear that $\mathcal{S}_F = \mathcal{T}$ and $R_{\mathcal{S}_F} = R$. \square

1.4.2 Strong sets and IIA

The analogue of Theorem 1.3 is the following.

Theorem 1.4. *Let F satisfy IIA. Then $\tilde{\mathcal{S}}_F$ is a partition of A and $R_{\tilde{\mathcal{S}}_F}$ is complete and acyclic.*

Proof. Let $x \in A$. In view of Lemma 1.9 we only still have to prove that there is an $S \in \tilde{\mathcal{S}}_F$ such that $x \in S$. Define $\mathcal{Z} = \{Z \in \mathcal{A} \mid x \in F(Z)\}$ and $S = F(\cup_{Z \in \mathcal{Z}} Z)$. By Lemma 1.10(ii) we have $S = \cup_{Z \in \mathcal{Z}} F(Z) \ni x$, so that it is sufficient to prove

that $S \in \tilde{\mathcal{S}}_F$. To this end, let $X \in \mathcal{A}$ such that $F(X) \cap S \neq \emptyset$, then it is sufficient to prove that $F(X) = S \cap X$.

Since $F(X) \cap S \neq \emptyset$, Lemma 1.10(ii) implies $F(X) \cup S = F(X) \cup F(\cup_{Z \in \mathcal{Z}} Z) = F(X \cup (\cup_{Z \in \mathcal{Z}} Z))$. In particular, this implies that $F(X \cup (\cup_{Z \in \mathcal{Z}} Z)) \cap X \neq \emptyset$ so that by IIA we obtain $F(X) = F(X \cup (\cup_{Z \in \mathcal{Z}} Z)) \cap X$. Thus, it follows that $F(X) = (F(X) \cup S) \cap X = F(X) \cup (S \cap X)$. Hence, $F(X) \supseteq S \cap X$. Therefore, it is sufficient to prove that $F(X) \subseteq S \cap X$.

By Lemma 1.10(ii), $F(X) \cap S \neq \emptyset$ implies $F(X) \cap (\cup_{Z \in \mathcal{Z}} F(Z)) \neq \emptyset$. Hence, for some $Z' \in \mathcal{Z}$, $F(X) \cap F(Z') \neq \emptyset$. Thus, by Lemma 1.10(ii), $F(X \cup Z') = F(X) \cup F(Z')$. It follows that $x \in F(X \cup Z')$ and thus, $X \cup Z' \in \mathcal{Z}$. In addition, since $S = \cup_{Z \in \mathcal{Z}} F(Z)$, $F(X \cup Z') \subseteq S$, and hence, $F(X) \cup F(Z') \subseteq S$. Therefore, $F(X) \subseteq S$ and trivially, $F(X) \subseteq S \cap X$. \square

Remark 1.2. For finite A , if F satisfies IIA, then the set of strong sets $\tilde{\mathcal{S}}_F$ can be computed analogously as in Lemma 1.12(i). Conversely, for general A , let \mathcal{T} be a partition of A completely and acyclically ordered by R . Suppose moreover that for every $X \in \mathcal{A}$, the collection $\{S \in \mathcal{T} \mid S \cap X \neq \emptyset\}$ has a maximal element S_X according to R . Then, it is easy to verify that $F(X) = X \cap S_X$ defines an IIA choice correspondence with $\tilde{\mathcal{S}}_F = \mathcal{T}$ as the set of strong sets with ordering $R_{\tilde{\mathcal{S}}_F} = R$. The uniqueness of F can be shown easily by contradiction: assuming that for some $Y \in \mathcal{A}$, $F(Y) \neq Y \cap S_Y$, either implies that F violates IIA, or that $F(S_Y) \neq S_Y$ and thus that $S_Y \notin \tilde{\mathcal{S}}_F$.

The logical converses of Theorems 1.3 and 1.4 do not hold. The following example describes a projection F of which the sets of weak and strong sets coincide, are a partition of A , and are completely and acyclically ordered by R_F , but which does not satisfy WIIA.

Example 1.10. Let $F(A) \subsetneq A$ and for all $X \in \mathcal{A}$ define F by

$$F(X) = \begin{cases} F(A) & \text{if } F(A) \subseteq X \\ X & \text{if } X \subseteq F(A) \\ X \setminus F(A) & \text{otherwise.} \end{cases}$$

It is straightforward to verify that F is a projection and $\mathcal{S}_F = \tilde{\mathcal{S}}_F = \{F(A), A \setminus F(A)\}$, which is a partition of A . Also, $R_{\mathcal{S}_F} = \{(F(A), A \setminus F(A))\}$ (in fact, it is not difficult to show that F satisfies WARP). Let $X, Y \in \mathcal{A}$ such that $F(A) \subseteq X$, $Y \subseteq X$, $Y \not\subseteq F(A)$, $F(A) \not\subseteq Y$, and $Y \cap F(A) \neq \emptyset$. Then $F(X) = F(A)$ but $F(Y) = Y \setminus F(A) \not\subseteq Y \cap F(A) = Y \cap F(X)$. Hence, F does not satisfy WIIA.

1.5 Summary

In this chapter we have established connections between the conditions of WARP, IIA, and WIIA for choice correspondences and their relations with the collections of weak and strong sets. The main results are summarized in Table 1.1 below.

WARP	Corollary 1.1 \implies	$F^2 = F$
WIIA & $F^2 = F$	Lemma 1.4 \implies	WARP
	Theorem 1.3 \implies	\mathcal{S}_F is a partition, $R_{\mathcal{S}_F}$ is complete and acyclic
IIA	Theorem 1.1 \iff	WARP & PA
	Theorem 1.2 \implies	R_F is transitive and acyclic

Table 1.1: Summary of main results

Chapter 2

Solidarity for public goods under single-peaked preferences: Characterizing target set correspondences

Abstract

We consider the problem of choosing a set of locations of a public good on the real line \mathbb{R} . Similarly to Klaus and Storcken (2002), we ordinally extend the agents' preferences over compact subsets of \mathbb{R} , and extend the results of Ching and Thomson (1996), Vohra (1999), and Klaus (2001) to choice correspondences. Specifically, we show that *efficiency* and either *population-monotonicity* or *one-sided replacement-dominance* characterize the class of target set correspondences on the domains of single-peaked preferences and symmetric single-peaked preferences.

2.1 Introduction

We study the social choice problem where a non-empty and compact set (of points) is chosen on the real line \mathbb{R} . We consider this (chosen) set to represent a public good such that each point in the set represents an option for the public good together with its location. We assume that agents have single-peaked preferences, that is, an agent's welfare is strictly increasing up to a certain point, his "peak", and is strictly decreasing beyond this point. Given a non-empty and compact set (of points) that represents the public good's options and their locations, an agent -although in good knowledge of all options and their respective locations- is unable to compute his chance of obtaining the public good at a particular location, e.g., in the case of parking spaces along a street, an agent knows that he will (eventually) find a parking spot somewhere along the street but he does not know where this will be. According to the literature, we should say that the agent needs to make a decision under *ignorance* (Peterson, 2009, p. 40). We therefore assume that

agents, when comparing sets, only consider their best (most favorite) point(s) and their worst (least favorite) point(s) in each set. Finally, we assume that the set has adequate capacity to accommodate all agents, that is, all agents have access to the public good but possibly at different locations.

More specifically, we look into the situation where the social planner wishes to make a choice by providing the public good in a way that is *efficient*, according to the agents' preferences, and that satisfies some notion of solidarity between agents towards changes in circumstances. Loosely speaking, solidarity requires that all agents not responsible for the change should be affected in the same direction. The changes in circumstances we study in this chapter are changes in the agents' population, by considering the property of *population-monotonicity*, and changes in some agents' preferences, by considering the property of *replacement-dominance*. *Population-monotonicity*, introduced in the context of bargaining (Thomson, 1983b,a), applies to a model with a variable population of agents and requires that if additional agents join a population, then the agents who were initially present should all be made at least as well off, as they were initially, or they should all be made at most as well off. *Replacement-dominance*, introduced in the context of quasi-linear binary public decision (Moulin, 1987), applies to a model with a fixed population of agents and requires that if the preferences of an agent change, then the other agents whose preferences remained unchanged should all be made at least as well off, as they were initially, or they should all be made at most as well off.

Further to the parking zone example, already briefly mentioned and further explained in Section 3.2, another example of the described situation could be the following. A social planner drafts an "if-needed" list of candidate locations to build a public hospital according to the agents' preferences. She does so in an effort to narrow down future construction scenarios while at the same time respecting (in an *efficient* sense) the agents' preferences and adhering to some notion of solidarity, as described above. Then, if at some future time the need to build a hospital materializes, each location in this list is scrutinized and one of them is chosen for the hospital to be built at, with this final verdict assumed unpredictable at the time when the list is drafted.

Many more social choice problems can be phrased as problems of providing a public good by choosing the location of it on the real line \mathbb{R} or an interval of it, or more generally, on a tree network,¹ when agents have single-peaked preferences. In these types of problems, it is very natural for changes in the population (e.g.,

¹A tree network is a connected graph that contains no cycles.

through a change in the birth or migration rate) or changes in the agents' preferences (e.g., through the influence of public media or social networks) to arise. Hence, the properties of *population-monotonicity* and *replacement-dominance* have been studied, together or individually, in a variety of contexts. For the special case where the tree network is a closed interval, the problem coincides with the problem of providing a public good by choosing its level when agents have single-peaked preferences (Moulin, 1980). Apart from the provision of public parking or the provision of a hospital by choosing an "if-needed" list of locations, further examples of providing a public good in one or more locations include the provision of (one or more) schools, parks, or libraries on a tree network that represents an infrastructure, e.g., the network of roads in a neighborhood.

For choice functions that assign a public good on an interval, or on a tree network, the solidarity properties *population-monotonicity* and *replacement-dominance*, have been considered. Specifically, for the location problem on an interval (on a tree network), it was shown that *efficiency* and *population-monotonicity* characterize the class of "target point functions" on the domain of single-peaked preferences (Thomson, 1993; Ching and Thomson, 1996).² and for constant sets of agents *efficiency* and *replacement-dominance* characterize the class of "target point functions" on the domains of single-peaked preferences and symmetric single-peaked preferences (Vohra, 1999). Moreover, it turns out that *efficiency* and *population-monotonicity* imply *replacement-dominance* and also, that the former characterization also holds on the domain of symmetric single-peaked preferences and on tree networks (Klaus, 2001). In addition, both aforementioned characterizations hold under much looser assumptions on the set of locations (alternatives) and the domain of preferences (Gordon, 2007a).³ Finally, if the set of admissible preferences is constrained on attribute-based preference domains,⁴ *efficiency* and either one of the two solidarity properties are only compatible on discrete trees, where equivalent characterizations are obtained (Gordon, 2015).

For the location problem on an interval, if the property of *replacement-*

²Each target point function is determined by its target point: if the target point is *efficient*, it is chosen; if it is not *efficient*, the closest *efficient* point is chosen. Such functions are sometimes called status quo rules or status quo solutions.

³The critical assumptions are: (i) the set of alternatives is fixed, (ii) the agents' preferences are defined over all alternatives, and (iii) the domain of preferences is common to all agents.

⁴Given a finite set of alternatives A , the non-empty and finite family of subsets $\mathcal{H} \subseteq 2^A$ is an attribute space if [for each attribute $H \in \mathcal{H}$, $H \neq \emptyset$ and the complement $H^C \in \mathcal{H}$] and [for each pair $x, y \in A$ with $x \neq y$, there exists $H \in \mathcal{H}$ such that $x \in H$ and $y \notin H$].

dominance is weakened to ϵ -*replacement-dominance*⁵ the characterization of target point functions still holds for the domain of single-peaked preferences (Harless, 2015a). However, for the location problem on a circle when a constant set of agents exists, no choice function satisfies *efficiency* and either *replacement-dominance* or *population-monotonicity* on the domain of symmetric single-peaked preferences (Gordon, 2007b).

Regarding choice correspondences, the case of providing a public good at exactly two locations, when one or both of the aforementioned solidarity properties are being considered, has been studied under different settings. On the domain of single-peaked preferences and if the agents compare pairs of locations using the max-extension,⁶ the following holds. For an interval in \mathbb{R} and a constant set of agents, the class of choice functions satisfying *efficiency* and *replacement-dominance* are the “left-peaks choice function” and the “right-peaks choice function”⁷ (Miyagawa, 2001). However, if this model is extended to trees, then no choice function satisfies *efficiency* and *replacement-dominance* on the symmetric single-peaked domain (Umezawa, 2012).

For the problem of providing a public good at exactly two locations on an interval, on the domain of single-peaked preferences and if agents compare pairs of locations using the leximin-extension,⁸ the following two results have been obtained that consider *population-monotonicity* or *replacement-dominance*. First, for a constant set of agents the class of choice functions satisfying *efficiency*, *anonymity*, and *population-monotonicity* is the class of “single-plateaued preference choice functions”⁹ (Ehlers, 2003); and second, in the same setting, the class of choice functions satisfying *efficiency* and *replacement-dominance* is the class of “single-peaked preference choice functions”¹⁰ (Ehlers, 2002).

⁵Agents’ solidarity is only required if the change in an agent’s preferences are below a certain threshold.

⁶Under the max-extension, an agent prefers set X to set Y if and only if he prefers his best point(s) in set X to his best point(s) in set Y .

⁷The left (right) peaks choice function chooses the two unique left-most (right-most) peaks.

⁸Under the leximin-extension, in the case of sets containing exactly two points, an agent prefers set X to set Y if and only if he either [prefers his best point(s) in set X to his best point(s) in set Y] or [he is indifferent between his best point in set X and his best point in set Y and prefers his second best point in set X to his second best point in set Y].

⁹Each single-plateaued preference choice function is determined by fixed single-plateaued preferences R and plateau $[r, \bar{r}]$: if all the agents’ peaks lie outside of $[r, \bar{r}]$, then loosely speaking, the best of the agents’ peaks and its indifferent point are chosen (according to R); otherwise, the two locations in the convex hull of the agents’ peaks lying closest to r and \bar{r} respectively are chosen.

¹⁰Each single-peaked preference choice function is essentially a single-plateaued preference choice function determined by a fixed single-plateaued preference relation R with the plateau being a point, i.e., $r = \bar{r}$.

In the setting of preference aggregation problems, where agents strictly rank a finite set of alternatives and a (not necessarily strict) social ranking over the alternatives must be chosen, the aforementioned solidarity properties have also been studied. It is shown that on the domain of strict rankings, *efficiency* and *population-monotonicity* characterize the class of “strict status-quo functions”¹¹ (Bossert and Sprumont, 2014). Moreover, in this result, *population-monotonicity* can be substituted with *adjacent replacement-dominance*.¹² Furthermore, if the domain is enlarged to also include weak rankings, *efficiency* and either *population-monotonicity* or *adjacent replacement-dominance* characterize the class of “status-quo functions”¹³ (Harless, 2016).

Finally, in the binary social choice model (i.e., when there are exactly two alternatives to choose from) and if agents can be indifferent between the two alternatives, a choice function satisfies *replacement-dominance* or *population-monotonicity* if and only if it is a “generalized mixed-consensus rule”¹⁴ (Harless, 2015b).

All the above mentioned work analyzes solidarity properties where at each preference profile, either at most two alternatives are chosen or a ranking over the alternatives is chosen. In this chapter we study a class of problems where more than two alternatives might be chosen, which are viewed as locations to provide a public good. This has been considered in a median voter context where the standard choice function setup is extended to choice correspondences since for an even number of agents or voters, a set of median voter locations exists, hence choosing the median implies choosing a set of median points (Klaus and Storcken, 2002). To capture the full spirit of this median voter result, Klaus and Storcken (2002) considered choice correspondences. Our motivation for extending

¹¹Each strict status-quo function is determined by a strict ranking R over the alternatives and reaches a unique efficient strict ranking as follows: beginning from R it reverses the order of an adjacently ranked pair of alternatives if all agents prefer the reverse to the initial ranking of the pair.

¹²*Adjacent replacement-dominance* is weaker than *replacement-dominance*: solidarity is only required when an agent reverses a single pair of adjacently ordered alternatives.

¹³Each status-quo function is determined by a ranking \bar{R} over the alternatives and reaches a unique efficient ranking as follows: beginning from \bar{R} it reverses the order of an adjacently ranked pair of single alternatives if all agents prefer the reverse to the initial ranking of the pair. Moreover, it “creates” order in an indifference class (of alternatives) if all agents prefer the alternative moved up in the order to the one (or more) alternatives moved down. Reversals in the order between a single alternative and an indifference class or between two indifference classes occur in a similar way.

¹⁴Each generalized mixed-consensus rule chooses for each profile either alternative a or alternative b . The only further requirement concerns cases where at least one agent prefers a over b and at least one agent prefers b over a ; specifically, either a is selected in all such cases or b is selected in all such cases.

choice from one or two locations to a set of locations is that we study situations in which the public good is usually provided through “larger” sets of options, e.g., the assignment of neighborhood parking spots along a street.

On the domain of single-peaked preferences as well as the smaller domain of symmetric single-peaked preferences, we show that the class of choice correspondences satisfying *efficiency* and either *one-sided replacement-dominance*¹⁵ or *population-monotonicity*, is the class of target set correspondences (Theorems 2.1 and 2.2). Each target set correspondence is determined by a target set $[a, b]$: if this set is *efficient*, it is chosen; if it is not *efficient*, then its largest *efficient* subset is chosen, if such a subset exists; otherwise, the closest *efficient* point to the target set is chosen. We also show that *efficiency* and *replacement-dominance* characterize the sub-class of target set correspondences where $a = b$, i.e., we obtain the class of target point functions (Corollary 2.3). Hence, we obtain corresponding results with the literature (Thomson, 1993; Ching and Thomson, 1996; Vohra, 1999).

Our results are parallel to the case where the public good is provided via a lottery over locations on an interval, and probabilistic target choice functions are characterized on the basis of *efficiency* and either *one-sided replacement-dominance* or *population-monotonicity* (Ehlers and Klaus, 2001).

The chapter proceeds as follows. Section 3.2 explains the model and states some preliminary results. Section 2.3 contains the definition of target set correspondences. Section 2.4 contains the solidarity properties and further preliminary results. Section 2.5 presents characterizations of target set correspondences.

2.2 The model

Denote the set of natural numbers by \mathbb{N} . There is a *grand population* of “potential” agents, indexed by $\mathbb{P} \subseteq \mathbb{N}$, where \mathbb{P} contains at least 3 agents. We denote the class of non-empty and finite subsets of \mathbb{P} by \mathcal{P} . A set of agents $N \in \mathcal{P}$ is called a *population*.

Each agent $i \in \mathbb{P}$ is equipped with *preferences* R_i , defined on the real line \mathbb{R} , that are *complete*, *transitive*, and *reflexive*. As usual, $x R_i y$ is interpreted as “ x is at least as desirable as y ”, $x P_i y$ as “ x is preferred to y ”, and $x I_i y$ as “ x is indifferent to y ”. Moreover, for preferences R_i there exists a number $p(R_i) \in \mathbb{R}$, called the *peak (level) of agent i* , with the following property: for each

¹⁵*One-sided replacement-dominance* is weaker than *replacement-dominance*: solidarity is not required when the preferences of the agent with the unique smallest peak are changed such that he becomes the agent with the unique largest peak, and vice-versa.

pair $x, y \in \mathbb{R}$ such that either $y < x \leq p(R_i)$, or $y > x \geq p(R_i)$, we have $x P_i y$. We call such preferences *single-peaked*. We denote the *domain of all single-peaked preferences* on \mathbb{R} by \mathcal{R} . Preferences R_i are *symmetric* if for each pair $x, y \in \mathbb{R}$, $|x - p(R_i)| = |y - p(R_i)|$ implies $x I_i y$. We denote the *domain of all symmetric single-peaked preferences* on \mathbb{R} by \mathcal{S} .

For each population $N \in \mathcal{P}$, we denote the set of (*preference*) *profiles* $R = (R_i)_{i \in N}$ where for each $i \in N$, $R_i \in \mathcal{R}$, by \mathcal{R}^N . Similarly, we denote the set of profiles $R = (R_i)_{i \in N}$, where for each $i \in N$, $R_i \in \mathcal{S}$ by \mathcal{S}^N . For each pair of populations $N, M \in \mathcal{P}$, with $N \subseteq M$, we denote the restriction $(R_i)_{i \in N} \in \mathcal{R}^N$ of profile $R \in \mathcal{R}^M$ to population N by R_N . Given profile $R \in \mathcal{R}^N$, for each pair $i, j \in N$ we also use the notation R_{-i} instead of $R_{N \setminus \{i\}}$ and $R_{-i,j}$ instead of $R_{N \setminus \{i,j\}}$.

In the sequel, all notation and definitions refer to single-peaked preferences but also apply to symmetric single-peaked preferences.

Given $N \in \mathcal{P}$ and $R \in \mathcal{R}^N$, we denote the (set of) *peaks* in R as $p(R) = \{p(R_i)\}_{i \in N}$. Let the *smallest peak* in R be $\underline{p}(R) \equiv \min \{p(R_i)\}_{i \in N}$ and the *largest peak* in R be $\bar{p}(R) \equiv \max \{p(R_i)\}_{i \in N}$. Let the *convex hull* of the peaks in R be $\text{Conv}(p(R)) \equiv [\underline{p}(R), \bar{p}(R)]$.

Denote the class of non-empty and compact subsets of \mathbb{R} by \mathcal{C} .¹⁶ Given a set $X \in \mathcal{C}$, let the *minimum (point)* of X be $\underline{X} \equiv \min X$ and the *maximum (point)* of X be $\bar{X} \equiv \max X$. Given a set $X \in \mathcal{C}$ and preferences $R_i \in \mathcal{R}$, let the set of most preferred point(s) or *best point(s)* of agent i in set X be $b_X(R_i) \equiv \{x \in X : \text{for each } y \in X, x R_i y\}$. Similarly, let the set of least preferred point(s) or *worst point(s)* of agent i in set X be $w_X(R_i) \equiv \{x \in X : \text{for each } y \in X, y R_i x\}$. Note that by single-peakedness the set $b_X(R_i)$ might contain two elements (when agent i 's peak is not included in set X); in this case, agent i is indifferent between these two elements. Similarly, $w_X(R_i) \subseteq \{\underline{X}, \bar{X}\}$ and in the case where $w_X(R_i) = \{\underline{X}, \bar{X}\}$ and $\underline{X} \neq \bar{X}$, agent i is again indifferent between these two elements. Hence, with some abuse of notation, we treat sets $b_X(R_i)$ and $w_X(R_i)$ as if they are points and for each $x \in X$, we write $b_X(R_i) R_i x R_i w_X(R_i)$.

We will consider choice correspondences that assign outcomes in \mathcal{C} with the interpretation that any agent “*knows the set of possible outcomes . . . , but has no information about the probabilities of those outcomes or about their likelihood ranking*” (Bossert et al., 2000, p. 295). For a survey of criteria and methods for ranking subsets of a set of outcomes under complete uncertainty we refer to

¹⁶As discussed in Remark 2.6, the requirement for sets in \mathcal{C} to be compact is without loss of generality.

Barberà et al. (2004, Section 3).

Before describing the extension of preferences over sets that we use, we first introduce the properties of *simple-monotonicity* and *independence* that characterize a small class of preference extensions over sets, albeit for a slightly different model than ours (Bossert et al., 2000, Theorem 1). We first illustrate via two examples why these properties are reasonable to assume in our model. Then, we present the characterization result and finally, we discuss its consequences for our model.

Note that below, we denote preferences defined over \mathcal{C} by $R_i^{\mathcal{C}}$ (if $x P_i y$, then $\{x\} P_i^{\mathcal{C}} \{y\}$).

Simple-monotonicity. *Let $x, y \in \mathbb{R}$. If $x P_i y$, then $\{x\} P_i^{\mathcal{C}} \{x, y\} P_i^{\mathcal{C}} \{y\}$.*

Independence. *Let $X, Y \in \mathcal{C}$ and $z \in \mathbb{R}$ such that $z \notin X \cup Y$. If $X P_i^{\mathcal{C}} Y$, then $[X \cup \{z\}] R_i^{\mathcal{C}} [Y \cup \{z\}]$.*

Both examples that follow pertain to a linear city whose residents own one car each and have single-peaked preferences over where to park.

Example 2.1 (Simple-monotonicity). All public parking is located in two (parking) garages at $x, y \in \mathbb{R}$, with $x \neq y$, that we simply refer to as zone x and y . Neither garage's capacity can accommodate all residents but the joint capacity is sufficient. Initially, a one-zone scheme is in place and all residents are assigned to either zone x or zone y : residents assigned to zone x (zone y) are only allowed to park at garage x (y), which has the capacity to accommodate them. Later, a two-zone scheme is adopted: each resident can use either one of the two garages. Consider a resident i of zone x who prefers x to y . Under the one-zone scheme he always parks at x , while under the two-zone scheme he sometimes parks at y (whenever x is full). We expect resident i to be worse off under the two-zone scheme, that is, if $x P_i y$, then $\{x\} P_i^{\mathcal{C}} \{x, y\} P_i^{\mathcal{C}} \{y\}$ and *simple-monotonicity* holds. \square

Example 2.2 (Independence). Two single-zone street parking schemes, $X \subset \mathbb{R}$ and $Y \subset \mathbb{R}$, are being considered for adoption. Before a final decision is made, and following a small development project on some previously unused land, an extra single parking garage $z \in \mathbb{R}$ becomes available. Now assume that instead of schemes X and Y , two new schemes are being considered for adoption, $X \cup \{z\}$ and $Y \cup \{z\}$. Suppose resident i initially prefers X to Y . Since space z was unavailable under X and Y and is now available under both $X \cup \{z\}$ and $Y \cup \{z\}$,

we expect i to find $X \cup \{z\}$ at least as desirable as $Y \cup \{z\}$. That is, if $z \notin X \cup Y$, and $X P_i^C Y$, then $[X \cup \{z\}] R_i^C [Y \cup \{z\}]$ and *independence* holds. \square

The next result shows that if the two aforementioned properties are required, an agent with *linear* preferences over outcomes¹⁷ only cares about his best and worst points in each finite set.¹⁸

Bossert et al. (2000, Theorem 1). *If simple-monotonicity and independence are satisfied, then for agent i with linear preferences R_i^L , and each finite set $X \in \mathcal{C}$, $X I_i^C \{b_X(R_i^L), w_X(R_i^L)\}$.*

In light of this result, two “standard” extensions that could be considered for our model are the *min-max*¹⁹ and the *max-min*²⁰ preference extensions, both of which fit our parking example since they are “consistent with the notion of limited rationality which is familiar in the theories of organization and bounded rationality (e.g., March (1988); March and Simon (1958)), and which suggests that, given a complex decision problem, the agent often seeks to simplify the problem by focusing on only a few salient features of the complex situation” (Bossert et al., 2000, pp. 300-301). However, given the problem at hand, we prefer to “not choose sides” by adopting either the “pessimistic” *min-max* extension or the “optimistic” *max-min* extension. Instead, we opt for the *best-worst* extension of preferences that declares a preference for a set X over a set Y if and only if this preference coincides with the preference of both the *min-max* extension and the *max-min* extension. Note however, as we discuss later, that this preference extension is incomplete. Finally, it is straightforward to show that the *best-worst* extension satisfies, *simple-monotonicity* and *independence*, not only when based on linear linear preferences over outcomes but also in our setting of single-peaked preferences over outcomes and sets of alternatives that are not always finite. In the sequel, and with a small abuse of notation, we use the same symbols to denote preferences over points and preferences over sets.

Specifically, under the *best-worst* extension of preferences over sets, when comparing two sets, an agent only considers his best and his worst point(s) in each

¹⁷A linear preference R^L is a *complete, transitive, reflexive, and antisymmetric* (i.e., for each $x, y \in \mathbb{R}$, $x I^L y$ implies $x = y$) binary relation. Single-peaked preferences are not antisymmetric.

¹⁸A similar result using a stronger version of *independence* is shown in Barberà et al. (1984).

¹⁹An agent prefers set X to set Y if and only if either [he prefers his worst point(s) in set X to his worst point(s) in set Y] or [he is indifferent between his worst point(s) in both sets and prefers his best point(s) in set X to his best point(s) in set Y].

²⁰An agent prefers set X to set Y if and only if either [he prefers his best point(s) in set X to his best point(s) in set Y] or [he is indifferent between his best point(s) in both sets and prefers his worst point(s) in set X to his worst point(s) in set Y].

of them. Given two sets $X, Y \in \mathcal{C}$, an agent prefers X to Y if he prefers his best point(s) in X to his best point(s) in Y and his worst point(s) in X to his worst point(s) in Y . The following definition also covers three more cases arising if an agent is indifferent between his best or worst point(s) in two sets.

Best-worst extension of preferences to sets. For each agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ and each pair of sets $X, Y \in \mathcal{C}$, we have

$$X R_i Y \text{ if and only if } \begin{cases} b_X(R_i) R_i b_Y(R_i) \\ \text{and} \\ w_X(R_i) R_i w_Y(R_i) \end{cases}$$

and

$$X P_i Y \text{ if and only if } X R_i Y \text{ and } \begin{cases} b_X(R_i) P_i b_Y(R_i) \\ \text{or} \\ w_X(R_i) P_i w_Y(R_i). \end{cases}$$

This extension of preferences is *transitive*, i.e., for each triple $X, Y, Z \in \mathcal{C}$, if $X R_i Y$ and $Y R_i Z$, then $X R_i Z$. However, it is not *complete*: there exist sets $X, Y \in \mathcal{C}$ such that neither $X R_i Y$ nor $Y R_i X$. To be more precise, we now make the following definition.

Comparability. Sets $X, Y \in \mathcal{C}$ are comparable by agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ if and only if $[b_X(R_i) P_i b_Y(R_i) \text{ implies } w_X(R_i) R_i w_Y(R_i)]$ and $[w_X(R_i) P_i w_Y(R_i) \text{ implies } b_X(R_i) R_i b_Y(R_i)]$.

Regarding the best-worst extension of preferences over sets, we now define *Pareto-efficiency*, *Pareto-dominance*, and *Pareto-equivalence*, henceforth, *efficiency*, *dominance*, and *equivalence* respectively.

Efficiency (of sets). Let $N \in \mathcal{P}$ and $R \in \mathcal{R}^N$. Set $X \in \mathcal{C}$ is efficient if and only if there is no set $Y \in \mathcal{C}$ such that for each $i \in N$, $Y R_i X$, and for at least one $j \in N$, $Y P_j X$. We denote the class containing all efficient sets for $R \in \mathcal{R}^N$ by $\text{PE}(R)$.

Dominance and equivalence. Let $N \in \mathcal{P}$ and $R \in \mathcal{R}^N$. Let pair $X, Y \in \mathcal{C}$ such that for each $i \in N$, $Y R_i X$. If for at least one $j \in N$, $Y P_j X$, then Y dominates X , otherwise Y and X are equivalent.

We now proceed to characterize efficient sets.

Proposition 2.1 (Efficient sets). For each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$, a set $X \in \mathcal{C}$ is efficient if and only if the following two conditions hold.

(i) X is a subset of the convex hull of the agents' peaks. That is,

$$X \subseteq \text{Conv}(p(R)).$$

(ii) All of the agents' peaks that lie in the convex hull of X are included in X . That is,

$$\text{Conv}(X) \cap p(R) \subseteq X.$$

We prove Proposition 2.1 in Appendix 2.A and illustrate it in Figure 2.1.

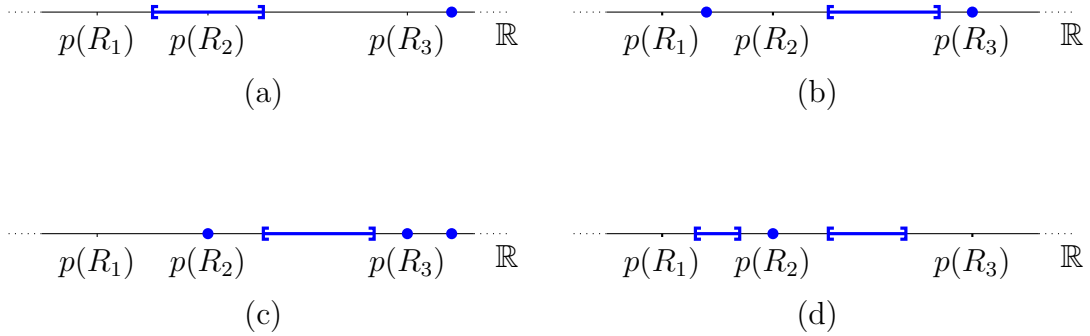


Figure 2.1: Let $N = \{1, 2, 3\}$ with $R \in \mathcal{R}^N$ and $p(R) = \{p(R_1), p(R_2), p(R_3)\}$. Sets under consideration are shown in bold. The set in (a) satisfies neither (i) nor (ii). The set in (b) satisfies (i) but not (ii). The set in (c) does not satisfy (i) but it satisfies (ii). The set in (d) satisfies both (i) and (ii), hence it is *efficient*.

When considering convex sets, the characterization in Proposition 2.1 simplifies.

Remark 2.1 (Efficient convex sets). For each $N \in \mathcal{P}$, each $R \in \mathcal{R}^N$, and each convex set $X = \text{Conv}(X) \in \mathcal{C}$, $X \in \text{PE}(R)$ if and only if $X \subseteq \text{Conv}(p(R))$. \square

Further consequences of Proposition 2.1 are Corollaries 2.1 and 2.2. Essentially, Corollary 2.1 states that given a population M with profile R , if $X \in \mathcal{C}$ is *efficient*, then it is also *efficient* for each population $N \subsetneq M$ such that the convex hull of population N 's peaks at profile R_N , and that of population M 's peaks at profile R , are the same.

Corollary 2.1. Let $M \in \mathcal{P}$, $R \in \mathcal{R}^M$, and $X \in \text{PE}(R)$. Then, for each $N \in \mathcal{P}$ such that $N \subsetneq M$ and $\text{Conv}(p(R_N)) = \text{Conv}(p(R))$, $X \in \text{PE}(R_N)$.

Proof. Let $N, M \in \mathcal{P}$ be such that $N \subsetneq M$, $R \in \mathcal{R}^M$, and $X \in \text{PE}(R)$. By Proposition 2.1 (i), $X \subseteq \text{Conv}(p(R))$. Since, $\text{Conv}(p(R)) = \text{Conv}(p(R_N))$, $X \subseteq \text{Conv}(p(R_N))$. By Proposition 2.1 (ii), $\text{Conv}(X) \cap p(R) \subseteq X$. Since, $p(R_N) \subsetneq p(R)$, $\text{Conv}(X) \cap p(R_N) \subseteq X$. By Proposition 2.1, $X \in \text{PE}(R_N)$. \square

Corollary 2.2 provides some consequences for *efficient* and *equivalent* sets.

Corollary 2.2. *Let $N \in \mathcal{P}$, $R \in \mathcal{R}^N$, and $X \in \text{PE}(R)$. Then, $\text{Conv}(X)$ is equivalent to X . Moreover, if Y is equivalent to X , then $\text{Conv}(Y) = \text{Conv}(X)$.*

We prove Corollary 2.2 in Appendix 2.A. Moreover, to simplify notation, in the sequel we always represent any *efficient* set by its convex hull.

2.3 Choice correspondences

A *choice correspondence* F assigns to each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$ a set $F(R) \in \mathcal{C}$, i.e., $F: \bigcup_{N \in \mathcal{P}} \mathcal{R}^N \rightarrow \mathcal{C}$. We denote the family of choice correspondences F by \mathcal{F} .

In the sequel, when the properties of *replacement-dominance* and *one-sided replacement-dominance* (defined in Section 2.4) are considered, the population of agents does not change. For this reason, we introduce *fixed-population choice correspondences*, henceforth *fp-choice correspondences*.

Given $N \in \mathcal{P}$, an *fp-choice correspondence* F for N assigns to each $R \in \mathcal{R}^N$ a set $F(R) \in \mathcal{C}$, i.e., $F: \mathcal{R}^N \rightarrow \mathcal{C}$. Let \mathcal{F}^N denote the family of fp-choice correspondences for N . A choice correspondence is a collection of fp-choice correspondences indexed by $N \in \mathcal{P}$.

Remark 2.2 (Choice functions). Given population $N \in \mathcal{P}$, if an fp-choice correspondence for N assigns to each $R \in \mathcal{R}^N$ a set consisting of a single point, it is essentially an fp-choice function. Similarly, if a choice correspondence assigns to each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$ a set consisting of a single point, it is essentially a choice function. \square

We now proceed to our *efficiency* notion for fp-choice correspondences and choice correspondences.

Efficiency (of choice correspondences).

(a) *Let $N \in \mathcal{P}$ and $F \in \mathcal{F}^N$ be an fp-choice correspondence. For each $R \in \mathcal{R}^N$, $F(R) \in \text{PE}(R)$.*

(b) Let choice correspondence $F \in \mathcal{F}$. For each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$, $F(R) \in \text{PE}(R)$.

The following classes of “target (choice) correspondences” and “fp-target (choice) correspondences” play an important role in the sequel.

Any *fp-target point correspondence* is determined by its fixed population and its target point. Similarly, any *target point correspondence* is determined by its target point. In both cases: if the target point is *efficient*, then it is chosen. If the target point is not *efficient*, then the (unique) closest *efficient* point to it is chosen.

Target point correspondences. Let $a \in \mathbb{R} \cup \{-\infty, \infty\}$. We define:

(a) for population $N \in \mathcal{P}$, the fp-target point correspondence with target a , $f^a \in \mathcal{F}^N$, such that for each $R \in \mathcal{R}^N$,	(b) the target point correspondence with target a , $f^a \in \mathcal{F}$, such that for each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$,
--	---

$$f^a(R) = \begin{cases} \{\underline{p}(R)\} & \text{if } a < \underline{p}(R) \\ \{\bar{p}(R)\} & \text{if } a > \bar{p}(R) \\ \{a\} & \text{otherwise.} \end{cases}$$

A (fp-)target point correspondence f^a is essentially a (*fp*-)target point function.²¹

Any *fp-target set correspondence* is determined by its population and its non-empty, closed, and convex target set. Similarly, any *target set correspondence* is determined by its non-empty, closed, and convex target set. In both cases: if the target set is *efficient*, it is chosen. If the target set is not *efficient*, the (unique) maximal *efficient* subset of the target set is chosen, if one exists; otherwise, the (unique) closest *efficient* point to the target set is chosen.

Target set correspondences. Let $[a, b] \subseteq \mathbb{R} \cup \{-\infty, \infty\}$. We define:

(a) for population $N \in \mathcal{P}$, the fp-target set correspondence with target $[a, b]$, $F^{a,b} \in \mathcal{F}^N$, such that for each $R \in \mathcal{R}^N$,	(b) the target set correspondence with target set $[a, b]$, $F^{a,b} \in \mathcal{F}$, such that for each $N \in \mathcal{P}$ and each $R \in \mathcal{R}^N$,
---	--

$$F^{a,b}(R) = \begin{cases} \{\underline{p}(R)\} & \text{if } b < \underline{p}(R) \\ \{\bar{p}(R)\} & \text{if } a > \bar{p}(R) \\ [a, b] \cap \text{Conv}(p(R)) & \text{otherwise.} \end{cases}$$

²¹The difference is that a (fp-)target point correspondence f^a only assigns singleton sets while the corresponding (fp-)target point function assigns the points in these sets.

Each target set correspondence is a set of fp-target set correspondences, one for each $N \in \mathcal{P}$, where the target set is constant and independent of the population. Also, each (fp-)target set correspondence with a target set $[a, b] \subseteq \mathbb{R} \cup \{-\infty, \infty\}$ such that $a = b$, is a (fp-)target point correspondence.

By Proposition 2.1, it follows that each (fp-)target set correspondence satisfies *efficiency*.

We illustrate the concept of an fp-target set correspondence in Figure 2.2. Since each target set correspondence is a collection of fp-target set correspondences indexed by $N \in \mathcal{P}$, a similar example for target set correspondences can be easily obtained if in Figure 2.2 we allow for the population to change.

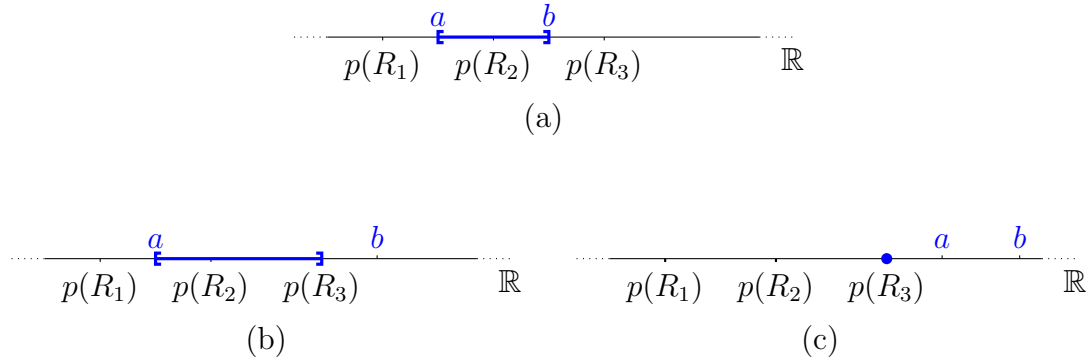


Figure 2.2: Let $N = \{1, 2, 3\}$ with $R \in \mathcal{R}^N$ and $p(R) = \{p(R_1), p(R_2), p(R_3)\}$. Let $F^{a,b} \in \mathcal{F}^N$. The chosen sets in each case are shown in bold. The target set in (a) is *efficient* and is chosen. The target set in (b) is not *efficient* but the maximal *efficient* subset exists and it is chosen. The target set in (c) is not *efficient* and no maximal *efficient* subset exists; hence the closest *efficient* point is chosen.

Remark 2.3 (Properties of fp-choice correspondences extend to choice correspondences). In Section 2.4, we introduce properties of fp-choice correspondences. Since a choice correspondence is a collection of fp-choice correspondences, these properties easily extend to choice correspondences. \square

2.4 Properties of choice correspondences

In the sequel, all properties and results refer to single-peaked preferences but also apply to symmetric single-peaked preferences.

We consider two solidarity properties of choice correspondences. The first solidarity property, expresses the solidarity among agents against changes in the population (Thomson, 1983b,a): if agents are added to the population, the agents

initially present should all be made at least as well off or they should all be made at most as well off by this change.

Population-monotonicity. *Let $F \in \mathcal{F}$ be a choice correspondence. For each pair $N, M \in \mathcal{P}$ such that $N \subseteq M$ and each $R \in \mathcal{R}^M$ the following holds:*

for each $i \in N$, $F(R_N) R_i F(R)$ or for each $i \in N$, $F(R) R_i F(R_N)$.

Population-monotonicity implies that the chosen sets, before and after the change in population, are *comparable*, and in the same way in terms of their welfare, by all agents present before and after this change.

The next lemma states that if a choice correspondence satisfies *efficiency* and *population-monotonicity*, then if agents are added to the population, all agents who were initially present are at most as well off.

Lemma 2.1 (Efficiency and population-monotonicity). *Let choice correspondence $F \in \mathcal{F}$ satisfy efficiency and population-monotonicity. Then, for each pair $N, M \in \mathcal{P}$ such that $N \subseteq M$, each $R \in \mathcal{R}^M$, and each $i \in N$, $F(R_N) R_i F(R)$. In particular, if $\text{Conv}(p(R_N)) = \text{Conv}(p(R))$, then $F(R_N) = F(R)$.*

Proof. Let choice correspondence $F \in \mathcal{F}$ satisfy *efficiency* and *population-monotonicity*. Let $N, M \in \mathcal{P}$ be such that $N \subseteq M$. Let $R \in \mathcal{R}^M$.

By *efficiency*, $F(R) \in \text{PE}(R)$ and $F(R_N) \in \text{PE}(R_N)$. By *population-monotonicity*, for each $i \in N$, $F(R) R_i F(R_N)$ or for each $i \in N$, $F(R_N) R_i F(R)$. If for each $i \in N$, $F(R) R_i F(R_N)$ and since $F(R_N) \in \text{PE}(R_N)$, then for each $i \in N$, $F(R_N) I_i F(R)$. Therefore, for each $i \in N$, $F(R_N) R_i F(R)$.

In particular, if $\text{Conv}(p(R_N)) = \text{Conv}(p(R))$, then by $F(R) \in \text{PE}(R)$ and Corollary 2.1, $F(R) \in \text{PE}(R_N)$. Since for each $i \in N$, $F(R_N) R_i F(R)$, and moreover $[F(R) \in \text{PE}(R_N) \text{ and } F(R_N) \in \text{PE}(R_N)]$, then for each $i \in N$, $F(R_N) I_i F(R)$. By Corollary 2.2, $\text{Conv}(F(R_N)) = \text{Conv}(F(R))$, and since we always represent any *efficient* set by its convex hull, $F(R_N) = F(R)$. \square

Proposition 2.2 ($F^{a,b}$ is population-monotonic). *Each target set correspondence satisfies population-monotonicity.*

Proof. Let $F^{a,b} \in \mathcal{F}$ be a target set correspondence. Let $N \in \mathcal{P}$ be such that $|N| \geq 2$ and $R \in \mathcal{R}^N$. We prove *population-monotonicity* of $F^{a,b}$ by showing that if $j \in N$ leaves all remaining agents end up at least as well off, i.e., for each $i \in N \setminus \{j\}$, $F^{a,b}(R_{-j}) R_i F^{a,b}(R)$.

Case 1. $\text{Conv}(p(R_{-j})) = \text{Conv}(p(R))$. Then, the chosen set remains the same, $F^{a,b}(R_{-j}) = F^{a,b}(R)$.

Case 2. $\text{Conv}(p(R_{-j})) \neq \text{Conv}(p(R))$. Then, j has either the unique smallest peak at R or the unique largest peak at R . By symmetry of arguments, assume that j has the unique smallest peak at R , $p(R_j) = \underline{p}(R)$. Then, $\underline{p}(R) < \underline{p}(R_{-j})$. There are 3 possibilities.

(i) $a, b < \underline{p}(R_{-j})$. Then, $F^{a,b}(R_{-j}) = \underline{p}(R_{-j})$. Furthermore, if $b \leq p(R_j)$, then $F^{a,b}(R) = p(R_j)$; if $a \leq p(R_j)$ and $b > p(R_j)$, then $F^{a,b}(R) = [p(R_j), b]$; and if $a > p(R_j)$, then $F^{a,b}(R) = [a, b]$. Hence, for each $i \in N \setminus \{j\}$, $b_{F^{a,b}(R_{-j})}(R_i) = w_{F^{a,b}(R_{-j})}(R_i) = \underline{p}(R_{-j})$, $b_{F^{a,b}(R)}(R_i) \in \{p(R_j), b\}$, and $w_{F^{a,b}(R)}(R_i) \in \{p(R_j), a\}$. Thus, for each $i \in N \setminus \{j\}$, $b_{F^{a,b}(R)}(R_i) < b_{F^{a,b}(R_{-j})}(R_i) \leq p(R_i)$ and $w_{F^{a,b}(R)}(R_i) < w_{F^{a,b}(R_{-j})}(R_i) \leq p(R_i)$. By single-peakedness, for each $i \in N \setminus \{j\}$, the best and worst points are improved. Hence, $F^{a,b}(R_{-j}) P_i F^{a,b}(R)$.

(ii) $a < \underline{p}(R_{-j})$ and $b \geq \underline{p}(R_{-j})$. Then, $\underline{F}^{a,b}(R) < \underline{F}^{a,b}(R_{-j}) = \underline{p}(R_{-j})$ and $\bar{F}^{a,b}(R) = \bar{F}^{a,b}(R_{-j})$. Thus, for each $i \in N \setminus \{j\}$, $\underline{F}^{a,b}(R) < \underline{F}^{a,b}(R_{-j}) \leq p(R_i)$. If $\bar{F}^{a,b}(R_{-j}) < p(R_i)$, then $b_{F^{a,b}(R)}(R_i) = b_{F^{a,b}(R_{-j})}(R_i) < p(R_i)$ and $w_{F^{a,b}(R)}(R_i) < w_{F^{a,b}(R_{-j})}(R_i) < p(R_i)$. Hence, by single-peakedness, i 's best point is at least as desirable and his worst point is improved. If $\bar{F}^{a,b}(R_{-j}) \geq p(R_i)$, then $b_{F^{a,b}(R)}(R_i) = b_{F^{a,b}(R_{-j})}(R_i) = p(R_i)$ and $w_{F^{a,b}(R)}(R_i) \in F^{a,b}(R_{-j}) \subseteq F^{a,b}(R)$. Thus, i 's best and worst points are at least as desirable. Hence, for each $i \in N \setminus \{j\}$, $F^{a,b}(R_{-j}) R_i F^{a,b}(R)$.

(iii) $a, b \geq \underline{p}(R_{-j})$. Then, the chosen set remains the same, $F^{a,b}(R_{-j}) = F^{a,b}(R)$. \square

The second solidarity property we consider expresses the solidarity among agents against changes in preferences (Moulin, 1987): if the preferences of an agent change, then the other agents should all be made at least as well off or they should all be made at most as well off. We formulate this requirement for fp-choice correspondences but as discussed in Remark 2.3, it easily extends to choice correspondences.

Replacement-dominance. *Let $N \in \mathcal{P}$ and $F \in \mathcal{F}^N$ be an fp-choice correspondence. For each $j \in N$, and each pair $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$ the following holds:*

for each $i \in N \setminus \{j\}$, $F(R) R_i F(\bar{R})$ or for each $i \in N \setminus \{j\}$, $F(\bar{R}) R_i F(R)$.

Replacement-dominance implies that the chosen sets, before and after the

change in preferences of some agent, are *comparable* by all other agents.

Note that for a population of one or two agents, *replacement-dominance* imposes no restriction on fp-choice correspondences. Hence, for each fixed population with one or two agents, each fp-target set correspondence satisfies *replacement-dominance*. However, if the fixed population contains at least three agents, then the target set must equal a point.

Proposition 2.3 ($F^{[a,b]}$ is replacement-dominant $\Leftrightarrow a = b$). *If a population consists of at least 3 agents, then an associated fp-target set correspondence satisfies replacement-dominance if and only if it is an fp-target point correspondence.*

Proof. Let $N \in \mathcal{P}$ be such that $|N| \geq 3$ and $F^{a,b} \in \mathcal{F}^N$ be an fp-target set correspondence.

First, if $a = b$, we prove *replacement-dominance* of f^a ($F^{a,b}$, $a = b$) by showing that for each pair $R, \bar{R} \in \mathcal{R}^N$ such that $\bar{R} \in \mathcal{R}^N$ and $R_{-j} = \bar{R}_{-j}$, [for each $i \in N \setminus \{j\}$, $f^a(R) R_i f^a(\bar{R})$] or [for each $i \in N \setminus \{j\}$, $f^a(\bar{R}) R_i f^a(R)$].

Case 1. $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. Then, the set (point) chosen remains the same, $f^a(\bar{R}) = f^a(R)$.

Case 2.1. $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Then, j has either the unique smallest peak at R or the unique largest peak at R . By symmetry of arguments, assume that $p(R_j) = \underline{p}(R)$. Then, $\underline{p}(R) < \underline{p}(\bar{R}) \leq \bar{p}(R) = \bar{p}(\bar{R})$. There are 2 possibilities.

(i) $a < \underline{p}(\bar{R})$. Then, $f^a(\bar{R}) = \{\underline{p}(\bar{R})\}$. Furthermore, if $a \leq \underline{p}(R)$, then $f^a(R) = \{\underline{p}(R)\}$ and if $a > \underline{p}(R)$, then $f^a(R) = \{a\}$. Hence, for each $i \in N \setminus \{j\}$, $f^a(R) < f^a(\bar{R}) \leq p(\bar{R}_i)$. Hence, by single-peakedness, for each $i \in N \setminus \{j\}$, $f^a(\bar{R}) P_i f^a(R)$.

(ii) $a \geq \underline{p}(\bar{R})$. Then, the set (point) chosen remains the same, $f^a(\bar{R}) = f^a(R)$.

Case 2.2. $\text{Conv}(p(\bar{R})) \supsetneq \text{Conv}(p(R))$. Then, by Case 2.1 (with the roles of R and \bar{R} reversed), for each $i \in N \setminus \{j\}$, $f^a(R) R_i f^a(\bar{R})$.

Case 3. $\text{Conv}(p(\bar{R})) \not\subseteq \text{Conv}(p(R))$ and $\text{Conv}(p(\bar{R})) \not\supseteq \text{Conv}(p(R))$. Then, j has either [the unique smallest peak at R and the unique largest peak at \bar{R}] or [the unique largest peak at R and the unique smallest peak at \bar{R}]. By symmetry of arguments, assume that $p(R_j) = \underline{p}(R)$ and $p(\bar{R}_j) = \bar{p}(\bar{R})$. Then, $\underline{p}(R) < \underline{p}(\bar{R}) \leq \bar{p}(R) < \bar{p}(\bar{R})$. There are 3 possibilities.

(i) $a < \underline{p}(\bar{R})$. Then, as shown in Case 2.1, for each $i \in N \setminus \{j\}$, $f^a(\bar{R}) P_i f^a(R)$.

(ii) $\underline{p}(\bar{R}) \leq a \leq \bar{p}(R)$. Then, the set (point) chosen remains the same, $f^a(\bar{R}) = f^a(R)$.

(iii) $a > \bar{p}(R)$. Then, $f^a(R) = \{\bar{p}(R)\}$. Furthermore, if $a \geq \bar{p}(\bar{R})$, then $f^a(\bar{R}) = \{\bar{p}(\bar{R})\}$ and if $a < \bar{p}(\bar{R})$, then $f^a(\bar{R}) = \{a\}$. Hence, for each $i \in N \setminus \{j\}$,

$p(\bar{R}_i) \leq f^a(R) < f^a(\bar{R})$. Hence, by single-peakedness, for each $i \in N \setminus \{j\}$, $f^a(R) P_i f^a(\bar{R})$.

Second, we prove that if $a < b$, then $F^{a,b}$ does not satisfy *replacement-dominance*. Without loss of generality, assume that $1, 2, 3 \in N$.

If $a = -\infty$, let $\bar{a} \in \mathbb{R}$ be such that $\bar{a} < b$, otherwise, let $\bar{a} = a$. If $b = \infty$, then let $\bar{b} \in \mathbb{R}$ be such that $\bar{b} > \bar{a}$, otherwise, let $\bar{b} = b$. Hence, $[\bar{a}, \bar{b}] \subseteq [a, b]$. We divide the interval $[\bar{a}, \bar{b}]$ into three equal parts and use the four points $a_1 = \bar{a}$, $a_2 = (\bar{a} + \frac{1}{3}(\bar{b} - \bar{a}))$, $a_3 = (\bar{a} + \frac{2}{3}(\bar{b} - \bar{a}))$, and $a_4 = \bar{b}$ to construct (symmetric) profiles $R, \bar{R} \in \mathcal{S}^N$ such that $p(R_1) = a_1$, $p(R_2) = p(\bar{R}_2) = a_2$, $p(R_3) = p(\bar{R}_3) = a_3$, $p(\bar{R}_1) = a_4$, and for each $i \in N \setminus \{1, 2, 3\}$, $p(R_i) = p(\bar{R}_i) = a_2$. Note that $R_{-1} = \bar{R}_{-1}$.

By the definition of $F^{a,b}$, we have $F^{a,b}(R) = [a_1, a_3]$ and $F^{a,b}(\bar{R}) = [a_2, a_4]$. Under both R and \bar{R} , the best points of agents 2 and 3 remain the same, $b_{F^{a,b}(R)}(R_2) = b_{F^{a,b}(\bar{R})}(R_2) = p(R_2)$ and $b_{F^{a,b}(R)}(R_3) = b_{F^{a,b}(\bar{R})}(R_3) = p(R_3)$. However, the worst points of agent 2 and 3 change as follows. For agent 2, $w_{F^{a,b}(R)}(R_2) = \{a_1, a_3\}$ and $w_{F^{a,b}(\bar{R})}(R_1) = \{a_4\}$. Since $p(R_2) = a_2 < a_3 < a_4$, single-peakedness implies $F^{a,b}(R) P_2 F^{a,b}(\bar{R})$. For agent 3, $w_{F^{a,b}(R)}(R_3) = \{a_1\}$ and $w_{F^{a,b}(\bar{R})}(R_3) = \{a_2, a_4\}$. Since $a_1 < a_2 < a_3 = p(R_3)$, single-peakedness implies $F^{a,b}(\bar{R}) P_3 F^{a,b}(R)$. This contradicts *replacement-dominance*. \square

We next introduce a property weaker than *replacement-dominance* in the sense that it does not require solidarity when the preferences of the agent with the unique smallest peak are changed such that he becomes the agent with the unique largest peak, or vice-versa; in other words, following a change in preferences of some agent, solidarity is required only if one side of the convex hull of the agents' peaks has remained the same. We formulate this requirement for fp-choice correspondences but as discussed in Remark 2.3, it easily extends to choice correspondences.

One-sided replacement-dominance. *Let $N \in \mathcal{P}$ and $F \in \mathcal{F}^N$ be an fp-choice correspondence. For each $j \in N$ and each pair $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(p(\bar{R}))$ or $\text{Conv}(p(R)) \supseteq \text{Conv}(p(\bar{R}))$ the following holds:*

for each $i \in N \setminus \{j\}$, $F(R) R_i F(\bar{R})$ or for each $i \in N \setminus \{j\}$, $F(\bar{R}) R_i F(R)$.

One-sided replacement-dominance implies that the chosen sets, before and after the change in preferences of some agent, are *comparable*, and in the same way in terms of their welfare, by all other agents. Moreover, *replacement-dominance* implies *one-sided replacement-dominance*.

The next lemma states that given a population of at least three agents and an associated fp-choice correspondence satisfying *efficiency* and *one-sided replacement-dominance*, if the preferences of an agent change in such a way that the new set of peaks is a subset of the initial one, all other agents end up at least as well off.

Lemma 2.2 (Efficiency and one-sided replacement-dominance). *Let $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy efficiency and one-sided replacement-dominance. Then, for each $j \in N$, each pair $R, \bar{R} \in \mathcal{R}^N$ such that $[R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$], and each $i \in N \setminus \{j\}$, $F(\bar{R}) R_i F(R)$. In particular, if $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$, then $F(\bar{R}) = F(R)$.*

We prove Lemma 2.2 in Appendix 2.B. Moreover, recall that for a population $N \in \mathcal{P}$ with one or two agents (*one-sided*) *replacement-dominance* imposes no restriction on an associated fp-choice correspondence. The following example illustrates why Lemma 2.2 does not hold for a population of two agents and an associated fp-choice correspondence.

Example 2.3. Let $N \in \mathcal{P}$ be such that $N = \{1, 2\}$ and $F \in \mathcal{F}^N$ be an fp-choice correspondence such that

$$F(R) = \begin{cases} p(R_2) & \text{if } p(R_2) = 1 \\ p(R_1) & \text{otherwise.} \end{cases}$$

Hence, F satisfies *efficiency*, and since $|N| = 2$, it trivially satisfies (*one-sided*) *replacement-dominance*. Let $R, \bar{R} \in \mathcal{R}^N$ be such that $p(R_1) = p(\bar{R}_1) = 0$, $p(R_2) = 2$, and $p(\bar{R}_2) = 1$. Hence, $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. It follows, that $F(R) = 0$ and $F(\bar{R}) = 1$. Hence, agent 1's peak $p(R_1) = F(R) < F(\bar{R})$. By single-peakedness, $F(R) P_1 F(\bar{R})$. \square

Proposition 2.4 ($F^{a,b}$ is one-sided replacement-dominant). *Each fp-target set correspondence satisfies one-sided replacement-dominance.*

Proof. Let $N \in \mathcal{P}$ and $F^{a,b} \in \mathcal{F}^N$ be an fp-target set correspondence. Since for $|N| \leq 2$, (*one-sided*) *replacement-dominance* imposes no restriction on fp-choice correspondence $F^{a,b}$, fix $|N| \geq 3$.

We prove that $F^{a,b}$ satisfies *one-sided replacement-dominance*, i.e., we show that for each $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(p(\bar{R}))$ or $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$, the following holds. For each $i \in N \setminus \{j\}$, $F^{a,b}(R) R_i F^{a,b}(\bar{R})$ or for each $i \in N \setminus \{j\}$, $F^{a,b}(\bar{R}) R_i F^{a,b}(R)$.

Case 1. $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. Then, the chosen set remains the same, $F^{a,b}(\bar{R}) = F^{a,b}(R)$.

Case 2.1. $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Then, j has either the unique smallest peak at R or the unique largest peak at R . By symmetry of arguments, assume that j has the unique smallest peak at R , $p(R_j) = \underline{p}(R)$. Then, $\underline{p}(R) < \underline{p}(\bar{R}) \leq \bar{p}(R) = \bar{p}(\bar{R})$. There are 3 possibilities.

(i) $a, b < \underline{p}(\bar{R})$. Then $F^{a,b}(\bar{R}) = \underline{p}(\bar{R})$. Furthermore, if $a, b \leq \underline{p}(R)$, then $F^{a,b}(R) = \underline{p}(R)$; if $a \leq \underline{p}(R)$ and $b > \underline{p}(R)$, then $F^{a,b}(R) = [\underline{p}(R), b]$; and if $a, b > \underline{p}(R)$, then $F^{a,b}(R) = [a, b]$. Hence, for each $i \in N \setminus \{j\}$, $b_{F^{a,b}(\bar{R})}(R_i) = w_{F^{a,b}(\bar{R})}(R_i) = \{p(\bar{R})\}$, $b_{F^{a,b}(R)}(R_i) \in \{\underline{p}(R), b\}$, and $w_{F^{a,b}(R)}(R_i) \in \{\underline{p}(R), a\}$. Thus, for each $i \in N \setminus \{j\}$, $b_{F^{a,b}(R)}(R_i) < b_{F^{a,b}(\bar{R})}(R_i) \leq p(R_i)$ and $w_{F^{a,b}(R)}(R_i) < w_{F^{a,b}(\bar{R})}(R_i) \leq p(R_i)$. By single-peakedness, for each $i \in N \setminus \{j\}$, best and worst points improve. Hence, $F^{a,b}(\bar{R}) P_i F^{a,b}(R)$.

(ii) $a < \underline{p}(\bar{R})$ and $b \geq \underline{p}(\bar{R})$. Then, for the minima $\underline{F}^{a,b}(R)$ and $\underline{F}^{a,b}(\bar{R})$ we have $\underline{F}^{a,b}(R) < \underline{F}^{a,b}(\bar{R}) = \underline{p}(\bar{R})$ and for the maxima $\bar{F}(R)$ and $\bar{F}(\bar{R})$ we have $\bar{F}(R) = \bar{F}(\bar{R})$. Thus, for each $i \in N \setminus \{j\}$, minimum $\underline{F}^{a,b}(R) < \underline{F}^{a,b}(\bar{R}) \leq p(R_i)$. If maximum $\bar{F}^{a,b}(\bar{R}) < p(R_i)$, then $b_{F^{a,b}(R)}(R_i) = b_{F^{a,b}(\bar{R})}(R_i) < p(R_i)$ and $w_{F^{a,b}(R)}(R_i) < w_{F^{a,b}(\bar{R})}(R_i) \leq p(R_i)$. Hence, by single-peakedness, i 's best point is at least as desirable and his worst point improves. If maximum $\bar{F}^{a,b}(\bar{R}) \geq p(R_i)$, then $b_{F^{a,b}(R)}(R_i) = b_{F^{a,b}(\bar{R})}(R_i) = p(R_i)$ and $w_{F^{a,b}(\bar{R})}(R_i) \in F^{a,b}(\bar{R}) \subseteq F^{a,b}(R)$. Thus, i 's best and worst points are at least as desirable. It follows, that for each $i \in N \setminus \{j\}$, $F^{a,b}(\bar{R}) R_i F^{a,b}(R)$.

(iii) $a, b \geq \underline{p}(\bar{R})$. Then, the set chosen remains the same, $F^{a,b}(\bar{R}) = F^{a,b}(R)$.

Case 2.2. $\text{Conv}(p(\bar{R})) \supsetneq \text{Conv}(p(R))$. Then, by Case 2.1 (with the roles of R and \bar{R} reversed), for each $i \in N \setminus \{j\}$, $F^{a,b}(R) R_i F^{a,b}(\bar{R})$. \square

The next proposition states an important relation between the two solidarity properties we study.

Proposition 2.5 (Efficiency and population-monotonicity \Rightarrow one-sided replacement-dominance). *Each choice correspondence satisfying efficiency and population-monotonicity also satisfies one-sided replacement-dominance.*

We prove Proposition 2.5 in Appendix 2.C.

Finally, although the property of *strategy-proofness*²² is not within the scope of this chapter, the following remark should be made.

²²An agent cannot affect the chosen set in his favor by misreporting his preferences (a formal definition in a slightly different context can be found on page 79).

Remark 2.4 (Strategy-proofness). Each (fp-)target set correspondence is (essentially) a *median correspondence* (defined on page 78). Specifically, an (fp-)target set correspondence with a target set $[a^N, b^N]$, at population N , is equivalent with a median correspondence $F^{\alpha, \beta}$, where $\alpha, \beta \in A^{|N|+1}$ such that $\alpha = \{-\infty, a^N, \dots, a^N, \infty\}$ and $\beta = \{-\infty, b^N, \dots, b^N, \infty\}$. Therefore, it follows from Theorems 3.4 and 3.6 that each (fp-)target set correspondence satisfies *strategy-proofness* in domains \mathcal{R} and \mathcal{S} respectively.

2.5 Characterizing target set correspondences

In the sequel, all results presented refer to single-peaked preferences but also apply to symmetric single-peaked preferences.

Our first theorem states that the properties of *efficiency* and *one-sided replacement-dominance* characterize fp-target set correspondences.

Theorem 2.1 (*F is efficient and one-sided replacement-dominant $\Leftrightarrow F = F^{a,b}$*). *If a fixed population consists of at least 3 agents, then an associated fp-choice correspondence satisfies efficiency and one-sided replacement-dominance if and only if it is an fp-target set correspondence.*

We prove Theorem 2.1 in Appendix 2.D. In addition, Corollary 2.3 that follows, strengthens a result for choice functions by Thomson (1993).

Corollary 2.3 (*F is efficient and replacement-dominant $\Leftrightarrow F = f^a$*). *If a fixed population consists of at least 3 agents, then an associated fp-choice correspondence satisfies efficiency and replacement-dominance if and only if it is an fp-target point correspondence.*

Proof. If part. By Propositions 2.1 and 2.3, all fp-target point correspondences satisfy *efficiency* and *replacement-dominance*.

Only if part. Let $N \in \mathcal{P}$ be such that $|N| \geq 3$ and let the fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *replacement-dominance*. Then, F satisfies *one-sided replacement-dominance* and by Theorem 2.1 it is an fp-target set correspondence $F^{a,b} \in \mathcal{F}^N$. By Proposition 2.3, $F^{a,b}$ satisfies *replacement-dominance* if and only if it is an fp-target point correspondence $f^a \in \mathcal{F}^N$. \square

We have formulated Theorem 2.1 and Corollary 2.3 for fp-choice correspondences where the fixed population contains at least 3 agents. If instead we consider choice correspondences, then *efficiency* and *one-sided replacement-dominance*

(*replacement-dominance*) imply that for each population with at least 3 agents, a different target set or target point can be chosen, while for each population with at most 2 agents, the choice correspondence can equal any *efficient* fp-choice correspondence.

Our second theorem states that the properties of *efficiency* and *population-monotonicity* characterize target set correspondences.

Theorem 2.2 (\mathbf{F} is efficient and population-monotonic $\Leftrightarrow \mathbf{F} = \mathbf{F}^{a,b}$). *A choice correspondence satisfies efficiency and population-monotonicity if and only if it is a target set correspondence.*

Proof. If part. By Propositions 2.1 and 2.2, all target set correspondences satisfy *efficiency* and *population-monotonicity*.

Only if part. Let choice correspondence $F \in \mathcal{F}$ satisfy *efficiency* and *population-monotonicity*. By Proposition 2.5, F satisfies *one-sided replacement-dominance*. Let $M \in \mathcal{P}$ be such that $|M| \geq 3$. By Theorem 2.1, for each $R \in \mathcal{R}^M$, $F = F^{a_M, b_M} \in \mathcal{F}^M$. Define points $a := a_M$ and $b := b_M$.

We show that for each $N \in \mathcal{P}$ and each $\bar{R} \in \mathcal{R}^N$, $F(\bar{R}) = F^{a,b}(\bar{R})$. We do so by showing that for each $N \in \mathcal{P}$, each $\bar{R} \in \mathcal{R}^N$, and each $R \in \mathcal{R}^M$, if $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$, then $F(\bar{R}) = F^{a,b}(R) = F^{a,b}(\bar{R})$ (the latter equality follows by the definition of $F^{a,b}$).

Let $R \in \mathcal{R}^M$ and $\bar{R} \in \mathcal{R}^N$. Recall that $F(R) = F^{a,b}(R)$. Begin from $R \in \mathcal{R}^M$ and construct $R^1 \in \mathcal{R}^{M \cup N}$ by adding the population $N \setminus M$ with profile $\bar{R}_{N \setminus M}$, i.e., $R^1 = (R, \bar{R}_{N \setminus M})$. Since $\text{Conv}(R^1) = \text{Conv}(p(R))$, by *population-monotonicity* and Lemma 2.1, $F(R^1) = F(R)$. Next, change the preferences of each $i \in N$ to \bar{R}_i and denote the new profile $R^2 = (R_{M \setminus N}^1, \bar{R}) \in \mathcal{R}^{M \cup N}$. Since $\text{Conv}(R^2) = \text{Conv}(R^1)$, by *population-monotonicity* and Lemma 2.1, $F(R^2) = F(R^1)$. Finally, remove the population $M \setminus N$ and notice that the new profile $R_N^2 = \bar{R} \in \mathcal{R}^N$. Since $\text{Conv}(p(\bar{R})) = \text{Conv}(R^2)$, by *population-monotonicity* and Lemma 2.1, $F(\bar{R}) = F(R^2)$. Hence, $F(\bar{R}) = F^{a,b}(R) = F^{a,b}(\bar{R})$. \square

All the properties we consider are independent.

Remark 2.5 (Independence of properties). Note that the properties in all our characterization results are independent. A constant choice correspondence that always chooses a fixed set satisfies (*one-sided*) *replacement-dominance* and *population-monotonicity* but violates *efficiency*. A choice correspondence that always chooses the peak of the agent with the lowest index satisfies *efficiency*, but it violates *one-sided replacement-dominance* and *population-monotonicity*. \square

Finally, we comment on the validity of our results for some natural model variations.

Remark 2.6 (Chosen sets are not necessarily compact). Although we only study compact subsets of \mathbb{R} , the compactness requirement is without loss of generality for the following reasons. First, the agents' peaks being real numbers and Proposition 2.1 (i) imply that unbounded sets are not *efficient*. Hence, by Theorems 2.1 and 2.2, the two classes of correspondences we characterize satisfy *efficiency* and therefore only select bounded sets. Second, concerning open (and bounded) sets, after assuming that each agent is indifferent between a set and its *closure*,²³ all our results hold and the target sets of target set correspondences and fp-target set correspondences can be open. Notice that in this case, the second requirement for the *efficiency* of a set, that is, Proposition 2.1 (ii), must change slightly to $\text{Conv}(\text{closure}(X)) \cap p(R) \subseteq \text{closure}(X)$; moreover, to accommodate for the possible openness of sets, throughout the text and for each set X , references to $\text{Conv}(X)$ must be substituted with $\text{Conv}(\text{closure}(X))$. \square

Remark 2.7 (Monotonic preferences). Allowing for agents to have monotonic preferences, i.e., have minus infinity or plus infinity as peaks, poses the following problem. If all agents have minus infinity or all agents have plus infinity as their peak, then by Proposition 2.1, no *efficient* set exists in \mathcal{C} . Moreover, if unbounded sets of \mathbb{R} are considered, then in this case the only *efficient* sets are $\{-\infty\}$ (when all agents have minus infinity as their peak) and $\{+\infty\}$ (when all agents have plus infinity as their peak). However, a policy interpretation for these two sets, as well as other unbounded sets, is not clear and we therefore do not add monotonic preferences to our model. \square

Remark 2.8 (Closed interval alternative set). All our results hold if the preferences of the agents are defined on some closed interval $[a, b] \subsetneq \mathbb{R}$. In this case and since *efficiency* is required, by Proposition 2.1 (i), the class of sets considered equals the class of non-empty subsets of $[a, b]$ and closedness is not required (see Remark 2.6). Moreover, agents can have monotonic preferences, i.e., have a or b as peaks, since the policy interpretation of “locating the public good at a ” or “locating the public good at b ” is straightforward, in contrast to our original model (see Remark 2.7). Finally, it should be mentioned that this restriction on the set of alternatives facilitates our main proof (Theorem 2.1) as follows. Since a profile with a as the minimum peak and b as the maximum peak can be chosen

²³Given $X \subsetneq \mathbb{R}$, the *closure* of X , $\text{closure}(X)$, is defined as the union of X with all its limit / boundary points.

(in contrast to our original model, where a profile with $-\infty$ as the minimum peak and $+\infty$ as the maximum peak is not available), the proof essentially follows from Lemma 2.11. \square

Throughout the Appendices we use the domain of single-peaked preferences \mathcal{R} , with the exception of Lemma 2.9 (Appendix 2.D), where we use the domain of symmetric single-peaked preferences \mathcal{S} . All results proven for \mathcal{R} also hold on \mathcal{S} ; however, for Lemma 2.9, the proof for \mathcal{S} requires a different approach (and additional “proof steps”) that also holds on \mathcal{R} .

2.A Proofs of Proposition 2.1 and Corollary 2.2

The following terms describe a set obtained by a truncation of a given set $X \in \mathcal{C}$ on one side at a specific point x , which is added to the new set to ensure that this new set is closed.

Left truncaddition (of a set at a point). Let point $x \in \mathbb{R}$ and set $X \in \mathcal{C}$. Then, set $Y \in \mathcal{C}$ is a *left truncaddition* of X at x if $Y = [X \cap (x, \infty)] \cup \{x\}$.

Right truncaddition (of a set at a point). Let point $x \in \mathbb{R}$ and set $X \in \mathcal{C}$. Then, set $Y \in \mathcal{C}$ is a *right truncaddition* of X at x if $Y = [X \cap (-\infty, x)] \cup \{x\}$.

Before proceeding with the proof of Proposition 2.1 we present two lemmas. First, we describe some cases where a truncaddition of a set at a point makes an agent weakly better off.

Lemma 2.3 (Truncadditions). *Let agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ and set $X \in \mathcal{C}$.*

(i) *Let minimum $\underline{X} < p(R_i)$, point $\underline{x} \in \mathbb{R}$ such that $\underline{X} < \underline{x} \leq p(R_i)$, and set $Y = [X \cap (\underline{x}, \infty)] \cup \{\underline{x}\}$ be a left truncaddition of set X at point \underline{x} . Then, $Y R_i X$. Moreover, if the unique worst point $w_X(R_i) = \underline{X}$, then $Y P_i X$.*

(ii) *Let maximum $\bar{X} > p(R_i)$, point $\bar{x} \in \mathbb{R}$ be such that $\bar{X} > \bar{x} \geq p(R_i)$, and set $Y = [X \cap (-\infty, \bar{x})] \cup \{\bar{x}\}$ be a right truncaddition of set X at point \bar{x} . Then, $Y R_i X$. Moreover, if the unique worst point $w_X(R_i) = \bar{X}$, then $Y P_i X$.*

(iii) *Let minimum $\underline{X} < p(R_i)$, maximum $\bar{X} > p(R_i)$, and points $\underline{x}, \bar{x} \in \mathbb{R}$ be such that $\underline{X} < \underline{x} \leq p(R_i) \leq \bar{x} < \bar{X}$, set $Y = [X \cap (\underline{x}, \infty)] \cup \{\underline{x}\}$ be a left truncaddition of set X at point \underline{x} , and set $Z = [Y \cap (-\infty, \bar{x})] \cup \{\bar{x}\}$ be a right truncaddition of set Y at point \bar{x} . Then, $Z P_i X$.*

Proof. Let agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ and set $X \in \mathcal{C}$.

(i) Let minimum $\underline{X} < p(R_i)$, point $\underline{x} \in \mathbb{R}$ such that $\underline{X} < \underline{x} \leq p(R_i)$, truncaddition $Y = [X \cap (\underline{x}, \infty)] \cup \{\underline{x}\}$, and Z be the set of truncated points, $Z = X \setminus Y$.

By single-peakedness, for each $z \in Z$, agent i prefers \underline{x} to z , $\underline{x} P_i z$. Hence, his best and worst points in Y are at least as desirable as his (respective) best and worst points in X . It follows, that $Y R_i X$. If additionally his worst point $w_X(R_i) = \bar{X} \notin Y$ is unique, then $\bar{X} P_i w_X(R_i)$ and $\underline{x} P_i w_X(R_i)$. Since by single-peakedness, $w_Y(R_i) \subseteq \{\underline{x}, \bar{X}\}$, it follows that $Y P_i X$.

(ii) Symmetric proof to (i).

(iii) Let minimum $\underline{X} < p(R_i)$, maximum $\bar{X} > p(R_i)$, points $\underline{x}, \bar{x} \in \mathbb{R}$ be such that $\underline{X} < \underline{x} \leq p(R_i) \leq \bar{x} < \bar{X}$, truncaddition $Y = [X \cap (\underline{x}, \infty)] \cup \{\underline{x}\}$, and truncaddition $Z = [Y \cap (-\infty, \bar{x}]] \cup \{\bar{x}\}$. By part (i), $Y R_i X$. By part (ii), $Z R_i Y$. Hence, by transitivity, $Z R_i X$. Moreover, by single-peakedness, his worst point(s) $w_X(R_i) \subseteq \{\underline{X}, \bar{X}\}$ and $w_Z(R_i) \subseteq \{\underline{x}, \bar{x}\}$. Since by single-peakedness $\underline{x} P_i w_X(R_i)$ and $\bar{x} P_i w_X(R_i)$, his worst point(s) improves. It follows that $Z P_i X$. \square

Second, adding a closed interval to a set, without changing its convex hull, makes an agent indifferent, unless his best point improves, in which case he is better off. Furthermore, removing an open interval from a set, without changing its convex hull, makes an agent indifferent, unless his best point worsens, in which case he is worse off.

Lemma 2.4. *Let agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ and set $X \in \mathcal{C}$.*

(i) *Let closed interval $[x, y] \subseteq \text{Conv}(X)$ and set $Y = X \cup [x, y]$. Then, $Y I_i X$ unless agent i 's best point(s) improves, i.e., $b_Y(R_i) P_i b_X(R_i)$, in which case, $Y P_i X$.*

(ii) *Let open interval $(x, y) \subsetneq \text{Conv}(X)$ and set $Y = X \setminus (x, y)$. Then, $X I_i Y$ unless agent i 's best point(s) worsens, i.e., $b_X(R_i) P_i b_Y(R_i)$, in which case, $X P_i Y$.*

Proof. Let agent $i \in \mathbb{P}$ with preferences $R_i \in \mathcal{R}$ and set $Y \in \mathcal{C}$.

(i) Let $[x, y] \subseteq \text{Conv}(X)$ and $Y = X \cup [x, y]$. By single-peakedness, agent i 's worst point(s) does not change, $w_X(R_i) = w_Y(R_i) \subseteq \{\underline{X}, \bar{X}\}$. If for his best point(s) we have $b_X(R_i) I_i b_Y(R_i)$, then $b_X(R_i) \subseteq b_Y(R_i)$ and $Y I_i X$. Otherwise, $b_X(R_i) \not\subseteq b_Y(R_i)$, his best point(s) improves, $b_Y(R_i) P_i b_X(R_i)$, and $Y P_i X$.

(ii) Let $(x, y) \subsetneq \text{Conv}(X)$ and $Y = X \setminus (x, y)$. By single-peakedness, agent i 's worst point(s) does not change, $w_X(R_i) = w_Y(R_i) \subseteq \{\underline{X}, \bar{X}\}$. If for his best point(s) we have $b_X(R_i) I_i b_Y(R_i)$, then $b_X(R_i) \supseteq b_Y(R_i)$ and $Y I_i X$. Otherwise, $b_X(R_i) \not\supseteq b_Y(R_i)$, his best point(s) worsens, $b_X(R_i) P_i b_Y(R_i)$, and $X P_i Y$. \square

Proof of Proposition 2.1. Let population $N \in \mathcal{P}$, profile $R \in \mathcal{R}^N$, and set $X \in \mathcal{C}$. Without loss of generality, assume that $N = \{1, \dots, n\}$ and $\underline{p}(R) = p(R_1) \leq \dots \leq p(R_n) = \bar{p}(R)$. The proof follows in three steps.

Step 1. We show that if set $X \in \text{PE}(R)$ then condition (i) holds, that is, $X \subseteq \text{Conv}(p(R))$.

Let set $X \in \text{PE}(R)$. Assume by contradiction that $X \not\subseteq \text{Conv}(p(R))$. Then, minimum $\underline{X} < p(R_1)$ or maximum $\bar{X} > p(R_n)$. By symmetry of arguments, assume that $\underline{X} < p(R_1)$.

Case 1. Let maximum $\bar{X} > p(R_n)$. Then, for each $i \in N$, minimum $\underline{X} < p(R_1) \leq p(R_i) \leq p(R_n) < \bar{X}$. Let $Y = [X \cap (p(R_1), \infty)] \cup \{p(R_1)\}$ be a left truncaddition of X at $p(R_1)$, and $Z = [Y \cap (-\infty, p(R_n))] \cup \{p(R_n)\}$ be a right truncaddition of Y at $p(R_n)$. Therefore, by Lemma 2.3 (iii), for each $i \in N$, $Z P_i X$. Hence, $X \notin \text{PE}(R)$; a contradiction.

Case 2. Let maximum $\bar{X} \leq p(R_n)$. Then, for each $i \in N$, minimum $\underline{X} < p(R_1) \leq p(R_i)$. Let $Y = [X \cap (p(R_1), \infty)] \cup \{p(R_1)\}$ be a left truncaddition of X at $p(R_1)$. By Lemma 2.3 (i), for each $i \in N$, $Y R_i X$. Furthermore, agent n 's worst point $w_X(R_n) = \underline{X}$ is unique. Therefore, by Lemma 2.3 (i), $Y P_n X$. Hence, $X \notin \text{PE}(R)$; a contradiction.

Step 2. We show that if set $X \in \text{PE}(R)$ then condition (ii) holds, that is, $(\text{Conv}(X) \cap p(R)) \subseteq X$.

Let set $X \in \text{PE}(R)$. By Step 1, $X \subseteq \text{Conv}(p(R))$. Assume by contradiction that $(\text{Conv}(X) \cap p(R)) \not\subseteq X$. Then, there exists agent $j \in N$ such that $p(R_j) \in \text{Conv}(X)$ and $p(R_j) \notin X$.

Let set $Y = X \cup \{p(R_j)\}$. By Lemma 2.4 (i), for each $i \in N$, $Y R_i X$. Furthermore, agent j 's best point $b_Y(R_j) = p(R_j) P_j b_X(R_j)$. Therefore, by Lemma 2.4 (i), $Y P_j X$. Hence, $X \notin \text{PE}(R)$; a contradiction.

Step 3. We show that if conditions (i) and (ii) hold for set $X \in \mathcal{C}$, then $X \in \text{PE}(R)$.

Let set $X \in \mathcal{C}$ be such that $X \subseteq \text{Conv}(p(R))$ and $(\text{Conv}(X) \cap p(R)) \subseteq X$. Assume by contradiction that $X \notin \text{PE}(R)$. Hence, there exists a set $Y \subseteq \mathbb{R}$ that *dominates* set X , i.e., for each agent $i \in N$, $Y R_i X$, and for at least one agent $j \in N$, $Y P_j X$.

Case 1. Let agent j 's peak $p(R_j) \in \text{Conv}(X)$. By condition (ii), $p(R_j) \in X$. Agent j 's best point $b_X(R_j) = p(R_j) \in X$ cannot be improved. By single-peakedness, agent j 's worst point(s) $w_X(R_j) \subseteq \{\underline{X}, \bar{X}\}$; if his worst point(s) $w_Y(R_j) P_j w_X(R_j)$, by single-peakedness, minimum $\underline{X} < \underline{Y}$ or maximum $\bar{X} > \bar{Y}$. By symmetry of arguments, assume minimum $\underline{X} < \underline{Y}$. Consider agent 1; by condition (i), his peak $p(R_1) \leq \underline{X} < \underline{Y}$. By single-peakedness, his best point $b_X(R_1) P_1 b_Y(R_1)$. It follows that for agent 1 set Y is not at least as desirable as set X . Hence, set Y does not *dominate* set X ; a contradiction.

Case 2. Let agent j 's peak $p(R_j) \notin \text{Conv}(X)$. Then, either $p(R_j) < \underline{X}$ or $p(R_j) > \bar{X}$. By symmetry of arguments, assume that $p(R_j) > \bar{X}$. By single-peakedness, agent j 's best point $b_X(R_j) = \bar{X}$ and agent j 's worst point $w_X(R_j) = \underline{X}$. If his best point(s) $b_Y(R_j) P_j b_X(R_j)$, by single-peakedness, maximum $\bar{X} < \bar{Y}$. If his worst point(s) $w_Y(R_j) P_j w_X(R_j)$, by single-peakedness, minimum $\underline{X} < \underline{Y}$. Consider now agent 1. By condition (i), his peak $p(R_1) \leq \underline{X} \leq \bar{X}$. By single-peakedness, his best and worst point(s) are $b_X(R_1) = \underline{X}$ and $w_X(R_1) = \bar{X}$. If minimum $\underline{X} < \underline{Y}$, by single-peakedness, $b_X(R_1) P_1 b_Y(R_1)$. If maximum $\bar{X} < \bar{Y}$, by single-peakedness, $w_X(R_1) P_1 w_Y(R_1)$. It follows that for agent 1 set Y is not at least as desirable as set X . Hence, set Y does not *dominate* set X ; a contradiction. \square

Proof of Corollary 2.2. Let population $N \in \mathcal{P}$, profile $R \in \mathcal{R}^N$, and set $X \in \text{PE}(R)$.

First, we show that $\text{Conv}(X)$ and X are *equivalent* sets. By single-peakedness, for each agent $i \in N$ such that $p(R_i) \in \text{Conv}(X)$, the best point $b_{\text{Conv}(X)}(R_i) = p(R_i)$ and by Proposition 2.1 (ii), $(\text{Conv}(X) \cap p(R)) \subseteq X$. Hence, the best point $b_{\text{Conv}(X)}(R_i) = b_X(R_i)$. By single-peakedness, for each agent $i \in N$ such that $p(R_i) \notin \text{Conv}(X)$, the best point $b_{\text{Conv}(X)}(R_i) \in \{\underline{X}, \bar{X}\}$. Since $\{\underline{X}, \bar{X}\} \subseteq X$, the best point $b_{\text{Conv}(X)}(R_i) = b_X(R_i)$. Moreover, since $\text{Conv}(X)$ is a closed interval and (trivially) $\text{Conv}(X) = X \cup \text{Conv}(X)$, by Lemma 2.4 (i), for each agent $i \in N$, $\text{Conv}(X) I_i X$.

Second, we show that if X and Y are *equivalent* sets, then $\text{Conv}(X) = \text{Conv}(Y)$. Let $Y \in \mathcal{C}$ be an equivalent set to $X \in \text{PE}(R)$. Let agent $1 \in N$ have the smallest peak at profile R , $p(R_1) = \underline{p}(R)$. By Proposition 2.1 (i), $X, Y \subseteq \text{Conv}(p(R))$, hence, $p(R_1) \leq \underline{X} \leq \bar{X}$ and $p(R_1) \leq \underline{Y} \leq \bar{Y}$. By single-peakedness, for agent 1, [best points are $b_X(R_1) = \underline{X}$ and $b_Y(R_1) = \underline{Y}$] and [worst points are $w_X(R_1) = \bar{X}$ and $w_Y(R_1) = \bar{Y}$]. Since $X I_1 Y$, $b_X(R_1) = b_Y(R_1)$ and $w_X(R_1) = w_Y(R_1)$. Therefore, $\text{Conv}(X) = \text{Conv}(Y)$. \square

2.B Proof of Lemma 2.2

Before proceeding with the proof of Lemma 2.2, we first prove an implication of *efficiency* and (*one-sided*) *replacement-dominance*.

An fp-choice correspondence satisfies *extreme-peaks-onliness* if the chosen set only depends on the convex hull of the peaks of the profile. We formulate *extreme-*

peaks-onliness for fp-choice correspondences but as discussed in Remark 2.3, it easily extends to choice correspondences.

Extreme-peaks-onliness. *Let fixed population $N \in \mathcal{P}$ and fp-choice correspondence $F \in \mathcal{F}^N$. For each pair of profiles $R, \bar{R} \in \mathcal{R}^N$, if $\text{Conv}(p(R)) = \text{Conv}(p(\bar{R}))$, then $F(R) = F(\bar{R})$.*

Notice that *extreme-peaks-onliness* not only implies the properties of *anonymity*²⁴ and *peaks-onliness*,²⁵ but since it only depends on the extreme agents' peaks, it is a much stronger property.

Lemma 2.5 (Efficiency and one-sided replacement-dominance \Rightarrow extreme-peaks-onliness). *If a fixed population consists of at least 3 agents, then each associated fp-choice correspondence satisfying efficiency and one-sided replacement-dominance also satisfies extreme-peaks-onliness.*

Proof. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy efficiency and one-sided replacement-dominance. Let the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $\text{Conv}(p(R)) = \text{Conv}(p(\bar{R}))$. Without loss of generality, assume that $N = \{1, 2, \dots, n\}$ and $\underline{p}(R) = p(R_1) \leq p(R_2) \leq \dots \leq p(R_n) = \bar{p}(R)$. In the following, we refer to agents who have neither the unique smallest peak nor the unique largest peak as *middle agents*.

We prove that $F(R) = F(\bar{R})$ in three steps.

Step 1. We show that if the preferences of one agent change and the convex hull of the peaks does not change, the chosen set does not change.

Case 1.1. The preferences of a middle agent at profile R change such that the convex hull of the peaks does not change. Let agent $k \in N$ be a middle agent at profile R and let profile $\bar{R} \in \mathcal{R}^N$ be such that $\bar{R}_{-k} = R_{-k}$, and $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. Notice that agent k is also a middle agent at profile \bar{R} .²⁶

By efficiency, $F(\bar{R}) \in PE(\bar{R})$ and $F(R) \in PE(R)$. Since agent k is a middle agent at both profiles R and \bar{R} , $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R)) = \text{Conv}(p(R_{-k}))$, and by Corollary 2.1, $F(\bar{R}), F(R) \in PE(R_{-k})$. Since $\bar{R}_{-k} = R_{-k}$, by one-sided replacement-dominance, for each agent $i \in N \setminus \{k\}$, $F(\bar{R}) R_i F(R)$ or for each agent $i \in N \setminus \{k\}$, $F(R) R_i F(\bar{R})$. By efficiency of both sets $F(R)$ and $F(\bar{R})$ at profile R_{-k} , for each agent $i \in N \setminus \{k\}$, $F(R) I_i F(\bar{R})$. By Corollary 2.2,

²⁴*Anonymity*: the identities of the agents do not affect the chosen set.

²⁵*Peaks-Onliness*: only the peaks of the agents affect the chosen set.

²⁶Note that if agent 1 (agent n) does not have the unique smallest (largest) peak, then he is a middle agent.

$\text{Conv}(F(\bar{R})) = \text{Conv}(F(R))$ and since we always represent any *efficient* set by its convex hull, $F(\bar{R}) = F(R)$.

Case 1.2. Either the preferences of the agent with the unique smallest peak at profiles R and \bar{R} change (agent 1), or the preferences of the agent with the unique largest peak at profiles R and \bar{R} change (agent n), such that the convex hull of the peaks does not change. By symmetry of arguments, assume that profile \bar{R} is such that $\bar{R}_{-1} = R_{-1}$ and $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. Hence, $p(\bar{R}_1) = p(R_1) < p(R_2) \leq \dots \leq p(R_n)$.

Begin from profile R and construct profile R^1 by changing middle agent 2's preferences to $R_2^1 = R_1$, i.e., $R^1 = (R_{-2}, R_2^1)$ where $\text{Conv}(R^1) = \text{Conv}(p(R))$. By Case 1.1, $F(R^1) = F(R)$. Next, change middle agent 1's preferences to $R_1^2 = \bar{R}_1$ such that the new profile is $R^2 = (R_{-1}^2, R_1^2)$ where $\text{Conv}(R^2) = \text{Conv}(R^1)$. By Case 1.1, $F(R^2) = F(R^1)$. Finally, change middle agent 2's preferences back to R_2 and notice that the new profile $(R_{-2}^2, R_2) = \bar{R}$ where $\text{Conv}(p(\bar{R})) = \text{Conv}(R^2)$. By Case 1.1, $F(\bar{R}) = F(R^2)$. Therefore, $F(\bar{R}) = F(R)$.

Step 2. We show that if two agents swap preferences, then the chosen set does not change.

Case 2.1. At least one of the swapping agents is a middle agent at profile R . Assume profile \bar{R} is obtained from profile R by agents $j, k \in N$ swapping preferences, i.e., $\bar{R}_{-j,k} = R_{-j,k}$, $\bar{R}_j = R_k$, and $\bar{R}_k = R_j$. Let agent $k \in N$ be a middle agent at profile R . Begin from profile R and construct profile R^1 by changing agent k 's preferences to $R_k^1 = R_j$, i.e., $R^1 = (R_{-k}, R_k^1)$ where $\text{Conv}(R^1) = \text{Conv}(p(R))$. By Case 1.1, $F(R^1) = F(R)$. Finally, change agent j 's preferences to $R_j^2 = R_k$ and notice that the new profile $(R_{-j}^2, R_j^2) = \bar{R}$ where $\text{Conv}(p(\bar{R})) = \text{Conv}(R^1)$. By Case 1.1, $F(\bar{R}) = F(R^1)$. Therefore, $F(\bar{R}) = F(R)$.

Case 2.2. None of the swapping agents is a middle agent at profile R . Hence, $p(R_1) < p(R_2) \leq \dots < p(R_n)$. Note that in this case, $\bar{R} \in \mathcal{R}^N$ is such that $\bar{R}_{-1,n} = R_{-1,n}$, $\bar{R}_1 = R_n$, and $\bar{R}_n = R_1$. Begin from profile R and construct profile R^1 by swapping middle agent 2's preferences with agent 1's preferences, denoting the new profile by R^1 . By Case 2.1, $F(R^1) = F(R)$. Next, swap middle agent 1's preferences with agent n 's preferences, denoting the new profile by R^2 . By Case 2.1, $F(R^2) = F(R^1)$. Finally, swap middle agent n 's preferences with agent 2's preferences and notice that the new profile is \bar{R} . By Case 2.1, $F(\bar{R}) = F(R^2)$. Therefore, $F(\bar{R}) = F(R)$.

Step 3. We show how each profile \bar{R} , where $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$, can be constructed from profile R by sequentially repeating the first two steps of the proof. Let profile \bar{R} be such that $\bar{R} = (\bar{R}_1, \dots, \bar{R}_n)$ and, without loss of generality,

assume $p(\bar{R}) = p(\bar{R}_1) \leq \dots \leq p(\bar{R}_n) = \bar{p}(\bar{R})$. Notice that set $\{\bar{1}, \dots, \bar{n}\}$ is a permutation of set $N = \{1, \dots, n\}$.

Begin from profile R and construct profile R^1 by sequentially replacing each agent's preferences R_i with \bar{R}_i , i.e., for each $i \in N$, $R_i^1 = \bar{R}_i$. Note that the stepwise change of agents' preferences never changes the convex hull of peaks and that $\text{Conv}(R^1) = \text{Conv}(p(R))$. By Step 1, $F(R^1) = F(R)$. Finally, permute the agents' preferences such that each agent \bar{i} obtains the preferences of agent i , i.e., the new profile R^2 is such that for each $i \in N$, $R_i^2 = R_i^1$. Hence, for each $i \in N$, $R_i^2 = \bar{R}_i$ and $R^2 = \bar{R}$. Since all permutations can be obtained via sequential pairwise swaps, by Step 2, $F(\bar{R}) = F(R)$. \square

We use Lemma 2.5 in the proof of Lemma 2.2.

Proof of Lemma 2.2. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *one-sided replacement-dominance*. By Lemma 2.5, F satisfies *extreme-peaks-onliness*. Let agent $j \in N$ and the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $R_{-j} = \bar{R}_{-j}$.

We show that if $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$, then all remaining agents end up at least as well off, i.e., for each $i \in N \setminus \{j\}$, $F(\bar{R}) R_i F(R)$. Without loss of generality, assume that $N = \{1, 2, \dots, n\}$ and $p(R) = p(R_1) \leq p(R_2) \leq \dots \leq p(R_n) = \bar{p}(R)$. In the following, we refer to agents who have neither the unique smallest peak nor the unique largest peak as *middle agents*.

Case 1. Let $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. By *extreme-peaks-onliness*, $F(\bar{R}) = F(R)$.

Case 2. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, at profile R , either agent $j = 1$ has the unique smallest peak or agent $j = n$ has the unique largest peak. By symmetry of arguments, assume that $j = 1$ has the unique smallest peak and profile \bar{R} is such that $\bar{R}_{-1} = R_{-1}$.

Case 2.1. Agent 1 is a middle agent at profile \bar{R} . Then, $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R_{-1}))$. By *efficiency*, $F(\bar{R}) \in PE(\bar{R})$ and $F(R) \in PE(R)$. By Corollary 2.1, $F(\bar{R}) \in PE(R_{-1})$.

Assume that $F(R) \subseteq \text{Conv}(p(R_{-1}))$. Since $F(R) \in PE(R)$, by Proposition 2.1 (ii), $\text{Conv}(F(R)) \cap p(R) \subseteq F(R)$. Hence, $\text{Conv}(F(R)) \cap p(R_{-1}) \subseteq F(R)$ and by Proposition 2.1, $F(R) \in PE(R_{-1})$. Since $\bar{R}_{-1} = R_{-1}$ and $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$, by *one-sided replacement-dominance*, for each agent $i \in N \setminus \{1\}$, $F(\bar{R}) R_i F(R)$ or for each agent $i \in N \setminus \{1\}$, $F(R) R_i F(\bar{R})$. By *efficiency* of both sets $F(R)$ and $F(\bar{R})$ at profile R_{-1} , for each agent $i \in N \setminus \{1\}$, $F(R) I_i F(\bar{R})$.

By Corollary 2.2, $\text{Conv}(F(\bar{R})) = \text{Conv}(F(R))$, and since we always represent any *efficient* set by its convex hull, $F(\bar{R}) = F(R)$.

Assume that $F(R) \not\subseteq \text{Conv}(p(R_{-1}))$. Then, minimum $\underline{F}(R) < \underline{p}(R_{-1}) \leq \underline{F}(\bar{R}) \leq \underline{p}(R_n)$. Hence, agent n 's worst points are $w_{F(R)}(R_n) = \{\underline{F}(R)\}$ and $w_{F(\bar{R})}(R_n) = \{\underline{F}(\bar{R})\}$. By single-peakedness, $w_{F(\bar{R})}(R_n) P_n w_{F(R)}(R_n)$. By *one-sided replacement-dominance*, agent n is better off, $F(\bar{R}) P_n F(R)$. Hence, by *one-sided replacement-dominance*, for each agent $i \in N \setminus \{1\}$, $F(\bar{R}) R_i F(R)$.

Case 2.2. Recall that $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ and that agent 1 has the unique smallest peak at profile R . In addition, let agent 1 also have the unique smallest peak at profile \bar{R} . Then, $\text{Conv}(p(R_{-1})) \subsetneq \text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, $p(R_1) < p(\bar{R}_1) < p(R_2) \leq \dots \leq p(R_n)$.

Begin from profile R and construct profile R^1 by changing middle agent 2's preferences to $R_2^1 = \bar{R}_1$, i.e., $R^1 = (R_{-2}, R_2^1)$. Since $\text{Conv}(R^1) = \text{Conv}(p(R))$, by *extreme-peaks-onliness*, $F(R^1) = F(R)$. Next, change agent 1's preferences to $R_1^2 = \bar{R}_1$ such that the new profile is $R^2 = (R_{-1}^1, R_1^2)$. Since agent 1 has the unique smallest peak at profile R^1 and is a middle agent at profile R^2 , by Case 2.1, for each agent $i \in N \setminus \{1, 2\}$, $F(R^2) R_i F(R^1)$. Finally, change middle agent 2's preferences back to R_2 and notice that the new profile $(R_{-2}^2, R_2) = \bar{R}$. Since $\text{Conv}(p(\bar{R})) = \text{Conv}(R^2)$, by *extreme-peaks-onliness*, $F(\bar{R}) = F(R^2)$. Therefore, for each agent $i \in N \setminus \{1, 2\}$, $F(\bar{R}) R_i F(R)$. In particular, $F(\bar{R}) R_n F(R)$. Since agent n has the largest peak, *efficiency* and single-peakedness imply $\underline{F}(R) \leq \underline{F}(\bar{R})$ and $\bar{F}(R) \leq \bar{F}(\bar{R})$. Hence, either $F(\bar{R}) = F(R)$ or $F(\bar{R}) P_n F(R)$. Then, since $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ and $\bar{R}_{-1} = R_{-1}$, by *one-sided replacement-dominance*, for each agent $i \in N \setminus \{1\}$ (including agent 2 now), $F(\bar{R}) R_i F(R)$. \square

2.C Proof of Proposition 2.5

Before proceeding with the proof of Proposition 2.5, we first prove an implication of *efficiency* and *population-monotonicity*.

Lemma 2.6. *Let choice correspondence $F \in \mathcal{F}$ satisfy efficiency and population-monotonicity. Then, for each population $N \in \mathcal{P}$ such that $|N| \geq 3$ and each profile $R \in \mathcal{R}^N$, the following hold.*

(i) *Without loss of generality, let agents $1, 2 \in N$ where $p(R_1) = \underline{p}(R)$ and $p(R_2) = \underline{p}(R_{-1})$. If maximum $\bar{F}(R) \in \text{Conv}(p(R_{-1}))$ and maximum $\bar{F}(R) \in w_{F(R)}(R_2)$, then maxima $\bar{F}(R) = \bar{F}(R_{-1})$. Moreover, if $F(R) \subseteq \text{Conv}(p(R_{-1}))$, then $F(R) = F(R_{-1})$.*

(ii) Without loss of generality, let agents $n-1, n \in N$ where $p(R_n) = \bar{p}(R)$ and $p(R_{n-1}) = \bar{p}(R_{-n})$. If minimum $\underline{F}(R) \in \text{Conv}(p(R_{-n}))$ and minimum $\underline{F}(R) \in w_{F(R)}(R_{n-1})$, then minima $\underline{F}(R) = \underline{F}(R_{-n})$. Moreover, if $F(R) \subseteq \text{Conv}(p(R_{-n}))$, then $F(R) = F(R_{-n})$.

Proof. Let choice correspondence $F \in \mathcal{F}$ satisfy efficiency and population-monotonicity. Let population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and profile $R \in \mathcal{R}^N$.

(i) Let agents $1, 2 \in N$ be such that $p(R_1) = \underline{p}(R)$ and $p(R_2) = \underline{p}(R_{-1})$. Let maximum $\bar{F}(R) \in \text{Conv}(p(R_{-1}))$ and maximum $\bar{F}(R) \in w_{F(R)}(R_2)$. Hence, $p(R_2) \leq \bar{F}(R)$. By population-monotonicity and Lemma 2.1, for each agent $i \in N \setminus \{1\}$, $F(R_{-1}) R_i F(R)$. Let agent $n \in N \setminus \{1, 2\}$ have the largest peak at profile R , i.e., $p(R_n) = \bar{p}(R) = \bar{p}(R_{-1})$. Since agent n has the largest peak at profiles R and R_{-1} , $F(R_{-1}) R_n F(R)$ and efficiency imply $\underline{F}(R) \leq \underline{F}(R_{-1}) \leq p(R_n)$ and $\bar{F}(R) \leq \bar{F}(R_{-1}) \leq p(R_n)$. Since agent 2 has the smallest peak at profile R_{-1} , $p(R_2) \leq \bar{F}(R)$, and $\bar{F}(R) \in w_{F(R)}(R_2)$, $F(R_{-1}) R_1 F(R)$ and efficiency imply $p(R_2) \leq \bar{F}(R_{-1}) \leq \bar{F}(R)$. Therefore, maxima $\bar{F}(R) = \bar{F}(R_{-1})$.

Moreover, let $F(R) \subseteq \text{Conv}(p(R_{-1}))$. Hence, $p(R_2) \leq \underline{F}(R)$. Since agent 2 has the smallest peak at profile R_{-1} and $p(R_2) \leq \underline{F}(R)$, $F(R_{-1}) R_1 F(R)$ and efficiency imply $p(R_2) \leq \underline{F}(R_{-1}) \leq \underline{F}(R)$. Therefore, minima $\underline{F}(R) = \underline{F}(R_{-1})$ and thus, $F(R) = F(R_{-n})$.

(ii) Symmetric proof to (i). □

Proof of Proposition 2.5. Let choice correspondence $F \in \mathcal{F}$ satisfy efficiency and population-monotonicity. Recall that for each population $N \in \mathcal{P}$, each choice correspondence $F \in \mathcal{F}$ specifies an fp-choice correspondence $F \in \mathcal{F}^N$. Since for each $N \in \mathcal{P}$ such that $|N| \leq 2$, (one-sided) replacement-dominance imposes no restriction on fp-choice correspondence $F \in \mathcal{F}^N$, let $N \in \mathcal{P}$ be such that $|N| \geq 3$.

We show that for each profile $R \in \mathcal{R}^N$, if the preferences of an agent $j \in N$ change, such that $R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$, then the other agents whose preferences remained unchanged all end up at least as well off, as they were initially, i.e., for each $i \in N \setminus \{j\}$, $F(R) R_i F(\bar{R})$.²⁷ Without loss of generality, assume that $N = \{1, 2, \dots, n\}$ and $\underline{p}(R) = p(R_1) \leq p(R_2) \leq \dots \leq p(R_n) = \bar{p}(R)$. In the following, we refer to agents who have neither the unique smallest peak nor the unique largest peak as *middle agents*.

Case 1. Let $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$.

Case 1.1. Let agent j be a middle agent at both profiles R and \bar{R} . Then,

²⁷Notice that the roles of profiles R and \bar{R} can be reversed, hence the case where $\text{Conv}(p(R)) \subseteq \text{Conv}(p(\bar{R}))$ is also covered.

$\text{Conv}(p(\bar{R})) = \text{Conv}(p(R)) = \text{Conv}(p(R_{-j}))$. Remove agent j from profile R to obtain profile R_{-j} . Since $\text{Conv}(p(R_{-j})) = \text{Conv}(p(R))$, by *population-monotonicity* and Lemma 2.1, $F(R_{-j}) = F(R)$. Next, add agent j with preferences \bar{R}_j to obtain profile \bar{R} . Since $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R_{-j}))$, by *population-monotonicity* and Lemma 2.1, $F(\bar{R}) = F(R_{-j})$. Therefore, $F(\bar{R}) = F(R)$.

Case 1.2. Let agent j have the unique smallest (largest) peak at both profiles R and \bar{R} . Hence, either agent $j = 1$ has the unique smallest peak at both profiles R and \bar{R} or agent $j = n$ has the unique largest peak at both profiles R and \bar{R} . By symmetry of arguments, assume that $j = 1$ and profile \bar{R} is such that $\bar{R}_{-1} = R_{-1}$. Hence, $p(R_1) = p(\bar{R}_1) < p(R_2) \leq \dots \leq p(R_n)$.

Begin from profile R and construct profile R^1 by changing agent 2's preferences to $R_2^1 = R_1$, i.e., $R^1 = (R_{-2}, R_2^1)$. Since $\text{Conv}(R^1) = \text{Conv}(p(R))$ and agent 2 is a middle agent at both profiles R^1 and R , by Case 1.1, $F(R^1) = F(R)$. Next, change agent 1's preferences to $R_1^2 = \bar{R}_1$ such that the new profile is $R^2 = (R_{-1}^2, R_1^2)$. Since $\text{Conv}(R^2) = \text{Conv}(R^1)$ and agent 1 is a middle agent at both profiles R^2 and R^1 , by Case 1.1, $F(R^2) = F(R^1)$. Finally, change agent 2's preferences back to R_2 and notice that the new profile $(R_{-2}^2, R_2) = \bar{R}$. Since $\text{Conv}(p(\bar{R})) = \text{Conv}(R^2)$ and agent 2 is a middle agent at both profiles \bar{R} and R^2 , by Case 1.1, $F(\bar{R}) = F(R^2)$. Therefore, $F(\bar{R}) = F(R)$.

Case 2. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, either agent $j = 1$ has the unique smallest peak at profile R or agent $j = n$ has the unique largest peak at profile R . By symmetry of arguments, assume that $j = 1$ and profile \bar{R} is such that $\bar{R}_{-1} = R_{-1}$.

Case 2.1. Let agent 1 be a middle agent at profile \bar{R} . Then, $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R_{-1}))$. Begin from profile R and remove agent 1 from profile R to obtain profile R_{-1} . By *population-monotonicity* and Lemma 2.1, for each agent $i \in N \setminus \{1\}$, $F(R_{-1}) R_i F(R)$. Next, add agent 1 with preferences \bar{R}_1 to obtain profile \bar{R} . Since $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R_{-1}))$, by *population-monotonicity* and Lemma 2.1, $F(\bar{R}) = F(R_{-1})$. Therefore, for each agent $i \in N \setminus \{1\}$, $F(\bar{R}) R_i F(R)$.

Case 2.2. Recall that $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ and let agent 1 have the unique smallest peak at profile R . In addition, let agent 1 also have the unique smallest peak at profile \bar{R} . Then, $\text{Conv}(p(R_{-1})) \subsetneq \text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, $p(R_1) < p(\bar{R}_1) < p(R_2) \leq \dots \leq p(R_n)$. The proof of this case proceeds in two parts.

First, we show that for each agent $i \in N \setminus \{1, 2\}$, $F(\bar{R}) R_i F(R)$ and $F(\bar{R}) \bar{R}_1 F(R)$. Begin from profile R and construct profile R^1 by changing agent 2's preferences to $R_2^1 = \bar{R}_1$, i.e., $R^1 = (R_{-2}, R_2^1)$. Since $\text{Conv}(R^1) = \text{Conv}(p(R))$ and

agent 2 is a middle agent at both profiles R^1 and R , by Case 1.1, $F(R^1) = F(R)$. Next, change agent 1's preferences to $R_1^2 = \bar{R}_1$ such that the new profile is $R^2 = (R_{-1}^1, R_1^2)$. Since agent 1 is a middle agent at profile R^2 , by Case 2.1, for each agent $i \in N \setminus \{1\}$, $F(R^2) R_i^1 F(R^1)$. Hence, for each agent $i \in N \setminus \{1, 2\}$, $F(R^2) R_i F(R^1)$ and $F(R^2) \bar{R}_1 F(R^1)$. Finally, change agent 2's preferences back to R_2 and notice that the new profile $(R_{-2}^2, R_2) = \bar{R}$. Since $\text{Conv}(p(\bar{R})) = \text{Conv}(R^2)$ and agent 2 is a middle agent at both profiles \bar{R} and R^2 , by Case 1.1, $F(\bar{R}) = F(R^2)$. Therefore, for each agent $i \in N \setminus \{1, 2\}$, $F(\bar{R}) R_i F(R)$ and $F(\bar{R}) \bar{R}_1 F(R)$.

Second, we prove that $F(\bar{R}) R_2 F(R)$. Since agent n has the largest peak at both profiles R and \bar{R} , $F(\bar{R}) R_n F(R)$ and efficiency imply $F(R) \leq F(\bar{R}) \leq p(R_n)$ and $\bar{F}(R) \leq \bar{F}(\bar{R}) \leq p(R_n)$. Hence, either $F(\bar{R}) = F(R)$ or $F(\bar{R}) P_n F(R)$. If $F(\bar{R}) = F(R)$, then $F(\bar{R}) R_2 F(R)$. If $F(\bar{R}) P_n F(R)$, then (a) $F(R) < F(\bar{R}) \leq p(R_n)$ or (b) $\bar{F}(R) < \bar{F}(\bar{R}) \leq p(R_n)$.

If $F(R) \geq p(R_2)$, then $F(\bar{R}) \subseteq \text{Conv}(p(R_{-1}))$ and by Lemma 2.6 (i), $F(\bar{R}) = F(R_{-1})$. Next, consider the change from profile R to R_{-1} . By *population-monotonicity* and Lemma 2.1, for each agent $i \in N \setminus \{1\}$, $F(R_{-1}) R_i F(R)$. Therefore, for each agent $i \in N \setminus \{1\}$ (including agent 2 now), $F(\bar{R}) R_i F(R)$.

The remaining case is that $F(R) < p(R_2)$. Since agent 1 has the smallest peak at profile \bar{R} , efficiency implies $p(\bar{R}_1) \leq F(\bar{R}) \leq \bar{F}(\bar{R})$. If (a) $F(R) < F(\bar{R})$, then $F(\bar{R}) \bar{R}_1 F(R)$ implies $F(R) < p(\bar{R}_1)$ and if (b) $\bar{F}(R) < \bar{F}(\bar{R})$, then $F(\bar{R}) \bar{R}_1 F(R)$ implies $\bar{F}(R) < p(\bar{R}_1)$ and thus, $F(R) < p(\bar{R}_1)$.

Hence, there are two cases (2.2. α) $F(R) < p(\bar{R}_1) \leq F(\bar{R}) < p(R_2)$ and $\bar{F}(R) = \bar{F}(\bar{R})$ and (2.2. β) $F(R) \leq \bar{F}(R) < p(\bar{R}_1) \leq F(\bar{R}) < p(R_2)$.

Case 2.2. α . If $\bar{F}(R) = \bar{F}(\bar{R}) \leq p(R_2)$, then $b_{F(R)}(R_2) = \bar{F}(R) = \bar{F}(\bar{R}) = b_{F(\bar{R})}(R_2) \leq p(R_2)$ and $w_{F(R)}(R_2) = F(R) < F(\bar{R}) = w_{F(\bar{R})}(R_2) < p(R_2)$. By single-peakedness, $F(\bar{R}) P_2 F(R)$.

If $\bar{F}(R) = \bar{F}(\bar{R}) > p(R_2)$, then $b_{F(R)}(R_2) = b_{F(\bar{R})}(R_2) = p(R_2)$, $w_{F(R)}(R_2) \in \{F(R), \bar{F}(R)\}$, and $w_{F(\bar{R})}(R_2) \in \{F(\bar{R}), \bar{F}(\bar{R})\}$. Then, $F(R) < F(\bar{R}) < p(R_2) < \bar{F}(R) = \bar{F}(\bar{R})$ and single-peakedness imply $F(\bar{R}) R_2 F(R)$.

Case 2.2. β . Notice that $b_{F(R)}(R_2) = \{F(R)\}$ and $w_{F(R)}(R_2) = \{F(R)\}$.

If $\bar{F}(\bar{R}) \leq p(R_2)$, then $\bar{F}(\bar{R}) \in b_{F(\bar{R})}(R_2)$ and $F(\bar{R}) \in w_{F(\bar{R})}(R_2)$. Since then $F(R) \leq \bar{F}(R) < F(\bar{R}) \leq \bar{F}(\bar{R}) \leq p(R_2)$, by single-peakedness, $F(\bar{R}) P_2 F(R)$.

If $\bar{F}(\bar{R}) > p(R_2)$, then $b_{F(\bar{R})}(R_2) = \{p(R_2)\}$ and $w_{F(\bar{R})}(R_2) \subseteq \{F(\bar{R}), \bar{F}(\bar{R})\}$. Hence, $b_{F(\bar{R})}(R_2) P_2 b_{F(R)}(R_2)$. Since $F(R) < F(\bar{R}) < p(R_2)$, by single-peakedness, $F(\bar{R}) P_2 F(R) = w_{F(R)}(R_2)$.

If $F(\bar{R}) \in w_{F(\bar{R})}(R_2)$, then $w_{F(\bar{R})}(R_2) P_2 w_{F(R)}(R_2)$ and $F(\bar{R}) P_2 F(R)$.

Finally, if $F(\bar{R}) \notin w_{F(\bar{R})}(R_2)$, then $w_{F(\bar{R})}(R_2) = \{\bar{F}(\bar{R})\}$. Note that $\bar{F}(\bar{R}) \in$

$\text{Conv}(p(R_{-1}))$. By Lemma 2.6 (i), $\bar{F}(\bar{R}) = \bar{F}(R_{-1})$. Consider the change from profile R to R_{-1} . By *population-monotonicity* and Lemma 2.1, for each agent $i \in N \setminus \{1\}$, $F(R_{-1}) R_i F(R)$. In particular, $F(R_{-1}) R_2 F(R)$ and $w_{F(R_{-1})}(R_2) R_2 w_{F(R)}(R_2)$. Since agent 2 has the smallest peak at profile R_{-1} , *efficiency* and *single-peakedness* imply that $\bar{F}(R_{-1}) \in w_{F(R_{-1})}(R_2)$. Hence, $\bar{F}(\bar{R}) \in w_{F(R_{-1})}(R_2)$ and $w_{F(\bar{R})}(R_2) = \bar{F}(\bar{R}) R_2 w_{F(R)}(R_2)$. Therefore, $F(\bar{R}) R_2 F(R)$. \square

2.D Proof of Theorem 2.1

Before proceeding with the proof of Theorem 2.1, we first prove some implications of *efficiency* and *(one-sided) replacement-dominance*. The first implication is *peak-monotonicity*, introduced by Ching (1994). The definition follows.

An fp-choice correspondence satisfies *peak-monotonicity* if whenever an agent's preferences change such that his peak moves to the left (right), the chosen set moves to the left (right). We formulate *peak-monotonicity* for fp-choice correspondences but as discussed in Remark 2.3, it easily extends to choice correspondences.

Peak-monotonicity. *Let fixed population $N \in \mathcal{P}$ and fp-choice correspondence $F \in \mathcal{F}^N$. For each agent $j \in N$ and each pair of profiles $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$,*

$$\text{if } p(\bar{R}_j) \leq p(R_j), \text{ then } \begin{cases} \text{minimum } \underline{F}(\bar{R}) \leq \underline{F}(R) \\ \text{and} \\ \text{maximum } \bar{F}(\bar{R}) \leq \bar{F}(R). \end{cases}$$

Lemma 2.7 (Efficiency and one-sided replacement-dominance \Rightarrow peak-monotonicity). *If a fixed population consists of at least 3 agents, then an associated fp-choice correspondence that satisfies efficiency and one-sided replacement-dominance also satisfies peak-monotonicity.*

Proof. Let fixed population $N \in \mathcal{P}$ such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *one-sided replacement-dominance*. Let agent $j \in N$ and the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $R_{-j} = \bar{R}_{-j}$ and $p(\bar{R}_j) \leq p(R_j)$. By *efficiency*, $F(R) \in \text{PE}(R)$ and $F(\bar{R}) \in \text{PE}(\bar{R})$. In the following, we refer to agents who have neither the unique smallest peak nor the unique largest peak as *middle agents*.

Case 1. Let agent j be a middle agent or have the smallest peak at profile R . Hence, $\underline{p}(\bar{R}) \leq \underline{p}(R) \leq \bar{p}(\bar{R}) = \bar{p}(R)$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(p(\bar{R}))$. By

one-sided replacement-dominance and Lemma 2.2, for each agent $i \in N \setminus \{j\}$, $F(R)R_iF(\bar{R})$. Finally, let agent $n \in N \setminus \{j\}$ have the largest peak at profile R , i.e., $p(R_n) = \bar{p}(R) = \bar{p}(\bar{R})$. By $F(R)R_nF(\bar{R})$ and *efficiency*, $\underline{F}(\bar{R}) \leq \underline{F}(R) \leq p(R_n)$ and $\bar{F}(\bar{R}) \leq \bar{F}(R) \leq p(R_n)$.

Case 2. Let agent j have the unique largest peak at profile R .

Case 2.1. Let agent j have the unique largest peak at profile R and be a middle agent at profile \bar{R} . Hence, $\underline{p}(\bar{R}) = \underline{p}(R) \leq \bar{p}(\bar{R}) < \bar{p}(R)$. By the symmetric argument of Case 1 (with agent n being a middle agent at profile \bar{R} instead of agent 1 being a middle agent at profile R , and with agent n 's peak moving to the right instead of agent 1's peak moving to the left), $\underline{F}(\bar{R}) \leq \underline{F}(R)$ and $\bar{F}(\bar{R}) \leq \bar{F}(R)$.

Case 2.2. Let agent j have the unique largest peak at profile R and the unique smallest peak at profile \bar{R} . Hence, $\underline{p}(\bar{R}) < \underline{p}(R) \leq \bar{p}(\bar{R}) < \bar{p}(R)$. Begin from profile R and construct profile R^1 by changing agent j 's preferences to R_j^1 such that his peak $p(R_j^1) = \underline{p}(R)$, i.e., $R^1 = (R_{-j}, R_j^1)$. Since agent j has the unique largest peak at profile R and is a middle agent at profile R^1 , by Case 2.1, $\underline{F}(R^1) \leq \underline{F}(R)$ and $\bar{F}(R^1) \leq \bar{F}(R)$. Finally, change agent j 's preferences to \bar{R}_j and notice that the new profile $(R_{-j}^1, \bar{R}_j) = \bar{R}$. Since agent j is a middle agent at profile R^1 , by Case 1, $\underline{F}(\bar{R}) \leq \underline{F}(R^1) \leq \underline{F}(R)$ and $\bar{F}(\bar{R}) \leq \bar{F}(R^1) \leq \bar{F}(R)$. \square

The second implication of *efficiency* and (*one-sided*) *replacement-dominance* is *uncompromisingness*, introduced by Border and Jordan (1983). The definition follows.

Loosely speaking, an fp-choice correspondence satisfies *uncompromisingness* if whenever an agent's preferences change such that his peaks, before and after this change, both lie on the same side of the minimum (maximum) point chosen, the minimum (maximum) point chosen does not change. We formulate *uncompromisingness*—and later *set-uncompromisingness*—for fp-choice correspondences but as discussed in Remark 2.3, they easily extend to choice correspondences.

Uncompromisingness. *Let fixed population $N \in \mathcal{P}$ and fp-choice correspondence $F \in \mathcal{F}^N$. For each agent $j \in N$ and each pair of profiles $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$,*

$$\text{if } \begin{cases} p(R_j) < \underline{F}(R) \text{ and } p(\bar{R}_j) \leq \underline{F}(R) \\ \text{or} \\ p(R_j) > \underline{F}(R) \text{ and } p(\bar{R}_j) \geq \underline{F}(R), \end{cases} \text{ then minima } \underline{F}(R) = \underline{F}(\bar{R})$$

and

$$\text{if } \begin{cases} p(R_j) > \bar{F}(R) \text{ and } p(\bar{R}_j) \geq \bar{F}(R) \\ \text{or} \\ p(R_j) < \bar{F}(R) \text{ and } p(\bar{R}_j) \leq \bar{F}(R), \end{cases} \text{ then maxima } \bar{F}(R) = \bar{F}(\bar{R}).$$

Uncompromisingness immediately implies the following notion of *set-uncompromisingness*.

Set-uncompromisingness. Let fixed population $N \in \mathcal{P}$ and fp-choice correspondence $F \in \mathcal{F}^N$. For each agent $j \in N$ and each pair of profiles $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$,

$$\text{if } \begin{cases} p(R_j) < \underline{F}(R) \text{ and } p(\bar{R}_j) \leq \underline{F}(R) \\ \text{or} \\ p(R_j) > \bar{F}(R) \text{ and } p(\bar{R}_j) \geq \bar{F}(R), \end{cases} \text{ then } F(R) = F(\bar{R}).$$

Lemma 2.8 (Uncompromisingness \Rightarrow set-uncompromisingness). Each fp-choice correspondence satisfying *uncompromisingness* also satisfies *set-uncompromisingness*.

Proof. Follows trivially by the definitions of *uncompromisingness* and *set-uncompromisingness*. \square

Before stating in Lemma 2.10 some conditions under which an fp-choice correspondence satisfies *uncompromisingness*, we first state a result for the domain of symmetric single-peaked preferences \mathcal{S} (Lemma 2.9). This is the only result where we have to change the proof technique when dealing with domain \mathcal{S} .²⁸ Specifically, we prove Lemma 2.9 using a so-called ‘‘leapfrogging’’ argument. During each leapfrog we right (left) extend the convex hull of the peaks by some distance and if this distance is not enough we repeat this argument as many (finite) times as necessary. Notice that Lemma 2.9 also holds on the domain of single-peaked preferences \mathcal{R} .

Lemma 2.9. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *one-sided replacement-dominance*. For each agent $j \in N$ and each pair of profiles $R, \bar{R} \in \mathcal{R}^N$ such that $R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(R)) \subsetneq \text{Conv}(p(\bar{R}))$,

²⁸Recall that all steps in all other proofs are for domain \mathcal{R} but they automatically apply to domain \mathcal{S} .

(i) if minimum $\underline{F}(R) < \bar{p}(R) < p(\bar{R}_j)$, then minima $\underline{F}(\bar{R}) = \underline{F}(R)$. Moreover, if also maximum $\bar{F}(R) < \bar{p}(R)$, then $F(\bar{R}) = F(R)$,

(ii) if maximum $\bar{F}(R) > \underline{p}(R) > p(\bar{R}_j)$, then maxima $\bar{F}(\bar{R}) = \bar{F}(R)$. Moreover, if also minimum $\underline{F}(R) > \underline{p}(R)$, then $F(\bar{R}) = F(R)$.

Proof. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy efficiency and one-sided replacement-dominance. By Lemmas 2.5 (Appendix 2.B) and 2.7, F satisfies extreme-peaks-onliness and peak-monotonicity.

Let agent $j \in N$ and the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $R_{-j} = \bar{R}_{-j}$ and $\text{Conv}(p(R)) \subsetneq \text{Conv}(p(\bar{R}))$. By efficiency, $F(R) \in \text{PE}(R)$. By extreme-peaks-onliness, it is without loss of generality to assume that both profiles R and \bar{R} are symmetric, i.e., $R, \bar{R} \in \mathcal{S}^N$.²⁹ In the following, we refer to agents who have neither the unique smallest peak nor the unique largest peak as *middle agents*. Moreover, we only prove (i) since the proof of (ii) is symmetric.

Let minimum $\underline{F}(R) < \bar{p}(R) < p(\bar{R}_j)$. Since $\bar{p}(R) < p(\bar{R}_j)$ and $F(R) \in \text{PE}(R)$, by Proposition 2.1 (i), $\underline{p}(R) \leq \underline{F}(R) \leq \bar{F}(R) \leq \bar{p}(R) < p(\bar{R}_j)$. Since also $\text{Conv}(p(R)) \subsetneq \text{Conv}(p(\bar{R}))$, agent j either [is a middle agent at profile R and has the unique largest peak at profile \bar{R}] or [has the unique largest peak at both profiles R and \bar{R}].

Case 1. Let agent j be a middle agent at profile R and have the unique largest peak at profile \bar{R} . Let agent $n \in N \setminus \{j\}$ have the largest peak at profile R , i.e., $p(R_n) = \bar{p}(R)$. Hence, minimum $\underline{F}(R) < \bar{p}(R)$ and efficiency imply $\underline{F}(R) < p(R_n)$ and $\bar{F}(R) \leq p(R_n)$. By single-peakedness, $b_{F(R)}(R_n) = \bar{F}(R)$ and $w_{F(R)}(R_n) = \underline{F}(R)$.

Let the distance between minimum $\underline{F}(R)$ and peak $p(R_n)$ be $\delta_0 = |\underline{F}(R) - p(R_n)|$. Let point $x_1 \in \mathbb{R}$ be on the right side of peak $p(R_n)$, i.e., $x_1 > p(R_n) = \bar{p}(R)$, such that the distance between minimum $\underline{F}(R)$ and point x_1 is $\delta_1 = |\underline{F}(R) - x_1| = \frac{3}{2}\delta_0$. Hence, distance $|p(R_n) - x_1| = |\underline{F}(R) - x_1| - |\underline{F}(R) - p(R_n)| = \frac{1}{2}\delta_0 = \frac{1}{2}|\underline{F}(R) - p(R_n)|$ and point x_1 is closer to peak $p(R_n)$ than minimum $\underline{F}(R)$ is.

Step 1. Begin from profile R and construct profile R^1 by changing agent j 's preferences to $R_j^1 \in \mathcal{S}$ such that his peak

$$p(R_j^1) = \begin{cases} p(\bar{R}_j) & \text{if } p(\bar{R}_j) \leq x_1 \\ x_1 & \text{otherwise,} \end{cases}$$

²⁹For each agent $i \in N$, we can replace preferences $R_i, \bar{R}_i \in \mathcal{R}$ by preferences $R'_i, \bar{R}'_i \in \mathcal{S}$ such that $p(R_i) = p(R'_i)$ and $p(\bar{R}_i) = p(\bar{R}'_i)$. Then, by extreme-peaks-onliness, $F(R) = F(R')$ and $F(\bar{R}) = F(\bar{R}')$.

i.e., $R^1 = (R_{-j}, R_j^1)$. Hence, $R_{-j}^1 = R_{-j}$. By *efficiency* and Proposition 2.1 (i), $p(R) = p(R^1) \leq \underline{F}(R^1) \leq \bar{F}(R^1) \leq \bar{p}(R^1) = p(\bar{R}_j)$. Since $p(R_j^1) > p(R_j)$, by *peak-monotonicity*, minimum $\underline{F}(R^1) \geq \underline{F}(R)$ and maximum $\bar{F}(R^1) \geq \bar{F}(R)$. Hence, $\underline{F}(R^1) \in [\underline{F}(R), p(\bar{R}_j)]$ and $\bar{F}(R^1) \in [\bar{F}(R), p(\bar{R}_j)]$. Since $\text{Conv}(p(R)) \subsetneq \text{Conv}(R^1)$, by *one-sided replacement-dominance* and Lemma 2.2, agent n ends up at most as well off, $F(R) R_n F(R^1)$. Hence, $b_{F(R)}(R_n) R_n b_{F(R^1)}(R_n)$ and $w_{F(R)}(R_n) R_n w_{F(R^1)}(R_n)$.

If $\underline{F}(R^1) \in [p(R_n), p(\bar{R}_j)]$, then $w_{F(R^1)}(R_n) = \bar{F}(R^1) \in [p(R_n), p(\bar{R}_j)]$. The distance of agent n 's worst point $\bar{F}(R^1)$ to peak $p(R_n)$ is $|p(R_n) - \bar{F}(R^1)| \leq |p(R_n) - p(R_j^1)| \leq |p(R_n) - x_1| = \frac{1}{2}\delta_0 = \frac{1}{2}|\underline{F}(R) - p(R_n)|$, which is smaller than the distance of minimum $\underline{F}(R)$ to peak $p(R_n)$. By symmetric single-peakedness, agent n prefers $w_{F(R^1)}(R_n) = \bar{F}(R^1)$ to $w_{F(R)}(R_n) = \underline{F}(R)$; a contradiction. Hence, $\underline{F}(R^1) \in [\underline{F}(R), p(R_n))$ and $w_{F(R^1)}(R_n) = \underline{F}(R^1)$. Since $\underline{F}(R^1) < p(R_n)$, for agent n to find $w_{F(R)}(R_n) = \underline{F}(R)$ at least as desirable as $w_{F(R^1)}(R_n) = \underline{F}(R^1)$, then minimum $\underline{F}(R) \geq \underline{F}(R^1)$. Hence, minima $\underline{F}(R^1) = \underline{F}(R)$.

Moreover, let maximum $\bar{F}(R) < \bar{p}(R) = p(R_n)$. Then, $b_{F(R)}(R_n) = \bar{F}(R)$. Recall that $\bar{F}(R^1) \in [\bar{F}(R), p(\bar{R}_j)]$. If $\bar{F}(R^1) \in [p(R_n), p(\bar{R}_j)]$, then agent n prefers $b_{F(R^1)}(R_n) = p(R_n)$ to $b_{F(R)}(R_n) = \bar{F}(R)$; a contradiction. Hence, $\bar{F}(R^1) \in [\bar{F}(R), p(R_n))$ and $b_{F(R^1)}(R_n) = \bar{F}(R^1)$. Since $\bar{F}(R^1) < p(R_n)$, for agent n to find $b_{F(R)}(R_n) = \bar{F}(R)$ at least as desirable as $b_{F(R^1)}(R_n) = \bar{F}(R^1)$, then maximum $\bar{F}(R) \geq \bar{F}(R^1)$. Hence, maxima $\bar{F}(R^1) = \bar{F}(R)$ and $F(R^1) = F(R)$.

If $p(R_j^1) = p(\bar{R}_j)$, then $\text{Conv}(R^1) = \text{Conv}(p(\bar{R}))$ and by *extreme-peaks-onliness*, $F(R^1) = F(\bar{R})$ and we are done. If $p(R_j^1) \neq p(\bar{R}_j)$, then note that agent n is now a middle agent and agent j has the unique largest peak at profile R^1 . We now explain the term ‘‘leapfrogging’’ in order to explain the proof technique: in Step 1, the peak of agent j moves to the right of agent n 's peak by figuratively leapfrogging over agent n . In Step 2, the roles of agents j and n reverse, and agent n leapfrogs over agent j to the right, etc.

Let point $x_2 \in \mathbb{R}$ be on the right side of peak $p(R_j^1)$, i.e., $x_2 > p(R_j^1) = \bar{p}(R^1)$, such that the distance between minimum $\underline{F}(R)$ and point x_2 is $\delta_2 = |\underline{F}(R) - x_2| = \frac{3}{2}\delta_1$. Hence, distance $|p(R_j^1) - x_2| = |\underline{F}(R) - x_2| - |\underline{F}(R) - p(R_j^1)| = \frac{1}{2}\delta_1 = \frac{1}{2}|\underline{F}(R) - p(R_j^1)|$ and point x_2 is closer to peak $p(R_j^1)$ than minimum $\underline{F}(R)$ is.

Step 2. Begin from profile R^1 and construct profile R^2 by changing agent n 's preferences to $R_n^2 \in \mathcal{S}$ such that his peak

$$p(R_n^2) = \begin{cases} p(\bar{R}_j) & \text{if } p(\bar{R}_j) \leq x_2 \\ x_2 & \text{otherwise,} \end{cases}$$

i.e., $R^2 = (R_{-n}^1, R_n^2)$. Hence, $R_{-n}^2 = R_{-n}^1$. By the arguments described in the previous step (with profiles R and R^1 replaced by profiles R^1 and R^2 and with agent n in the role of agent j), minima $\underline{F}(R^2) = \underline{F}(R^1) = \underline{F}(R)$.

Moreover, let maximum $\bar{F}(R) < \bar{p}(R)$. Then, maximum $\bar{F}(R) = \bar{F}(R^1) < \bar{p}(R^1) = p(R_j^1)$ and by the arguments described in the previous step (with profiles R and R^1 replaced by profiles R^1 and R^2 and with agent n in the role of agent j), $F(R^2) = F(R^1) = F(R)$.

If $p(R_n^2) = p(\bar{R}_j)$, then $\text{Conv}(R^2) = \text{Conv}(p(\bar{R}))$ and by *extreme-peaks-onliness*, $F(R^2) = F(\bar{R})$ and we are done. If $p(R_j^2) \neq p(\bar{R}_j)$. Then, according to the reasoning described below, repeat the leapfrogging steps described above $\nu \in \mathbb{N}^+$ amount of times.

Recall that $\delta_1 = \frac{3}{2}\delta_0$ and $\delta_2 = \frac{3}{2}\delta_1$. Hence, $\delta_\nu = \frac{3}{2}\delta_{\nu-1} = \left(\frac{3}{2}\right)^\nu \delta_0$ and since $\delta_0 \neq 0$, in the limit, $\lim_{\nu \rightarrow \infty} \delta_\nu = \infty$. Thus, for each profile $\bar{R} \in \mathcal{R}^N$ such that $\bar{R}_{-j} = R_{-j}$ and $p(\bar{R}_j) > p(R_j)$, there exists a finite $\nu \in \mathbb{N}^+$ such that the distance $\delta_\nu > |\underline{F}(R) - p(\bar{R}_j)|$. Therefore, for each profile $\bar{R} \in \mathcal{R}^N$ such that $\bar{R}_{-j} = R_{-j}$ and $p(\bar{R}_j) > p(R_j)$, there exists a profile R^ν such that $\text{Conv}(R^\nu) = \text{Conv}(p(\bar{R}))$ and the following holds. If minimum $\underline{F}(R) < \bar{p}(R) = p(R_n) < p(\bar{R}_j)$, then minima $\underline{F}(R^\nu) = \underline{F}(R)$ and moreover, if also maximum $\bar{F}(R) < \bar{p}(R)$, then $F(R^\nu) = F(R)$. Since $\text{Conv}(R^\nu) = \text{Conv}(p(\bar{R}))$, by *extreme-peaks-onliness*, $F(R^\nu) = F(\bar{R})$ and we are done.

Case 2. Let agent $j = n$ have the unique largest peak at profiles R and \bar{R} . Let agent $k \in N \setminus \{j\}$ be a middle agent at profile R and construct profile R^1 by changing his preferences to R_k^1 such that his peak $p(R_k^1) = \bar{p}(R)$, i.e., $R^1 = (R_{-k}, R_k^1)$. Since $\text{Conv}(R^1) = \text{Conv}(p(R))$, by *extreme-peaks-onliness*, $F(R^1) = F(R)$. Therefore, since minimum $\underline{F}(R) < \bar{p}(R) = \bar{p}(R^1) = p(R_k^1) < p(\bar{R}_j)$, by Case 1, minima $\underline{F}(\bar{R}) = \underline{F}(R^1) = \underline{F}(R)$ and moreover, if also maximum $\bar{F}(R) < \bar{p}(R) = \bar{p}(R^1)$, by Case 1, $F(\bar{R}) = F(R^1) = F(R)$. \square

Lemma 2.10 (Efficiency and one-sided replacement-dominance \Rightarrow uncompromisingness). *If a fixed population consists of at least 3 agents, then an associated fp-choice correspondence that satisfies efficiency and one-sided replacement-dominance also satisfies uncompromisingness.*

Proof. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *one-sided replacement-dominance*. By Lemmas 2.5 (Appendix 2.B) and 2.7, F satisfies *extreme-peaks-onliness* and *peak-monotonicity*. Let agent $j \in N$ and the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $R_{-j} = \bar{R}_{-j}$. In the following, we refer to agents who have neither the unique

smallest peak nor the unique largest peak as *middle agents*.

(i) We show that if $[p(R_j) < \underline{F}(R) \text{ and } p(\bar{R}_j) \leq \underline{F}(R)]$ or $[p(R_j) > \underline{F}(R) \text{ and } p(\bar{R}_j) \geq \underline{F}(R)]$, then minima $\underline{F}(R) = \underline{F}(\bar{R})$. By *efficiency*, $F(R) \in \text{PE}(R)$. Hence by Proposition 2.1 (i), $F(R) \subseteq \text{Conv}(p(R))$. Notice that $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$ or $\text{Conv}(p(\bar{R})) \supseteq \text{Conv}(p(R))$.

Case 1. Let $p(R_j) < \underline{F}(R)$ and $p(\bar{R}_j) \leq \underline{F}(R)$. Hence, since $F(R) \subseteq \text{Conv}(p(R))$, $p(R_j) \neq \bar{p}(R)$.

Case 1.1. Let $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. By *extreme-peaks-onliness*, $F(R) = F(\bar{R})$.

Case 1.2. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, agent j has the unique smallest peak at profile R and minimum $\underline{F}(R) \geq p(\bar{R}_j) \geq \underline{p}(\bar{R}) > p(R_j)$. Begin from profile R and construct profile \bar{R} by changing agent j 's preferences to \bar{R}_j , i.e., $\bar{R} = (R_{-j}, \bar{R}_j)$. Since $p(\bar{R}_j) > p(R_j)$ and $\bar{R}_{-j} = R_{-j}$, by *peak-monotonicity*, minimum $\underline{F}(\bar{R}) \geq \underline{F}(R)$. If minimum $\underline{F}(\bar{R}) > \underline{F}(R) \geq p(\bar{R}_j)$, then $F(\bar{R}) \neq F(R)$ and minimum $\underline{F}(\bar{R}) > \underline{p}(\bar{R}) > p(R_j)$. Since $\bar{R}_{-j} = R_{-j}$, by Lemma 2.9 (ii) (with the roles of R and \bar{R} reversed), $F(\bar{R}) = F(R) \neq F(\bar{R})$, a contradiction. Therefore, minima $\underline{F}(\bar{R}) = \underline{F}(R)$.

Case 1.3. Let $\text{Conv}(p(\bar{R})) \supsetneq \text{Conv}(p(R))$. Hence, agent j has the unique smallest peak at profile \bar{R} and minimum $\underline{F}(R) > p(R_j) \geq \underline{p}(R) > p(\bar{R}_j)$. By Lemma 2.9 (ii), $F(\bar{R}) = F(R)$.

Case 2. Let $p(R_j) > \underline{F}(R)$ and $p(\bar{R}_j) \geq \underline{F}(R)$. Hence, since $F(R) \subseteq \text{Conv}(p(R))$, $p(R_j) \neq \underline{p}(R)$.

Case 2.1. Let $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. By *extreme-peaks-onliness*, $F(R) = F(\bar{R})$.

Case 2.2. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$. Hence, agent j has the unique largest peak at profile R and minimum $\underline{F}(R) \leq p(\bar{R}_j) \leq \bar{p}(\bar{R}) < p(R_j)$. Begin from profile R and construct profile \bar{R} by changing agent j 's preferences to \bar{R}_j , i.e., $\bar{R} = (R_{-j}, \bar{R}_j)$. Since $p(\bar{R}_j) < p(R_j)$ and $\bar{R}_{-j} = R_{-j}$, by *peak-monotonicity*, minimum $\underline{F}(\bar{R}) \leq \underline{F}(R)$. If minimum $\underline{F}(\bar{R}) < \underline{F}(R) \leq p(\bar{R}_j)$, then minimum $\underline{F}(\bar{R}) < \bar{p}(\bar{R}) < p(R_j)$. Since $\bar{R}_{-j} = R_{-j}$, by Lemma 2.9 (i) (with the roles of R and \bar{R} reversed), minimum $\underline{F}(\bar{R}) = \underline{F}(R) \neq \underline{F}(\bar{R})$, a contradiction. Therefore, minima $\underline{F}(\bar{R}) = \underline{F}(R)$.

Case 2.3. Let $\text{Conv}(p(\bar{R})) \supsetneq \text{Conv}(p(R))$. Hence, agent j has the unique largest peak at profile \bar{R} and minimum $\underline{F}(R) < p(R_j) \leq \bar{p}(R) < p(\bar{R}_j)$. By Lemma 2.9 (i), minima $\underline{F}(\bar{R}) = \underline{F}(R)$.

(ii) The proof that if $[p(R_j) > \bar{F}(R) \text{ and } p(\bar{R}_j) \geq \bar{F}(R)]$ or $[p(R_j) < \bar{F}(R) \text{ and } p(\bar{R}_j) \leq \bar{F}(R)]$, then maxima $\bar{F}(R) = \bar{F}(\bar{R})$ is symmetric to the proof of

(i). □

The next result is crucial in the proof of Theorem 2.1.

Lemma 2.11. *Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy efficiency and one-sided replacement-dominance. Let fp-target set correspondence $F^{a,b} \in \mathcal{F}^N$. For each pair of profiles $R, \bar{R} \in \mathcal{R}^N$ such that $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$, if $F(R) = F^{a,b}(R)$, then $F(\bar{R}) = F^{a,b}(\bar{R})$.*

Proof. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy efficiency and one-sided replacement-dominance. Let fp-target set correspondence $F^{a,b} \in \mathcal{F}^N$. By Propositions 2.1 and 2.4, $F^{a,b}$ satisfies efficiency and one-sided replacement-dominance. By Lemma 2.5 (Appendix 2.B), Lemma 2.10, and Lemma ??, F and $F^{a,b}$ satisfy extreme-peaks-onliness, uncompromisingness, and set-uncompromisingness.

Let the pair of profiles $R, \bar{R} \in \mathcal{R}^N$ be such that $F(R) = F^{a,b}(R)$ and $\text{Conv}(p(\bar{R})) \subseteq \text{Conv}(p(R))$. Without loss of generality, assume that $N = \{1, \dots, n\}$ and $\underline{p}(R) = p(R_1) \leq \dots \leq p(R_n) = \bar{p}(R)$. We show that $F(\bar{R}) = F^{a,b}(\bar{R})$.

Case 1. Let $\text{Conv}(p(\bar{R})) = \text{Conv}(p(R))$. By extreme-peaks-onliness and the definition of $F^{a,b}$, $F(\bar{R}) = F(R) = F^{a,b}(R) = F^{a,b}(\bar{R})$.

Case 2. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ be such that $\underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(\bar{R}) = \bar{p}(R)$. By extreme-peaks-onliness, it is without loss of generality to assume that at both profiles R and \bar{R} , agent 1 has the smallest peak and all other agents have the largest peak, i.e., $R = (R_1, R_n, \dots, R_n)$ such that $p(R_1) \leq p(R_n)$ and $\bar{R} = (\bar{R}_1, R_n, \dots, R_n)$ such that $p(\bar{R}_1) \leq p(R_n)$. Hence, $R_{-1} = \bar{R}_{-1}$ and $\underline{p}(R) < \underline{p}(\bar{R}) \leq \bar{p}(\bar{R}) = \bar{p}(R)$. By efficiency and Proposition 2.1 (i), $p(R_1) = \underline{p}(R) \leq \underline{F}(R) \leq \bar{F}(R) \leq \bar{p}(R)$ and $p(\bar{R}_1) = \underline{p}(\bar{R}) \leq \underline{F}(\bar{R}) \leq \bar{F}(\bar{R}) \leq \bar{p}(\bar{R})$.

Case 2.1. Recall that $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ is such that $[\underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(\bar{R}) = \bar{p}(R)]$ and in addition, let $p(\bar{R}_1) = \underline{p}(\bar{R}) \leq \underline{F}(R)$. Then, $p(R_1) = \underline{p}(R) < \underline{F}(R)$. By set-uncompromisingness, $F(\bar{R}) = F(R) = F^{a,b}(R)$ and by the definition of $F^{a,b}$, point $a \geq \underline{p}(\bar{R})$. If point $a \leq \bar{p}(R) = \bar{p}(\bar{R})$, then $F^{a,b}(R) = [a, b] \cap \text{Conv}(p(R)) = [a, b] \cap \text{Conv}(p(\bar{R})) = F^{a,b}(\bar{R})$. If point $a > \bar{p}(R) = \bar{p}(\bar{R})$, then, $F^{a,b}(R) = \{\bar{p}(R)\} = F^{a,b}(\bar{R})$. Therefore, $F(\bar{R}) = F^{a,b}(\bar{R})$.

Case 2.2. Recall that $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ is such that $[\underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(\bar{R}) = \bar{p}(R)]$ and in addition, let $p(\bar{R}_1) = \underline{p}(\bar{R}) > \underline{F}(R)$ and $p(\bar{R}_1) = \underline{p}(R) \leq \bar{F}(R)$. Then, $\underline{F}(R) \neq \bar{F}(R)$ and $p(R_1) < \bar{F}(R)$. By uncompromisingness, maxima $\bar{F}(\bar{R}) = \bar{F}(R)$. Recall that by efficiency and Proposition 2.1 (i), minimum $\underline{F}(\bar{R}) \geq \underline{p}(\bar{R}) = p(\bar{R}_1)$. Next, assuming that minimum $\underline{F}(\bar{R}) > \underline{p}(\bar{R}) = p(\bar{R}_1) > \underline{F}(R)$

results in a contradiction as follows: since $p(\bar{R}_1) < \underline{F}(\bar{R})$ and $p(R_1) < \underline{F}(\bar{R})$, by *uncompromisingness*, minimum $\underline{F}(R) = \underline{F}(\bar{R}) \neq \underline{F}(R)$, a contradiction. Hence, minimum $\underline{F}(\bar{R}) = \underline{p}(\bar{R})$ and thus, $\underline{F}(\bar{R}) = [\underline{p}(\bar{R}), \bar{F}(R)]$. Since $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ and $F(R) = [a, b] \cap \text{Conv}(p(R))$, $\underline{F}(\bar{R}) = F(R) \cap \text{Conv}(p(\bar{R})) = [a, b] \cap \text{Conv}(p(\bar{R}))$. Therefore, by the definition of $F^{a,b}$, $\underline{F}(\bar{R}) = [a, b] \cap \text{Conv}(p(\bar{R})) = F^{a,b}(\bar{R})$.

Case 2.3. Recall that $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ is such that $[\underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(\bar{R}) = \bar{p}(R)]$ and in addition, let $p(\bar{R}_1) = \underline{p}(\bar{R}) > \bar{F}(R) \geq \underline{F}(R)$. By the definition of $F^{a,b}$, points $a, b < \underline{p}(\bar{R})$. Next, assuming that maximum $\bar{F}(\bar{R}) > \underline{p}(\bar{R}) = p(\bar{R}_1) > \bar{F}(R)$ results in a contradiction as follows: since $p(\bar{R}_1) < \bar{F}(\bar{R})$ and $p(R_1) < \bar{F}(\bar{R})$, by *uncompromisingness*, maximum $\bar{F}(R) = \bar{F}(\bar{R}) \neq \bar{F}(R)$, a contradiction. Hence, maximum $\bar{F}(\bar{R}) = \underline{p}(\bar{R})$ and thus $\underline{F}(\bar{R}) = \{\underline{p}(\bar{R})\}$. Since point $b < \underline{p}(\bar{R})$, by the definition of $F^{a,b}$, $\underline{F}(\bar{R}) = \{\underline{p}(\bar{R})\} = F^{a,b}(\bar{R})$.

Case 3. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ be such that $\underline{p}(\bar{R}) = \underline{p}(R)$ and $\bar{p}(\bar{R}) < \bar{p}(R)$. By a symmetric proof to Case 2, $\underline{F}(\bar{R}) = F^{a,b}(\bar{R})$.

Case 4. Let $\text{Conv}(p(\bar{R})) \subsetneq \text{Conv}(p(R))$ be such that $\underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(\bar{R}) < \bar{p}(R)$. Let profile $R^1 \in \mathcal{R}^N$ be such that $\underline{p}(R^1) = \underline{p}(\bar{R}) > \underline{p}(R)$ and $\bar{p}(R^1) = \bar{p}(R)$. By Case 2, $\underline{F}(R^1) = F^{a,b}(R^1)$. Next, since $\underline{p}(\bar{R}) = \underline{p}(R^1)$ and $\bar{p}(\bar{R}) < \bar{p}(R^1)$, by Case 3, $\underline{F}(\bar{R}) = F^{a,b}(\bar{R})$. \square

Proof of Theorem 2.1. If part. By Propositions 2.1 and 2.4, each fp-target set correspondence satisfies *efficiency* and *one-sided replacement-dominance*.

Only if part. Let fixed population $N \in \mathcal{P}$ be such that $|N| \geq 3$ and fp-choice correspondence $F \in \mathcal{F}^N$ satisfy *efficiency* and *one-sided replacement-dominance*. By Lemma 2.5 (Appendix 2.B), Lemma 2.10, and Lemma ??, F satisfies *extreme-peaks-onliness*, *uncompromisingness*, and *set-uncompromisingness*.

For each pair of points $\alpha, \beta \in \mathbb{R}$ such that $\alpha \leq \beta$, define a profile $R^{\alpha,\beta} \in \mathcal{R}^N$ to be such that $\underline{p}(R^{\alpha,\beta}) = \alpha$ and $\bar{p}(R^{\alpha,\beta}) = \beta$. Without loss of generality, assume that $N = \{1, \dots, n\}$ and $\alpha = p(R_1^{\alpha,\beta}) \leq \dots \leq p(R_n^{\alpha,\beta}) = \beta$. By *efficiency* and Proposition 2.1 (i), $\alpha \leq \underline{F}(R^{\alpha,\beta}) \leq \bar{F}(R^{\alpha,\beta}) \leq \beta$.

We prove that there exists an fp-target set correspondence $F^{a,b} \in \mathcal{F}^N$ such that for each profile $R \in \mathcal{R}^N$, $F(R) = F^{a,b}(R)$.

There are four cases. Loosely speaking, in all but the last case the proof proceeds as follows. Given a profile $R^{\alpha,\beta} \in \mathcal{R}^N$ and for each profile $R \in \mathcal{R}^N$ we select a profile such that the convex hull of its peaks is a superset of both $\text{Conv}(R^{\alpha,\beta})$ and $\text{Conv}(p(R))$ and then, we apply Lemma 2.11 to show that $F(R) = F^{a,b}(R)$.

Case 1. There exist $\alpha, \beta \in \mathbb{R}$ such that for $R^{\alpha, \beta} \in \mathcal{R}^N$, $\alpha < \underline{F}(R^{\alpha, \beta}) \leq \bar{F}(R^{\alpha, \beta}) < \beta$. Define points $a := \underline{F}(R^{\alpha, \beta})$ and $b := \bar{F}(R^{\alpha, \beta})$. Since $F(R^{\alpha, \beta}) = [a, b] = [a, b] \cap \text{Conv}(R^{\alpha, \beta})$, by the definition of $F^{a, b}$, $F(R^{\alpha, \beta}) = F^{a, b}(R^{\alpha, \beta})$. Let $R \in \mathcal{R}^N$. Begin from profile $R^{\alpha, \beta}$ and construct profile R^1 by changing agent 1's preferences to R_1^1 such that his peak

$$p(R_1^1) = \begin{cases} p(R_1^{\alpha, \beta}) & \text{if } p(R_1^{\alpha, \beta}) \leq \underline{p}(R) \\ \underline{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^1 = (R_{-1}^{\alpha, \beta}, R_1^1)$. Since $p(R_1^{\alpha, \beta}) < \underline{F}(R^{\alpha, \beta})$ and $p(R_1^1) < \underline{F}(R^{\alpha, \beta})$, by *set-uncompromisingness*, $F(R^1) = F(R^{\alpha, \beta}) = [a, b]$. Then, change agent n 's preferences to R_n^2 such that his peak

$$p(R_n^2) = \begin{cases} p(R_n^1) & \text{if } p(R_n^1) \geq \bar{p}(R) \\ \bar{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^2 = (R_{-n}^1, R_n^2)$. Since $p(R_n^1) > \bar{F}(R^1)$ and $p(R_n^2) > \bar{F}(R^1)$, by *set-uncompromisingness*, $F(R^2) = F(R^1) = [a, b]$. Since $F(R^2) = [a, b] = [a, b] \cap \text{Conv}(R^2)$, by the definition of $F^{a, b}$, $F(R^2) = F^{a, b}(R^2)$. Since, $F(R^2) = F^{a, b}(R^2)$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(R^2)$, by Lemma 2.11, $F(R) = F^{a, b}(R)$.

Case 2. There exist $\alpha, \beta \in \mathbb{R}$ such that for $R^{\alpha, \beta} \in \mathcal{R}^N$, $\alpha = \underline{F}(R^{\alpha, \beta}) \leq \bar{F}(R^{\alpha, \beta}) < \beta$, and for each $\bar{\alpha} \leq \alpha$ and its associated $R^{\bar{\alpha}, \beta} \in \mathcal{R}^N$, $\bar{\alpha} = \underline{F}(R^{\bar{\alpha}, \beta}) \leq \bar{F}(R^{\bar{\alpha}, \beta}) < \beta$.

Case 2.1. There exist $\alpha, \beta \in \mathbb{R}$ as specified in Case 2 and in addition, $\alpha = \underline{F}(R^{\alpha, \beta}) < \bar{F}(R^{\alpha, \beta}) < \beta$. Define points $a := -\infty$ and $b := \bar{F}(R^{\alpha, \beta})$. Since $F(R^{\alpha, \beta}) = [\underline{p}(R^{\alpha, \beta}), b] = [a, b] \cap \text{Conv}(R^{\alpha, \beta})$, by the definition of $F^{a, b}$, $F(R^{\alpha, \beta}) = F^{a, b}(R^{\alpha, \beta})$. Let $R \in \mathcal{R}^N$. Begin from profile $R^{\alpha, \beta}$ and construct profile R^1 by changing agent 1's preferences to R_1^1 such that his peak

$$p(R_1^1) = \begin{cases} p(R_1^{\alpha, \beta}) & \text{if } p(R_1^{\alpha, \beta}) \leq \underline{p}(R) \\ \underline{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^1 = (R_{-1}^{\alpha, \beta}, R_1^1)$. Since $\underline{p}(R^1) \leq \alpha$ and $\bar{p}(R^1) = \beta$, as specified in Case 2 and by *extreme-peaks-onliness*, $\underline{p}(R^1) = \underline{F}(R^1)$. Since $p(R_1^{\alpha, \beta}) < \bar{F}(R^{\alpha, \beta})$ and $p(R_1^1) < \bar{F}(R^{\alpha, \beta})$, by *uncompromisingness*, maxima $\bar{F}(R^1) = \bar{F}(R^{\alpha, \beta}) = b$. Hence,

$F(R^1) = [\underline{p}(R^1), b]$. Then, change agent n 's preferences to R_n^2 such that his peak

$$p(R_n^2) = \begin{cases} p(R_n^1) & \text{if } p(R_n^1) \geq \bar{p}(R) \\ \bar{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^2 = (R_{-n}^1, R_n^2)$. Since $p(R_n^1) > \bar{F}(R^1)$ and $p(R_n^2) > \bar{F}(R^1)$, by *set-uncompromisingness*, $F(R^2) = F(R^1) = [\underline{p}(R^2), b]$. Since $F(R^2) = [\underline{p}(R^2), b] = [a, b] \cap \text{Conv}(R^2)$, by the definition of $F^{a,b}$, $F(R^2) = F^{a,b}(R^2)$. Since $F(R^2) = F^{a,b}(R^2)$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(R^2)$, by Lemma 2.11, $F(R) = F^{a,b}(R)$.

Case 2.2. There exist $\alpha, \beta \in \mathbb{R}$, as specified in Case 2 and in addition, $\alpha = \underline{F}(R^{\alpha,\beta}) = \bar{F}(R^{\alpha,\beta}) < \beta$, and for each $\bar{\alpha} \leq \alpha$ and its associated $R^{\bar{\alpha},\beta} \in \mathcal{R}^N$, $\bar{\alpha} = \underline{F}(R^{\bar{\alpha},\beta}) = \bar{F}(R^{\bar{\alpha},\beta}) < \beta$. Define points $a, b := -\infty$. Since $b < \underline{p}(R^{\alpha,\beta})$ and $F(R^{\alpha,\beta}) = \{\underline{p}(R^{\alpha,\beta})\}$, by the definition of $F^{a,b}$, $F(R^{\alpha,\beta}) = F^{a,b}(R^{\alpha,\beta})$. Let $R \in \mathcal{R}^N$. Begin from profile $R^{\alpha,\beta}$ and construct profile R^1 by changing agent 1's preferences to R_1^1 such that his peak

$$p(R_1^1) = \begin{cases} p(R_1^{\alpha,\beta}) & \text{if } p(R_1^{\alpha,\beta}) \leq \underline{p}(R) \\ \underline{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^1 = (R_{-1}^{\alpha,\beta}, R_1^1)$. Since $\underline{p}(R^1) \leq \alpha$ and $\bar{p}(R^1) = \beta$, as specified in this case and by *extreme-peaks-onliness*, $F(R^1) = \{\underline{p}(R^1)\}$. Then, change agent n 's preferences to R_n^2 such that his peak

$$p(R_n^2) = \begin{cases} p(R_n^1) & \text{if } p(R_n^1) \geq \bar{p}(R) \\ \bar{p}(R) & \text{otherwise,} \end{cases}$$

i.e., $R^2 = (R_{-n}^1, R_n^2)$. Since $p(R_n^1) > \bar{F}(R^1)$ and $p(R_n^2) > \bar{F}(R^1)$, by *set-uncompromisingness*, $F(R^2) = F(R^1) = \{\underline{p}(R^2)\}$. Since $b < \underline{p}(R^2)$, by the definition of $F^{a,b}$, $F(R^2) = F^{a,b}(R^2)$. Since $F(R^2) = F^{a,b}(R^2)$ and $\text{Conv}(p(R)) \subseteq \text{Conv}(R^2)$, by Lemma 2.11, $F(R) = F^{a,b}(R)$.

Case 3. There exist $\alpha, \beta \in \mathbb{R}$ such that for $R^{\alpha,\beta} \in \mathcal{R}^N$, $\alpha < \underline{F}(R^{\alpha,\beta}) \leq \bar{F}(R^{\alpha,\beta}) = \beta$, and for each $\bar{\beta} \geq \beta$ and its associated $R^{\alpha,\bar{\beta}} \in \mathcal{R}^N$, $\alpha < \underline{F}(R^{\alpha,\bar{\beta}}) \leq \bar{F}(R^{\alpha,\bar{\beta}}) = \bar{\beta}$. The proof of this case is symmetric to Case 2.

Case 4. For each $\alpha, \beta \in \mathbb{R}$ such that $\alpha \leq \beta$ and its associated $R^{\alpha,\beta} \in \mathcal{R}^N$, $\alpha = \underline{F}(R^{\alpha,\beta}) \leq \bar{F}(R^{\alpha,\beta}) = \beta$. Define points $a := -\infty$ and $b := \infty$. Since for each $\alpha, \beta \in \mathbb{R}$ and its associated $R^{\alpha,\beta} \in \mathcal{R}^N$, $\alpha = \underline{F}(R^{\alpha,\beta}) \leq \bar{F}(R^{\alpha,\beta}) = \beta$, by *extreme-peaks-onliness*, for each $R \in \mathcal{R}^N$, $F(R) = \text{Conv}(p(R))$. Therefore, since

$a < \underline{p}(R)$ and $b > \bar{p}(R)$, by the definition of $F^{a,b}$, $F(R) = F^{a,b}(R)$. \square

Chapter 3

On strategy-proofness and single-peakedness: median-voting over intervals

Abstract

We study *correspondences* that choose an interval of alternatives when agents have single-peaked preferences. Similar to Klaus and Storcken (2002), we ordinally extend these preferences over intervals. Loosely speaking, we extend the results of Moulin (1980) to our setting and show that the results of Ching (1997) cannot always be similarly extended. Our main results are the following. First, *strategy-proofness* and *peaks-onliness* characterize the class of generalized median correspondences. Second, we characterize the *anonymous* sub-class of generalized median correspondences, the class of median correspondences. Third, although *peaks-onliness* cannot be replaced by the “weaker” property of *continuity* in the aforementioned results -as is the case in Ching (1997)- this equivalence is achieved when *voter-sovereignty* is also required, in the characterizations of the classes of *efficient* generalized median correspondences and *efficient* median correspondences. Finally, when preferences are symmetric and single-peaked, only the characterizations for the classes of *efficient* generalized median correspondences and *efficient* median correspondences can be extended; moreover, in these results the properties of *peaks-onliness* and *continuity* are unnecessary.

3.1 Introduction

We study the problem where an interval of alternatives is chosen on the interval $[0, 1]$ based on the preferences of a finite number of agents. This interval can be considered as the political spectrum, while the chosen interval can in turn be considered as the legislative constitution or the governmental coalition (in the sense that some “extreme” views are not accounted for by the constitution or are not represented by any member(s) of the governmental coalition). We assume

that agents have *single-peaked preferences* defined over all alternatives on $[0, 1]$; that is, an agent's welfare is strictly increasing up to his "peak" (his favorite alternative), and is strictly decreasing thereafter. These agents, when comparing two intervals, only consider their best (most favorite) alternative and their worst (least favorite) alternative(s) on each interval. Moreover, we look into the situation where the voting mechanism choosing the interval of alternatives guarantees that the agents announce their true preferences; in other words, we are interested in voting mechanisms -which we call (choice) *correspondences*- that are *strategy-proof*.

Although the classic result of Gibbard and Satterthwaite establishes that on the full domain of preferences -with more than two alternatives available- *strategy-proofness* and *non-dictatorship* are incompatible (Gibbard, 1973; Satterthwaite, 1975), this is not true for the domain of single-peaked preferences, the domain of interest in this paper.

This compatibility between the two aforementioned properties has been well studied in the context of (choice) *functions* and for infinite sets of alternatives, where following the announcement of the agents' (single-peaked) preferences one alternative is chosen. Specifically, it has been shown that *strategy-proofness* and *peaks-onliness* (the agents only announce their peak) characterize the class of generalized median rules (described in Section 3.3.1) (Moulin, 1980). Moreover, when also requiring the property of either *efficiency* (in the Pareto sense), or *anonymity* (the names of the agents don't matter), or both to be satisfied, the sub-classes of either efficient generalized median rules (Section 3.3.1), or median rules (Section 3.3.2), or efficient median rules (Section 3.3.2) are characterized (Moulin, 1980). A similar result also holds for the one-dimensional case, when the range of the function is closed and not connected (Barberà and Jackson, 1994). In addition, on the smaller *domain of quadratic and separable preferences*¹ and on dimensions equal or larger to 1, *peaks-onliness* can be substituted by *unanimity* (when a common best alternative exists, it is chosen) (Border and Jordan, 1983); furthermore, it turns out that in these results two of the required properties can be weakened; specifically, *peak-onliness* and *efficiency* can be substituted by *continuity* (a small change in the announced preferences does not change the outcome a lot) and *voter-sovereignty* (no alternative is a priori excluded from being chosen) respectively (Ching, 1997).² Finally, a measure of manipulability was recently

¹In this domain, an agent's welfare depends on the distance of the alternative chosen from his peak, projected in every dimension. Specifically, the larger the sum of all such projected distances, the smaller the welfare gained.

²Although technically *continuity* is not weaker than *peaks-onliness*, loosely speaking, it imposes fewer restrictions on the result.

proposed, that can be used to compare two generalized median rules (via some necessary and sufficient conditions) (Arribillaga and Massó, 2016).

For the case where a single alternative is chosen among a finite set (of alternatives), *strategy-proofness* and *voter-sovereignty* characterize, on the domain of strict preferences, a class of functions similar to the class of efficient generalized median rules (Barberà et al., 1993). Moreover, the admissible preferences of all agents being *top-connected*³ characterize the maximal domain in which (i) every *strategy-proof* and *unanimous* function is a generalized median rule, and (ii) every generalized median rule is *strategy-proof* (Achuthankutty and Roy, 2017).

When departing from the setting where agents have single-peaked preferences and only one alternative is chosen, a few more results should be mentioned. First, in the case of *probabilistic functions*,⁴ where the agents' single-peaked preferences are ordinarily extended over probability distributions via first-order stochastic dominance, similar results to Moulin's results (1980) were achieved (Ehlers et al., 2002). Next, if agents have *single-dipped preferences*,⁵ *strategy-proofness* and *unanimity* characterize the class of *collections of 0-decisive sets with a tie-breaker*⁶ (Manjunath, 2014). Last but not least, we must mention the two following results where the agents' preferences are single-peaked and two alternatives can be chosen, with the agents comparing different pairs of alternatives using the *max-extension*.⁷

(i) *Strategy-proofness, continuity, anonymity, and users-only*⁸ characterize the class of *double median functions*⁹ (Heo, 2013).

(ii) *Efficiency and replacement-dominance*¹⁰ characterize the class of rules

³For every agent and every pair of "neighboring" alternatives (a, b) there exist admissible preferences such that a is the most favorite alternative and b is the second most favorite alternative.

⁴Given the agents' preferences, a probability distribution over all alternatives is chosen.

⁵An agent's welfare is strictly decreasing up to his "dip" (his least favorite alternative), and is strictly increasing thereafter.

⁶Each such function chooses either the minimum or the maximum alternative. Loosely speaking, if all agents are indifferent between the two alternatives the choice depends on the preference profile (over all other alternatives). Otherwise, the choice depends on the number of agents preferring the minimum over the maximum alternative, their identities, and their preferences.

⁷When comparing two pairs of alternatives $X = \{x_1, x_2\}$ and $Y = \{y_1, y_2\}$, an agent first locates in each pair the alternative he ranks higher, say x^* and y^* . If he prefers x^* to y^* , then he also prefers X to Y . If he is indifferent between x^* and y^* , then he is also indifferent between X and Y .

⁸For each pair of chosen alternatives (a, b) , the choice of a depends only on agents preferring a over b .

⁹A double median function can be decomposed into two median rules, where for each preference profile each one selects one alternative.

¹⁰If the preferences of an agent change, then the other agents should all be made at least as well off or they should all be made at most as well off. See page 36 for a formal definition.

comprised of the *left-peaks function* and the *right-peaks function*¹¹ Miyagawa (2001).

The above two results are -loosely speaking- similar to the results of this paper; in Section 3.5.5 we discuss them and compare them with the results of this paper.

In line with most of the related literature, our main results also make use of either the property of *peaks-onliness* or a version of *continuity* adapted for our context (i.e., where an interval of alternatives is chosen). In addition, we also study the sub-cases where correspondences are either *efficient*, or *anonymous*, or both. Concisely, our results are the following. First, in the domain of single-peaked preferences, *strategy-proofness* and *peaks-onliness* characterize the class of generalized median correspondences (Theorem 3.1); and if *anonymity* is also required, then the sub-class of median correspondences is characterized (Theorem 3.2). Second, neither of these results holds in the domain of symmetric and single-peaked preferences, nor can in these results *continuity* substitute *peaks-onliness* (the counter-example on page 84). Third, in the domain of single-peaked preferences, *strategy-proofness*, *voter-sovereignty*, and either *peaks-onliness* or *continuity* characterize the class of efficient generalized median correspondences (Theorem 3.3); and if *anonymity* is also required, then the sub-class of efficient median correspondences is characterized (Theorem 3.4). Finally, in the domain of symmetric and single-peaked preferences, the classes of efficient generalized median correspondences and efficient median correspondences can be similarly characterized with one difference; due to *peaks-onliness* being inherent in the domain, *continuity* plays no role.

The chapter proceeds as follows. Section 3.2 explains the model and states a preliminary result. Section 3.3 includes the definitions of choice functions and correspondences, as well as the definition of the classes of such functions and correspondence we characterize. Section 3.4 contains the properties we are interested in and some further preliminary results. Finally, Section 3.5 contains all main results and characterizations, as well as a table summarizing our results.

3.2 The model

Consider a *coalition* (of agents) $N \equiv \{1, \dots, n\}$, such that $n \geq 2$, and a set of *alternatives* $A \equiv [0, 1]$.¹² We denote generic agents by i and j , and generic

¹¹The left (right) peaks function chooses the two unique left-most (right-most) peaks.

¹²The set of alternatives is chosen without loss of generality. Essentially, our results hold for any closed interval in \mathbb{R} .

alternatives by x and y . Each i is equipped with preferences R_i , defined over A , that are *complete*, *transitive*, and *reflexive*. As usual, $x R_i y$ is interpreted as “ x is at least as desirable as y ”, $x P_i y$ as “ x is preferred to y ”, and $x I_i y$ as “ x is indifferent to y ”. Moreover, for preferences R_i there exists an alternative $p_i \in A$, called the *peak* of i , with the following property: if either $y < x \leq p_i$ or $y > x \geq p_i$, we have $x P_i y$. We call such preferences *single-peaked* and denote the *domain of single-peaked preferences* by \mathcal{R} . Furthermore, if for preferences $R_i \in \mathcal{R}$, $|x - p_i| = |y - p_i|$ implies $x I_i y$, then we say these preferences are *symmetric* and denote the *domain of symmetric preferences* by \mathcal{S} .

In the sequel, all notation and definitions refer to domain \mathcal{R} but also apply to domain \mathcal{S} . Moreover, all results presented in this section hold in both domains.

Let \mathcal{R}^N be the set of profiles $R \equiv (R_i)_{i \in N}$ such that for each $i \in N$, $R_i \in \mathcal{R}$. Given $R \in \mathcal{R}^N$ and $j \in N$, we also use R and (R_{-j}, R_j) interchangeably. For each $R \in \mathcal{R}^N$, we denote the *vector of peaks* of R by $p \equiv (p_i)_{i \in N}$. Let the *smallest peak* in R be $\underline{p} \equiv \min(\{p_i\}_{i \in N})$ and the *largest peak* in R be $\bar{p} \equiv \max(\{p_i\}_{i \in N})$. Finally, let the *convex hull* of peaks in R be $\text{Conv}(p) \equiv [\underline{p}, \bar{p}]$.

Let the class of closed intervals in A be denoted by \mathcal{A} . We denote generic sets in \mathcal{A} by X and Y . We denote the *minimum* of X by $\underline{X} \equiv \min(X)$ and the *maximum* of X by $\bar{X} \equiv \max(X)$. For each $R_i \in \mathcal{R}$, we denote the *best alternative(s)* of i in X by $b_{R_i}(X) \equiv \{x \in X : \text{for each } y \in X, x R_i y\}$ and the *worst alternative(s)* of i in X by $w_{R_i}(X) \equiv \{x \in X : \text{for each } y \in X, y R_i x\}$. Note that single-peakedness of R_i and non-emptiness of X imply that the sets $b_{R_i}(X)$ and $w_{R_i}(X)$ contain one or two elements; specifically, if $b_{R_i}(X)$ (respectively, $w_{R_i}(X)$) contains two elements, agent i is indifferent between them. It is with some abuse of notation that we treat sets $b_{R_i}(X)$ and $w_{R_i}(X)$ as if they are points and for each $x \in X$, we write $b_{R_i}(X) R_i x R_i w_{R_i}(X)$.

We extend all preferences $R_i \in \mathcal{R}$, defined over A , to preferences defined over \mathcal{A} according to the “best-worst” extension of preferences characterized by Barberà et al. (1984).¹³ Specifically, when comparing two sets, an agent only considers his best and his worst point(s) in each of them. Therefore, an agent prefers X to Y if he prefers his best point(s) in X to his best point(s) in Y and his worst point(s) in X to his worst point(s) in Y . The following definition also covers three more cases arising when an agent is indifferent between his best or worst point(s) in the

¹³Preferences R_i^A defined over \mathcal{A} satisfy *weak-dominance* ($x P_i^A y$ implies $\{x\} P_i^A \{x, y\} P_i^A \{y\}$) and *weak-independence* (given triple $X, Y, Z \in \mathcal{A}$ such that $[X \cap Z] = [Y \cap Z] = \emptyset$, $X P_i^A Y$ implies $[X \cup Z] R_i^A [Y \cup Z]$) if and only if i compares sets in \mathcal{A} according to the “best-worst” extension of preferences. Examples illustrating the reasoning behind requiring these properties (in a slightly different model) are provided in Klaus and Protopapas (2016).

two sets.

With some abuse of notation, we use the same symbols to denote preferences over alternatives and preferences over sets of alternatives.

Best-worst extension of preferences. For each $i \in N$ with preferences $R_i \in \mathcal{R}$, and each pair $X, Y \in \mathcal{A}$,

$$X R_i Y \text{ if and only if } \begin{cases} b_{R_i}(X) R_i b_{R_i}(Y) \\ \text{and} \\ w_{R_i}(X) R_i w_{R_i}(Y). \end{cases}$$

and

$$X P_i Y \text{ if and only if } X R_i Y \text{ and } \begin{cases} b_{R_i}(X) P_i b_{R_i}(Y) \\ \text{or} \\ w_{R_i}(X) P_i w_{R_i}(Y). \end{cases}$$

This extension of preferences is *transitive*: for each triple $X, Y, Z \in \mathcal{A}$, if $X R_i Y$ and $Y R_i Z$, then $X R_i Z$. However, it is not *complete*: there exist $X, Y \in \mathcal{A}$ such that neither $X R_i Y$ nor $Y R_i X$. To be precise, we now introduce the following definition.

Comparability. Given preferences $R_i \in \mathcal{R}$, sets $X, Y \in \mathcal{A}$ are comparable if and only if $[b_{R_i}(X) P_i b_{R_i}(Y) \text{ implies } w_{R_i}(X) R_i w_{R_i}(Y)]$ and $[w_{R_i}(X) P_i w_{R_i}(Y) \text{ implies } b_{R_i}(X) R_i b_{R_i}(Y)]$.

Based on the best-worst extension of preferences, we now define (Pareto) *efficient sets*.

Efficient sets. Given profile $R \in \mathcal{R}^N$, set $X \in \mathcal{A}$ is efficient if and only if there is no set $Y \in \mathcal{A}$ such that for each $i \in N$, $Y R_i X$, and for at least one $j \in N$, $Y P_j X$; we denote the class containing all efficient sets at R by $E(R)$.

We now present a characterization of efficient sets in this setting that follows from Klaus and Protopapas (2016). Note that the original result is a little more complicated since it holds for all compact sets.

Proposition 3.1 (Klaus and Protopapas (2016)). At profile $R \in \mathcal{R}^N$, a closed interval is efficient if and only if it is a subset of the convex hull of peaks in R .

3.3 Choice functions and correspondences

In the sequel, all notation and definitions refer to domain \mathcal{R} but also apply to domain \mathcal{S} . Moreover, all results presented in this section hold in both domains.

Each $i \in N$, announces preferences $V_i \in \mathcal{R}$ with associated *announced peak* $v_i \in A$. Given (true) profile $R \in \mathcal{R}^N$, if $V_i = R_i$, we say that i is *sincere*; otherwise, if $V_i \neq R_i$, we say that i *deviates*. All terminology, notation, and results of Section 3.2, defined for preferences $R_i \in \mathcal{R}$, are carried over to announced preferences $V_i \in \mathcal{R}$ by replacing R and p by V and v respectively, and adding the term “announced” as necessary. For example, since in profile $R \in \mathcal{R}^N$ the smallest peak is denoted by $\underline{p} \equiv \min(\{p_i\}_{i \in N})$, in *announced profile* $V_N \in \mathcal{R}^N$ the *smallest announced peak* is denoted by $\underline{v} \equiv \min(\{v_i\}_{i \in N})$.

A (*choice*) *correspondence* F assigns to each $V \in \mathcal{R}^N$ a set $F(V) \in \mathcal{A}$, i.e., $F: \mathcal{R}^N \rightarrow \mathcal{A}$. Given $V \in \mathcal{R}^N$, let the *minimum* of $F(V)$ be $\underline{F}(V) \equiv \min\{F(V)\}$ and the *maximum* of $F(V)$ be $\bar{F}(V) \equiv \max\{F(V)\}$. We denote the family of correspondences by \mathcal{F} . Moreover, if a correspondence $F \in \mathcal{F}$ assigns to each $V \in \mathcal{R}^N$ an interval consisting of a single point we will refer to it as a *function* and use notation $f \in \mathcal{F}$, i.e., $f: \mathcal{R}^N \rightarrow A$.

Before defining in Sections 3.3.1 and 3.3.2 two classes of functions and correspondences that our results revolve around, the following definition is necessary: for each odd and positive integer k , and each vector $T \in \mathbb{R}^k$, label the coordinates of T such that $t_1 \leq \dots \leq t_k$; we define the *median* (coordinate) of T by $\text{med}(T) \equiv t_{\frac{k+1}{2}}$

Finally, we (would like the reader to notice) that the classes of generalized median rules and correspondences, defined in Section 3.3.1, are as the name suggests, a generalization of the classes of median rules and correspondences, defined in Section 3.3.2. Loosely speaking, this generalization boils down to the agents influencing the chosen interval non-symmetrically. This is discussed in Remark 3.3 (Section 3.3.2). The reason behind this sequencing is simple: our results for the classes of generalized median rules and correspondences can be easily shown to hold for the subclasses of median rules and correspondences respectively.

3.3.1 Generalized median rules and correspondences

The first class of functions we consider was introduced under the name *strategy-proof voting schemes* and characterized by *strategy-proofness*¹⁴ and *peaks-*

¹⁴No agent gains by deviating.

*onliness*¹⁵ (Moulin, 1980, Proposition 3). It was later shown that *peaks-onliness* can be substituted with the “weaker” property of *continuity*¹⁶ (Ching, 1997, Theorem). In order to provide a useful intuition in understanding this class, we present an example inspired by the one provided in Arribillaga and Massó (2016, p. 564).

Example 3.1. Consider the two agent case, i.e., $N = \{1, 2\}$ and choose a 4-dimensional vector $\alpha = (\alpha_\emptyset, \alpha_{\{1\}}, \alpha_{\{2\}}, \alpha_N)$ such that $\alpha_N \leq \alpha_{\{1\}} \leq \alpha_{\{2\}} \leq \alpha_\emptyset$. Next, define the function $f^\alpha \in \mathcal{F}$ as follows. For each $V \in \mathcal{R}^N$, if $v_1 \leq v_2$, choose $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{1\}}, \alpha_N)$ and set $f^\alpha(V) = \text{med}(\tilde{\alpha}_v, v)$, and if $v_1 > v_2$, choose $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{2\}}, \alpha_N)$ and set $f^\alpha(V) = \text{med}(\tilde{\alpha}_v, v)$.

Notice that if $\alpha_{\{1\}} \neq \alpha_{\{2\}}$, then the agents have asymmetric power in influencing the chosen alternative. Before discussing further this asymmetry, in an effort to shed more light on the behavior of f^α , we first provide a second definition of it.

$$\text{For each } V \in \mathcal{R}^N, f^\alpha(V) = \begin{cases} \alpha_N & \text{if } v_1, v_2 \leq \alpha_N \\ v_2 & \text{if } v_1 \leq \alpha_N \leq v_2 \leq \alpha_{\{1\}} \\ \alpha_{\{1\}} & \text{if } v_1 \leq \alpha_N \leq \alpha_{\{1\}} \leq v_2 \\ \text{med}(v_1, v_2, \alpha_{\{1\}}) & \text{if } \alpha_N \leq v_1 \leq \alpha_{\{1\}} \\ v_1 & \text{if } \alpha_{\{1\}} \leq v_1 \leq \alpha_{\{2\}} \\ \text{med}(v_1, v_2, \alpha_{\{2\}}) & \text{if } \alpha_{\{2\}} \leq v_1 \leq \alpha_\emptyset \\ \alpha_{\{2\}} & \text{if } v_2 \leq \alpha_{\{2\}} \leq \alpha_\emptyset \leq v_1 \\ v_2 & \text{if } \alpha_{\{2\}} \leq v_2 \leq \alpha_\emptyset \leq v_1, \text{ and} \\ \alpha_\emptyset & \text{if } \alpha_\emptyset \leq v_1, v_2. \end{cases}$$

It is easy to see from this second definition that the range of f^α equals $[\alpha_N, \alpha_\emptyset]$. Hence, this function can be interpreted as one assigning to agents 1 and 2 the power to choose an alternative from the interval $[\alpha_N, \alpha_\emptyset]$. Furthermore, as already briefly discussed, this power is not symmetric among the agents but depends on the choice of $\alpha_{\{1\}}$ and $\alpha_{\{2\}}$. For instance in this example, since $\alpha_{\{1\}} \leq \alpha_{\{2\}}$, agent 1 has a greater power than agent 2 in influencing the chosen alternative. To see this, first consider agent 1. He can make sure that the chosen alternative is not larger than $\alpha_{\{1\}}$ and not smaller than v_1 (by announcing $v_1 \leq \alpha_{\{1\}}$), or that it is not larger than v_1 and not smaller than $\alpha_{\{1\}}$ (by announcing $v_1 \geq \alpha_{\{1\}}$). In

¹⁵The chosen alternative only depends on the vector of announced peaks.

¹⁶If the announced preferences change a “little”, the chosen alternative does not change “a lot”.

addition, he is a dictator on the interval $[\alpha_{\{1\}}, \alpha_{\{2\}}]$.

Next, consider agent 2. He only has the power to influence the chosen alternative if agent 1 “allows” him to do so. That is, if $\alpha_N \leq v_1 \leq \alpha_{\{1\}}$, then agent 2 can pinpoint the chosen alternative on the interval $[v_1, \alpha_{\{1\}}]$, and if $v_1 \leq \alpha_N \leq \alpha_{\{1\}}$, then agent 2 can pinpoint the chosen alternative on the interval $[\alpha_N, \alpha_{\{1\}}]$. Similarly, if $\alpha_{\{2\}} \leq v_1 \leq \alpha_\emptyset$, then agent 2 can pinpoint the chosen alternative on the interval $[\alpha_{\{2\}}, v_1]$, and if $\alpha_{\{2\}} \leq \alpha_\emptyset \leq v_1$, then agent 2 can pinpoint the chosen alternative on the interval $[\alpha_{\{2\}}, \alpha_\emptyset]$.

The general n -agent case works as follows. First, take a vector α in A^{2^n} , i.e., the dimension of α equals the number of all sub-coalitions in N (including the empty set). Specifically, let $\alpha \equiv (\alpha_M)_{M \subseteq N}$, such that for each $L \subseteq M$, $\alpha_L \geq \alpha_M$. Next, for an announced profile V with associated vector of announced peaks v , label the agents such that $v_{\bar{1}} \leq \dots \leq v_{\bar{n}}$.¹⁷ Finally, construct vector $\tilde{\alpha}_v$ in A^{n+1} such that $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{\bar{1}\}}, \alpha_{\{\bar{1}, \bar{2}\}}, \dots, \alpha_N)$ and notice that by construction, $\alpha_N \leq \dots \leq \alpha_{\{\bar{1}, \bar{2}\}} \leq \alpha_{\{\bar{1}\}} \leq \alpha_\emptyset$. The *generalized median rule* associated with vector α chooses alternative $\text{med}(v, \tilde{\alpha}_v)$.

Generalized median rules. Let vector $\alpha \in A^{2^n}$ be such that $\alpha \equiv (\alpha_M)_{M \subseteq N}$, where for each pair $L, M \subseteq N$ with $L \subsetneq M$, $\alpha_L \geq \alpha_M$. Also, for each $V \in \mathcal{R}^N$, let bijection $\pi: N \rightarrow N$ be such that $v_{\pi(1)} \leq \dots \leq v_{\pi(n)}$ and construct vector $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{\pi(1)\}}, \alpha_{\{\pi(1), \pi(2)\}}, \dots, \alpha_N)$. We denote the *generalized median rule* associated with vector α by f_G^α , where for each $V \in \mathcal{R}^N$, $f_G^\alpha(V) \equiv \text{med}(v, \tilde{\alpha}_v)$. Finally, we denote the class of *generalized median rules* by \mathcal{f}_G .¹⁸

Clearly, if all agents announce different peaks, a unique ordering of them by their announced peak exists. Moreover, for the case where some agents announce the same peak and hence such a unique ordering does not exist, the chosen alternative does not depend on the particular ordering chosen; as shown in Ching (1997, Remark 1).

The first class of correspondences we characterize in Section 3.5 extends the spirit of generalized median rules to correspondences. Specifically, take two vectors $\alpha \leq \beta$, each of dimension 2^n , such that $\alpha \equiv (\alpha_M)_{M \subseteq N}$ and $\beta \equiv (\beta_M)_{M \subseteq N}$. Next, for an announced profile V with associated vector of announced peaks v , label the

¹⁷Whenever two agents announce the same peak, no unique way to label the agents exists. However, the specific choice of labels does not affect the chosen alternative (Ching, 1997, Remark 1).

¹⁸It should be noted that in the literature a generalized median rule $f_G^\alpha \in \mathcal{f}_G$ is often described as follows: For each $V \in \mathcal{R}^N$, $f_G^\alpha(V) = \min_{M \subseteq N} \max_{i \in M} \{v_i, \alpha_M\}$.

agents such that $v_1 \leq \dots \leq v_n$ and construct vectors $\tilde{\alpha}_v$ and $\tilde{\beta}_v$, each of dimension $n + 1$, such that $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{1\}}, \alpha_{\{1,2\}}, \dots, \alpha_N)$ and $\tilde{\beta}_v = (\beta_\emptyset, \beta_{\{1\}}, \beta_{\{1,2\}}, \dots, \beta_N)$. The *generalized median correspondence* associated with vectors α and β chooses the interval where the minimum alternative is $\text{med}(v, \tilde{\alpha}_v)$ and the maximum alternative is $\text{med}(v, \tilde{\beta}_v)$.

Generalized median correspondences. Let vectors $\alpha, \beta \in A^{2^n}$ be such that $\alpha \equiv (\alpha_M)_{M \subseteq N}$ and $\beta \equiv (\beta_M)_{M \subseteq N}$, with $\alpha \leq \beta$, and for each pair $L, M \subseteq N$, with $L \subsetneq M$, $\alpha_L \geq \alpha_M$ and $\beta_L \geq \beta_M$. Also, for each $V \in \mathcal{R}^N$, let bijection $\pi: N \rightarrow N$ such that $v_{\pi(1)} \leq \dots \leq v_{\pi(n)}$ and construct vectors $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{\pi(1)\}}, \alpha_{\{\pi(1), \pi(2)\}}, \dots, \alpha_N)$ and $\tilde{\beta}_v = (\beta_\emptyset, \beta_{\{\pi(1)\}}, \beta_{\{\pi(1), \pi(2)\}}, \dots, \beta_N)$. We denote the *generalized median correspondence* associated with vectors α and β by $F_G^{\alpha, \beta}$, where for each $V \in \mathcal{R}^N$, $F_G^{\alpha, \beta}(V) \equiv [\text{med}(v, \tilde{\alpha}_v), \text{med}(v, \tilde{\beta}_v)]$. Finally, we denote the class of *generalized median correspondences* by \mathcal{F}_G .

Remark 3.1. By definition of \mathcal{F}_G and \mathcal{I}_G , for each profile V , $F_G^{\alpha, \beta}(V) \equiv [\text{med}(v, \tilde{\alpha}_v), \text{med}(v, \tilde{\beta}_v)] = [f_G^\alpha(V), f_G^\beta(V)]$. Therefore, a *generalized median correspondence* $F_G^{\alpha, \beta}$ can be decomposed into two *generalized median rules* f_G^α and f_G^β .

The next result considers *single-valued* *generalized median correspondences*.

Lemma 3.1. A *generalized median correspondence* $F_G^{\alpha, \beta}$ is *single-valued* if and only if $\alpha = \beta$. Moreover, in this case $F_G^{\alpha, \beta}$ is essentially a *generalized median rule*.¹⁹

Proof. Let $F_G^{\alpha, \beta} \in \mathcal{F}_G$ and $f_G^\alpha, f_G^\beta \in \mathcal{I}_G$. Let $V \in \mathcal{R}^N$. By Remark 3.1, $F_G^{\alpha, \beta}(V) = [f_G^\alpha(V), f_G^\beta(V)]$. If $\alpha = \beta$, then $F_G^{\alpha, \beta}(V) = \{f_G^\alpha(V)\}$. Hence, $F_G^{\alpha, \beta}$ is *single-valued*.

If $F_G^{\alpha, \beta}$ is *single-valued*, then $F_G^{\alpha, \beta}(V) = [f_G^\alpha(V), f_G^\beta(V)]$ implies $f_G^\alpha(V) = f_G^\beta(V)$. Assuming $\alpha \neq \beta$ results in a contradiction as follows. Since $\alpha \neq \beta$, there exists a coalition $M \subseteq N$ such that $\alpha_M \neq \beta_M$. Let $|M| = m$ and specify V such that for each agent $i \in M$, $v_i = 0$, and for each agent $j \in N \setminus M$, $v_j = 1$. Hence, at profile V , the m th coordinate of vectors $\tilde{\alpha}_v$ and $\tilde{\beta}_v$ will be α_M and β_M respectively. Moreover, by definition of \mathcal{F}_G , $\alpha_N \leq \alpha_{\{1, \dots, n-1\}} \leq \dots \leq \alpha_{\{1\}} \leq \alpha_\emptyset$ and $\beta_N \leq \beta_{\{1, \dots, n-1\}} \leq \dots \leq \beta_{\{1\}} \leq \beta_\emptyset$. Thus, there are at least $n + 1 - m$ coordinates of $\tilde{\alpha}_v$ not larger than α_M (i.e., coordinates $\alpha_M, \dots, \alpha_N$) and at least $m + 1$ coordinates of $\tilde{\alpha}_v$ not smaller than α_M (i.e., coordinates $\alpha_\emptyset, \dots, \alpha_M$). Similarly, there are at least

¹⁹To be precise, a *single-valued* *generalized median correspondence* assigns singleton sets of alternatives while the corresponding *generalized median rule* assigns the alternatives contained in these sets.

$n + 1 - m$ coordinates of $\tilde{\beta}_v$ not larger than β_M and at least $m + 1$ coordinates of $\tilde{\beta}_v$ not smaller than β_M . Hence, $F_G^{\alpha,\beta} = [\text{med}(v, \tilde{\alpha}_v), \text{med}(v, \tilde{\beta}_v)] = [\alpha_M, \beta_M]$ contradicting that $F_G^{\alpha,\beta}$ is *single-valued*. Therefore, $F_G^{\alpha,\beta}(V)$ being single-valued implies $\alpha = \beta$. \square

Our results in Section 3.5 will also concern *efficient generalized median correspondences*. Formally, given $F_G^{\alpha,\beta} \in \mathcal{F}_G$, if for each $V \in \mathcal{R}^N$, $F_G^{\alpha,\beta} \in E(V)$, we say that $F_G^{\alpha,\beta}$ is an *efficient generalized median correspondence* and denote the *class of efficient generalized median correspondences* by \mathcal{F}_{EG} . The next result concerns this class of correspondences.

Lemma 3.2. *A generalized median correspondence $F_G^{\alpha,\beta}$ is an efficient generalized median correspondence if and only if vectors α, β are such that $\alpha_N = \beta_N = 0$ and $\alpha_\emptyset = \beta_\emptyset = 1$.*

Proof. Let $F_G^{\alpha,\beta} \in \mathcal{F}_G$. Assuming that $F_G^{\alpha,\beta} \in \mathcal{F}_{EG}$ such that α, β are not as described above, results in a contradiction as follows.

If $\alpha_N \neq 0$ or $\beta_N \neq 0$, choose $V \in \mathcal{R}^N$ such that $v = (0, \dots, 0)$. By Proposition 3.1, $E(V) = \{0\}$ and by the definition of \mathcal{F}_G , $F_G^{\alpha,\beta}(V) = [\alpha_N, \beta_N]$. Hence, $F_G^{\alpha,\beta}(V) \notin E(V)$. Similarly, if $\alpha_\emptyset \neq 1$ or $\beta_\emptyset \neq 1$, choose $V \in \mathcal{R}^N$ such that $v = (1, \dots, 1)$. Again, by Proposition 3.1, $E(V) = \{1\}$ and by the definition of \mathcal{F}_G , $F_G^{\alpha,\beta}(V) = [\alpha_\emptyset, \beta_\emptyset]$. Hence, $F_G^{\alpha,\beta}(V) \notin E(V)$.

Finally, if $\alpha_N = \beta_N = 0$ and $\alpha_\emptyset = \beta_\emptyset = 1$, then for each $V \in \mathcal{R}^N$, $\text{med}(v, \tilde{\alpha}_v) \in \text{Conv}(v)$ and $\text{med}(v, \tilde{\beta}_v) \in \text{Conv}(v)$. Hence, by the definition of \mathcal{F}_G , $F_G^{\alpha,\beta}(V) \subseteq \text{Conv}(v)$, and thus by Proposition 3.1, $F_G^{\alpha,\beta}(V) \in E(V)$. \square

3.3.2 Median rules and correspondences

The second class of functions we consider was introduced under the name *strategy-proof and anonymous voting schemes* and characterized by *strategy-proofness*, *peaks-onliness*, and *anonymity*²⁰ (Moulin, 1980, Proposition 2). As discussed in Remark 3.3, this class of functions is a subclass of generalized median rules since now all agents possess the same power in influencing the chosen alternative. For the 2-agent case, it suffices to set $\alpha_{\{1\}} = \alpha_{\{2\}}$ in Example 3.1 (page 74).

The general n -agent case works as follows. Take a vector a in A^{n+1} . For an announced profile V with associated vector of announced peaks v , the *median rule* associated with a chooses alternative $\text{med}(v, a)$.

²⁰The names of the agents do not affect the chosen alternative.

Median rules. Let vector $a \in A^{n+1}$ be such that $a \equiv (a_1, \dots, a_{n+1})$, where $a_1 \leq \dots \leq a_{n+1}$. We denote the median rule associated with vector a by f_M^a , where for each $V \in \mathcal{R}^N$, $f_M^a(V) \equiv \text{med}(v, a)$. Finally, we denote the class of median rules by \mathcal{F}_M .

The second class of correspondences we characterize in Section 3.5 extends the spirit of median rules to correspondences. Specifically, take two vectors $a \leq b$, each of dimension $n + 1$. For an announced profile V with associated vector of announced peaks v , the *median correspondence* associated with a and b chooses the interval where the minimum alternative is $\text{med}(v, a)$ and the maximum alternative is $\text{med}(v, b)$.

Median correspondences. Let vectors $a, b \in A^{n+1}$ be such that $a \equiv (a_1, \dots, a_{n+1})$ and $b \equiv (b_1, \dots, b_{n+1})$, with $a \leq b$, $a_1 \leq \dots \leq a_{n+1}$, and $b_1 \leq \dots \leq b_{n+1}$. We denote the median correspondence associated with vectors a and b by $F_M^{a,b}$, where for each $V \in \mathcal{R}^N$, $F_M^{a,b}(V) \equiv [\text{med}(v, a), \text{med}(v, b)]$. Finally, we denote the class of median correspondences by \mathcal{F}_M .

Remark 3.2. By definition of \mathcal{F}_M and \mathcal{F}_M , for each profile V , $F_M^{a,b}(V) \equiv [\text{med}(v, a), \text{med}(v, b)] = [f_M^a(V), f_M^b(V)]$. Therefore, a median correspondence $F_M^{a,b}$ can be decomposed into two median rules f_M^a and f_M^b .

Remark 3.3. The class of median rules (correspondences) is a subclass of the class of generalized median rules (correspondences). That is, given $F_M^{a,b} \in \mathcal{F}_M$, let $F_G^{\alpha,\beta} \in \mathcal{F}_G$ by choosing vectors $\alpha, \beta \in A^{2^n}$ such that the weight of each coalition only depends on its cardinality. Specifically, for each $M \subseteq N$, choose $\alpha_M = a_{n+1-|M|}$ (i.e., choose $\alpha_\emptyset = a_{n+1}$, for each $i \in N$, choose $\alpha_{\{i\}} = a_n$, for each $i, j \in N$ with $i \neq j$, choose $\alpha_{\{i,j\}} = a_{n-1}$, and so on) and $\beta_M = b_{n+1-|M|}$. It follows that for each $V \in \mathcal{R}^N$, $\tilde{\alpha}_v = a$ and $\tilde{\beta}_v = b$, implying $F_M^{a,b}(V) = F_G^{\alpha,\beta}(V)$.

The next result considers single-valued median correspondences.

Lemma 3.3. A median correspondence $F_M^{a,b}$ is single-valued if and only if $a = b$. Moreover, in this case $F_M^{a,b}$ is essentially a median rule.²¹

Lemma 3.3 follows from Lemma 3.1 and Remark 3.3.

Our results in Section 3.5 also concern *efficient median correspondences*. Formally, given $F_M^{a,b} \in \mathcal{F}_M$, if for each $V \in \mathcal{R}^N$, $F_M^{a,b} \in E(V)$, we say that $F_M^{a,b}$ is an *efficient median correspondence* and denote the *class of efficient median correspondences* by \mathcal{F}_{EM} . The next result concerns this class of correspondences.

²¹To be precise, a single-valued median correspondence assigns singleton sets of alternatives while the corresponding median rule assigns the alternatives contained in these sets.

Lemma 3.4. *A median correspondence $F_M^{a,b}$ is an efficient median correspondence if and only if vectors a, b are such that $a_1 = b_1 = 0$ and $a_{n+1} = b_{n+1} = 1$.*

Lemma 3.4 follows from Lemma 3.2 and Remark 3.3.

Remark 3.4. As discussed in Section 3.5, both classes of generalized median correspondences and median correspondences are *strategy-proof*²², similar to the results on functions by Moulin (1980). However, it should be noted that in contrast to Moulin's results these classes of correspondences are not *group strategy-proof*.²³ The following example illustrates this.

Example 3.2. Let $N = \{1, 2, 3\}$ and $F^{a,b} \in \mathcal{F}_{EM}$ such that $a = \{0, 0, 0, 1\}$ and $b = \{0, 0, 1, 1\}$. In addition, let $V, V' \in \mathcal{S}$ be such that $v_1 = v'_1 = 0$, $v_2 = 0.5$, $v'_2 = 0.6$, and $v_3 = v'_3 = 1$. Then, $F(V) = [0, 0.5]$ and $F(V') = [0, 0.6]$. Therefore, assuming V are the true preferences of the agents implies that although agent 2 is indifferent to deviating, by announcing V'_2 , agent 3 gains by this deviation.

3.4 Properties of correspondences

In the sequel, all properties are defined for correspondences in domain \mathcal{R} but also apply to correspondences in domain \mathcal{S} . Moreover, all results presented in this section hold in both domains.

The first two properties we consider are related; the first is our *efficiency* notion for correspondences while the second, being weaker than the first, requires no alternative in A to be a priori excluded from being selected.

Efficiency. *For each $V \in \mathcal{R}^N$, $F(V) \in E(V)$.*

Voter-sovereignty. *For each $x \in A$, there exists $V \in \mathcal{R}^N$ such that $F(V) = \{x\}$.*

The next property, which is central in our results, requires no agent to gain by deviating. Moreover, it implies *comparability* between the chosen sets before and after an agent's deviation.

Strategy-proofness. *For each $i \in N$, each $R_i \in \mathcal{R}$, and each $V \in \mathcal{R}^N$, $F(V_{-i}, R_i) R_i F(V_{-i}, V_i)$.*

The next property requires the chosen set to depend only on the vector of announced peaks.

²²No agent gains by deviating. See Section 3.5.1 for a formal proof.

²³No group of agents can deviate such that some members of the group gain and no member of the group loses.

Peaks-onliness. For each pair $V, V' \in \mathcal{R}^N$ such that $v = v'$, $F(V) = F(V')$.

Loosely speaking, the next property requires when the announced preferences of an agent change “a little”, the minimum and maximum alternatives chosen to not change “a lot”. Before describing it formally, we must first define the three following notions. First, the “indifference relation”, which -loosely speaking- given preferences $V_i \in \mathcal{R}$, maps each alternative x to an alternative y , that i finds indifferent to x , according to V_i . Formally, for each $V_i \in \mathcal{R}$, the *indifference relation* $r_{V_i}: [0, 1] \rightarrow [0, 1]$ is defined as follows. For each $x \in [0, v_i]$, $r_{V_i}(x) = y$ if $y \in [v_i, 1]$ exists such that $y I_i x$, or $r_{V_i}(x) = 1$ otherwise; while for each $x \in [v_i, 1]$, $r_{V_i}(x) = y$ if $y \in [0, v_i]$ exists such that $y I_i x$, or $r_{V_i}(x) = 0$ otherwise. Second, the distance between a pair $V_i, V'_i \in \mathcal{R}$, which is measured using the indifference relation. Formally, it is defined to be $d(V_i, V'_i) \equiv \max_{x \in [0, 1]} |r_{V_i}(x) - r_{V'_i}(x)|$. Finally, the notion of convergence. Specifically, for $k \in \mathbb{N}^+$, a sequence $\{V_i^k\}$ in \mathcal{R} converges to V_i , if $k \rightarrow \infty$ implies the distance $d(V_i, V_i^k) \rightarrow 0$. We denote this convergence by $V_i^k \rightarrow V_i$.

Min/max continuity. For each $V \in \mathcal{R}^N$, each $i \in N$, and each $\{V_i^k\}$ in \mathcal{R} ,

$$\text{if } V_i^k \rightarrow V_i, \text{ then } \begin{cases} \underline{F}(V_{-i}, V_i^k) \rightarrow \underline{F}(V), \text{ and} \\ \bar{F}(V_{-i}, V_i^k) \rightarrow \bar{F}(V). \end{cases}$$

Notice that *min/max continuity* for functions is equivalent to the regular *continuity* property for functions (with respect to the preference profile). Moreover, in Appendix 3.A we show the equivalence of this property with the standard continuity properties for correspondences, *upper-hemi continuity* and *lower-hemi continuity*.

The next property requires that the agents' identities do not matter.

Anonymity. For each bijection $\sigma: N \rightarrow N$ and each pair $V, V' \in \mathcal{R}^N$ such that for each $i \in N$, $V_i = V'_{\sigma(i)}$, $F(V) = F(V')$.

The last property we consider depends only on the announced peaks of the agents. Loosely speaking, following a change in an agent's announced preferences, if before and after this change both announced peaks lie on the same side of the minimum (maximum) chosen alternative, then the minimum (maximum) chosen alternative does not change.

Uncompromisingness. For each $i \in N$ and each pair $V, V' \in \mathcal{R}^N$ such that

$$V'_{-i} = V_{-i},$$

$$\begin{aligned} \text{if } & \begin{cases} v_i < \underline{F}(V) \text{ and } v'_i \leq \underline{F}(V) \text{ or} \\ v_i > \underline{F}(V) \text{ and } v'_i \geq \underline{F}(V), \end{cases} & \text{then } \underline{F}(V) = \underline{F}(V'), \text{ and} \\ \text{if } & \begin{cases} v_i < \bar{F}(V) \text{ and } v'_i \leq \bar{F}(V) \text{ or} \\ v_i > \bar{F}(V) \text{ and } v'_i \geq \bar{F}(V), \end{cases} & \text{then } \bar{F}(V) = \bar{F}(V'). \end{aligned}$$

When a correspondence does not satisfy *uncompromisingness*, we say that it is *compromised*.

3.5 Results

We begin by presenting in Section 3.5.1 results concerning interrelations between the properties presented in Section 3.4. Said results are then used in our characterization results presented in Sections 3.5.2 and 3.5.3. Loosely speaking, in Section 3.5.2, we extend the characterizations of Moulin (1980, Propositions 2 and 3)²⁴ to correspondences in domain \mathcal{R} ; while in Section 3.5.3, we show which of these characterizations can be extended in domain \mathcal{S} . Next, in section 3.5.4 we show that the properties in all our characterization results are independent; and finally, in section 3.5.5 we compare these results to those of Miyagawa (2001) and Heo (2013).

3.5.1 Interrelations between properties

Our first result in this section holds in domain \mathcal{S} . It shows that if *strategy-proofness* is satisfied, then *efficiency* and *voter-sovereignty* are equivalent.

Proposition 3.2. *For strategy-proof correspondences efficiency and voter-sovereignty are equivalent in domain \mathcal{S} .*

We prove Proposition 3.2 in Appendix 3.B. In addition, a similar equivalence result holds in domain \mathcal{R} , albeit slightly weaker since *peaks-onliness* or *min/max continuity* is also required. By Proposition 3.2, this result trivially holds in domain \mathcal{S} as well.

²⁴Proposition 2: A function satisfies *strategy-proofness*, *peaks-onliness*, and *anonymity* in \mathcal{R} if and only if it is a median rule. Proposition 3: A function satisfies *strategy-proofness* and *peaks-onliness* in \mathcal{R} if and only if it is a generalized median rule.

Proposition 3.3. *The following two statements for strategy-proof correspondences hold.*

(i) *If peaks-onliness is satisfied, then efficiency and voter-sovereignty are equivalent.*

(ii) *If min/max continuity is satisfied, then efficiency and voter-sovereignty are equivalent.*

We prove Proposition 3.3 in Appendix 3.B. Moreover, the next result holds only in domain \mathcal{R} .²⁵ It shows that *strategy-proofness* and *peaks-onliness* are equivalent with *uncompromisingness*.

Proposition 3.4. *The following two statements for correspondences are equivalent in domain \mathcal{R} .*

(i) *Strategy-proofness and peaks-onliness are satisfied.*

(ii) *Uncompromisingness is satisfied.*

We prove Proposition 3.4 in Appendix 3.C. Moreover, the next result is in the spirit of Proposition 3.4 and holds in domain \mathcal{S} .

Proposition 3.5. *The following two statements for correspondences are equivalent in domain \mathcal{S} .*

(i) *Strategy-proofness and voter-sovereignty are satisfied.*

(ii) *Uncompromisingness and voter-sovereignty are satisfied.*

We prove Proposition 3.5 in Appendix 3.C. Moreover, our final result also concerns *uncompromisingness*. It holds in both domains \mathcal{R} and \mathcal{S} .

Proposition 3.6. *Each correspondence satisfying strategy-proofness, min/max continuity, and voter-sovereignty also satisfies uncompromisingness.*

We prove Proposition 3.6 in Appendix 3.C.

3.5.2 Results in the single-peaked domain \mathcal{R}

We now present our characterization results for (generalized) median correspondences, as well as a counter-example justifying the absence of such results in some cases. All results hold in domain \mathcal{R} . The extension of these results in domain \mathcal{S} is discussed in Section 3.5.3.

Our first result concerns the class of generalized median correspondences.

²⁵An example of Proposition 3.4 not holding in domain \mathcal{S} is illustrated by the counter-example on page 84.

Theorem 3.1. *The following three statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) F satisfies strategy-proofness and peaks-onliness.
- (ii) F satisfies uncompromisingness.
- (iii) F is a generalized median correspondence.

The equivalence of statements (i) and (ii) follows from Proposition 3.4. We prove the equivalence of statements (ii) and (iii) in Appendix 3.D; note that this part of the proof also holds in domain \mathcal{S} .

Our second result concerns the class of median correspondences.

Theorem 3.2. *The following three statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) F satisfies strategy-proofness, peaks-onliness, and anonymity.
- (ii) F satisfies uncompromisingness and anonymity.
- (iii) F is a median correspondence.

Proof. The equivalence of statements (i) and (ii) follows from Proposition 3.4. We proceed by showing the equivalence of statements (ii) and (iii) in two steps; note that this part of the proof also holds in domain \mathcal{S} .

Step 1 - (statement (ii) implies statement (iii)): Let $F \in \mathcal{F}$ satisfy *uncompromisingness* and *anonymity*, and $V \in \mathcal{R}$. By Theorem 3.1, there exists $F_G^{\alpha, \beta} \in \mathcal{F}_G$ such that $F(V) = F_G^{\alpha, \beta}(V)$. Moreover, *anonymity* implies for $\alpha, \beta \in A^{2^n}$ that for each pair $L, M \subseteq N$, if $|L| = |M|$, then $\alpha_L = \alpha_M$ and $\beta_L = \beta_M$. Thus, for each $M \subseteq N$, let $a_{n+1-|M|} = \alpha_M$ and $b_{n+1-|M|} = \beta_M$, to effectively construct vectors $a, b \in A^{n+1}$. Next, let $F_M^{a, b} \in \mathcal{F}_M$ and notice that for each $V \in \mathcal{R}^N$, $F_G^{\alpha, \beta}(V) = [\text{med}(v, \tilde{\alpha}_v), \text{med}(v, \tilde{\beta}_v)] = [\text{med}(v, a), \text{med}(v, b)] = F_M^{a, b}(V)$.

Step 2 - (statement (iii) implies statement (ii)): Let $F_M^{a, b} \in \mathcal{F}_M$. In addition, let $F_G^{\alpha, \beta} \in \mathcal{F}_G$ by choosing vectors $\alpha, \beta \in A^{2^n}$ such that the weight of each coalition only depends on its cardinality; specifically, for each $M \subseteq N$, $\alpha_M = a_{n+1-|M|}$ and $\beta_M = b_{n+1-|M|}$. Hence, for each $V \in \mathcal{R}^N$, $F_G^{\alpha, \beta}(V) = [\text{med}(v, \tilde{\alpha}_v), \text{med}(v, \tilde{\beta}_v)] = [\text{med}(v, a), \text{med}(v, b)] = F_M^{a, b}(V)$. Therefore, by Theorem 3.1, $F_M^{a, b}$ satisfies *uncompromisingness* and by the definition of \mathcal{F}_M , $F_M^{a, b}$ satisfies *anonymity*. \square

Next, we show that in Theorems 3.1 and 3.2 *peaks-onliness* cannot be substituted with *min/max continuity*. We illustrate this in the counter-example that follows by exhibiting a correspondence satisfying *strategy-proofness*, *min/max continuity*, and *anonymity* and violating *voter-sovereignty* -and more importantly-

uncompromisingness; which, as shown in the aforementioned theorems, is satisfied by both classes of generalized median correspondences and median correspondences. Moreover, as explained in Section 3.5.3, this example also illustrates that the aforementioned theorems cannot be extended in domain \mathcal{S} .

Counter-example. Let $|N| \geq 1$ and define $r_V^* \equiv \max\{r_{V_i}(0)\}_{i \in N}$, that is, at announced profile V , among the indifferent announced alternatives to 0 of each agent $i \in N$, r_V^* is the largest one. Next, define $F^* \in \mathcal{F}$ as follows. For each $V \in \mathcal{R}^N$, $F^*(V) = [0, r_V^*]$. By definition, it follows that F^* satisfies min/max continuity and anonymity, and that it violates voter-sovereignty. We proceed in 2 steps

Step 1: We show F^* satisfies strategy-proofness. Let $V \in \mathcal{R}^N$ ($V \in \mathcal{S}^N$) be such that $i \in N$ is sincere, i.e., $V_i = R_i$. Also, let $V'_i \in \mathcal{R}$ ($V'_i \in \mathcal{S}$) be such that $V'_i \neq V_i$. There are two cases.

Case 1. Let $r_{V_i}(0) = r_V^*$. By single-peakedness, $b_{R_i}(F^*(V)) = \{p_i\}$, implying i 's best point does not improve by deviating at V , and $0 \in w_{R_i}(F^*(V))$. By the definition of F^* , $0 \in F^*(V_{-i}, V'_i)$, hence i 's worst point(s) does not improve by deviating at V . Therefore, $F^*(V) R_i F^*(V_{-i}, V'_i)$.

Case 2. Let $r_{V_i}(0) < r_V^*$. By single-peakedness, $b_{R_i}(F^*(V)) = \{p_i\}$, implying i 's best point does not improve by deviating at V , and $w_{V_i}(F^*(V)) = \{r_V^*\}$. By the definition of F^* , $r_V^* \in F^*(V_{-i}, V'_i)$, hence i 's worst point does not improve by deviating at V . Therefore, $F^*(V) R_i F^*(V_{-i}, V'_i)$.

Step 2: We show that F^* can be compromised. Let $N = \{1, 2, 3\}$. Let pair $V, V' \in \mathcal{S}^N$ be defined as follows: $v_1 = 0.2$, $v'_1 = 0.3$, and $v_2 = v'_2 = v_3 = v'_3 = 0$. Hence, $r_V^* = r_{V_1}(0) = 0.4$ and $r_{V'}^* = r_{V'_1}(0) = 0.6$. Therefore, $F(V) = [0, 0.4]$ and $F(V') = [0, 0.6]$. Clearly, F is compromised.

We conclude this section by presenting the “efficient versions” of Theorems 3.1 and 3.2. Notice that now peaks-onliness and min/max continuity become substitutable.

Theorem 3.3. *The following four statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) F satisfies strategy-proofness, peaks-onliness, and voter-sovereignty.
- (ii) F satisfies uncompromisingness and voter-sovereignty.
- (iii) F satisfies strategy-proofness, min/max continuity, and voter-sovereignty.
- (iv) F is an efficient generalized median correspondence.

Proof. The equivalence of statements (i) and (ii) follows from Proposition 3.4. The equivalence of statement (ii) and (iv) is shown as follows. By Theorem 3.1, statement (ii) implies $F \in \mathcal{F}_G$. Hence, by the definition of \mathcal{F}_G , F satisfies *peaks-onliness*. Thus, Proposition 3.3 and the definition of \mathcal{F}_{EG} imply $F \in \mathcal{F}_{EG}$, i.e., statement (ii) implies statement (iv). Moreover, by Theorem 3.1 and $\mathcal{F}_{EG} \subsetneq \mathcal{F}_G$, statement (iv) implies F satisfies *uncompromisingness*; in addition, by the definition of \mathcal{F}_{EG} , statement (iv) implies F satisfies *efficiency* and therefore *voter-sovereignty*, i.e., statement (iv) implies statement (ii). Finally, notice that this equivalence of statements (ii) and (iv) also holds in domain \mathcal{S} .

Next, by Proposition 3.6, statement (iii) implies statement (ii). We complete the proof by showing statement (ii) implies statement (iii). By Step 1 of the proof of Theorem 3.1(statement (ii) implies statement (iii)) on page 106, if $F \in \mathcal{F}$ satisfies *uncompromisingness*, then for $V \in \mathcal{R}^N$ and each $i \in N$ the following holds. If V_i^0 is such that $v_i^0 = 0$ and V_i^1 is such that $v_i^1 = 1$, then $\underline{F}(V) = \text{med}(\underline{F}(V), \underline{F}(V_{-i}, V_i^0), \underline{F}(V_{-i}, V_i^1))$ and $\bar{F}(V) = \text{med}(\bar{F}(V), \bar{F}(V_{-i}, V_i^0), \bar{F}(V_{-i}, V_i^1))$. Hence clearly statement (ii) implies F satisfies *min/max continuity*. Finally, by the equivalence of statements (i) and (ii), statement (ii) implies F satisfies *strategy-proofness*. \square

Theorem 3.4. *The following four statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) F satisfies *strategy-proofness, peaks-onliness, anonymity, and voter-sovereignty*.
- (ii) F satisfies *uncompromisingness, anonymity, and voter-sovereignty*.
- (iii) F satisfies *strategy-proofness, min/max continuity, anonymity, and voter-sovereignty*.
- (iv) F is an *efficient median correspondence*.

Proof. The equivalence of statements (i), (ii), and (iii) follows from Theorem 3.3. The equivalence of statements (ii) and (iv) is shown as follows. By Theorem 3.2, statement (ii) implies $F \in \mathcal{F}_M$. Hence, Proposition 3.3 and the definition of \mathcal{F}_{EM} imply $F \in \mathcal{F}_{EM}$, i.e., statement (ii) implies statement (iv). Moreover, by Theorem 3.2 and $\mathcal{F}_{EM} \subsetneq \mathcal{F}_M$, statement (iv) implies F satisfies *uncompromisingness*, and *anonymity*; in addition, by the definition of \mathcal{F}_{EM} , statement (iv) implies F satisfies *efficiency* and therefore *voter-sovereignty*, i.e., statement (iv) implies statement (ii). Finally, notice that this equivalence of statements (ii) and (iv) also holds in domain \mathcal{S} . \square

3.5.3 Results in the single-peaked and symmetric domain \mathcal{S}

We now show the characterizations in domain \mathcal{S} that are -loosely speaking- equivalent to those presented in Section 3.5.2 for domain \mathcal{R} . Specifically, the non-efficient characterizations in domain \mathcal{R} (Theorems 3.1 and 3.2) cannot be extended in domain \mathcal{S} . This is illustrated by the counter-example presented on page 84, where the given correspondence satisfies *strategy-proofness*, *anonymity*, and *min/max continuity* in domain \mathcal{S} but violates *uncompromisingness*. This violation is of importance because as shown by the proof of Theorem 3.1 (statement (iii) implies statement (ii)) on page 103 -this part of the proof also holds in domain \mathcal{S} - both classes of generalized median correspondences and median correspondences satisfy *uncompromisingness*.

Concerning the efficient characterizations in domain \mathcal{R} (Theorems 3.3 and 3.4), these do extend in domain \mathcal{S} . Moreover, since *peaks-onliness* is an inherent property of domain \mathcal{S} , *min/max continuity* is unnecessary in these characterizations.

Theorem 3.5. *The following three statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) *F satisfies strategy-proofness and voter-sovereignty.*
- (ii) *F satisfies uncompromisingness and voter-sovereignty.*
- (iii) *F is an efficient generalized median correspondence.*

Proof. The equivalence of statements (i) and (ii) constitutes Proposition 3.5. The equivalence of statements (ii) and (iii) follows from Theorem 3.3 (recall that as noted on page 85, statements (ii) and (iv) of Theorem 3.3 are also equivalent in domain \mathcal{S}). □

Theorem 3.6. *The following three statements for a correspondence $F \in \mathcal{F}$ are equivalent.*

- (i) *F satisfies strategy-proofness, voter-sovereignty, and anonymity.*
- (ii) *F satisfies uncompromisingness, voter-sovereignty, and anonymity.*
- (iii) *F is an efficient median correspondence.*

Proof. The equivalence of statements (i) and (ii) constitutes Proposition 3.5. The equivalence of statements (ii) and (iii) follows from Theorem 3.4 (recall that as noted on page 85, statements (ii) and (iv) of Theorem 3.4 are also equivalent in domain \mathcal{S}). □

3.5.4 Independence of properties

Concerning the independence of the properties used in our results, consider the following four correspondences. First, correspondence F^* proposed by the counterexample on page 84. Second, let correspondence $F_1 \in \mathcal{F}$ choose the minimum announced peak when more than two agents prefer it against the maximum announced peak, and choose the maximum announced peak otherwise; in both domains \mathcal{R} and \mathcal{S} , it satisfies *strategy-proofness*, *anonymity*, and *voter-sovereignty* but violates *peaks-onliness* (in domain \mathcal{R}), *min/max continuity*, and *uncompromisingness*. Third, for a small and positive value ε let correspondence $F_2 \in \mathcal{F}$ choose the minimum of: (a) the minimum announced peak plus ε and (b) the maximum peak; in both domains \mathcal{R} and \mathcal{S} , it satisfies all the properties we are interested in except for *strategy-proofness* and *uncompromisingness*. Finally, let $F_3 \in \mathcal{F}$ be the “constant” correspondence always choosing 0; in both domains \mathcal{R} and \mathcal{S} , it satisfies all the properties we are interested in except for *voter-sovereignty*.

Table 3.1 summarizes our results and also depicts that correspondences F^* , F_1 , F_2 , and F_3 suffice to show the independence of the properties used in our results.

	\mathcal{F}_G	\mathcal{F}_{EG}	\mathcal{F}_M	\mathcal{F}_{EM}	F^*	F_1	F_2	F_3
Domain \mathcal{R} ○	① ②	① ② ③	① ②	① ② ③				
Domain \mathcal{S} ●		④ ⑤		④ ⑤				
<i>Strategy-proofness</i>	①	① ② ④	①	① ② ④	✓	✓	✗	✓
<i>Peaks-onliness</i> (in \mathcal{R})	①	①	①	①	✗	✗	✓	✓
<i>Min/max continuity</i>		②		②	✓	✗	✓	✓
<i>Voter-sovereignty</i>		① ② ③ ④ ⑤		① ② ③ ④ ⑤	✗	✓	✓	✗
<i>Anonymity</i>			① ②	① ② ③ ④ ⑤	✓	✓	✓	✓
<i>Uncompromisingness</i>	②	③ ⑤	②	③ ⑤	✗	✗	✗	✓

The table above has a double purpose. First, columns \mathcal{F}_G , \mathcal{F}_{EG} , \mathcal{F}_M , and \mathcal{F}_{EM} , denoting the characterized classes of correspondences, defined in Sections 3.3.1 and 3.3.2, summarize our characterization results, with all results in domain \mathcal{R} shown by circled black numbers in a white background and all results in domain \mathcal{S} shown by circled white numbers in a black background. For example, in the column referring to \mathcal{F}_{EG} , the white circles containing number 4 show that in domain \mathcal{S} , *strategy-proofness* and *voter-sovereignty* characterize this class of correspondences. Second, the table shows the independence of the properties used in each characterization result. Specifically, all combinations of properties that must be checked are satisfied by at least one of the four non-median correspondences F^* , F_1 , F_2 , and F_3 , defined in Section 3.5.4 (with the exception of the combinations showing the independence of *anonymity* in the characterizations of \mathcal{F}_M and \mathcal{F}_{EM} ; these combinations are satisfied directly by the characterizations of \mathcal{F}_G and \mathcal{F}_{EG} respectively).

Table 3.1: Summary of the main results and independence of properties

3.5.5 Discussion

The classes of generalized median correspondences and median correspondences characterized in this chapter seem very similar to the class of double median functions characterized in Heo (2013). Moreover, the reader might have noticed that the left-peaks (right-peaks) function, characterized in Miyagawa (2001), resembles a special case of a median correspondence. However, there are some notable differences between these results and the results of this paper, which are summarized in the following three points.

(i) By using the max-extension of preferences in our setting, as is the case in the two aforementioned papers, it is straightforward to show that the only *efficient* correspondence would be the one always choosing the interval of the peaks, that is, for all $V \in \mathcal{R}$, $F(V) = [\underline{v}, \bar{v}]$. This follows from the agents only caring about their best alternative in a set, and from our setting not limiting the number of alternatives that may be chosen at a given profile.

(ii) Concerning the results of Heo (2013), the class of double median functions seems to be equivalent to the class of median correspondences. Specifically, the pair of alternatives (x_1, x_2) chosen by a double median function are essentially the minimum and maximum alternatives of the interval chosen by a median correspondence. However, apart from the distinction made in point (i), we should note the following: Heo's characterization result makes use of *users-only*, a property that partitions each coalition of agents into two sub-coalitions; one preferring x_1 over x_2 , and everyone else, with only the first partition (second partition) influencing the choice of alternative x_1 (x_2). In our setting, for each $F^{a,b} \in \mathcal{F}_M$, the choice of both vectors a and b depends on the preferences of all the agents.

(iii) Concerning the results of Miyagawa (2001) and apart of the distinction made in point (i), although the left-peaks function seems to be a special case of a median correspondence, this is not the case; the left-peaks function always chooses the two *distinct* left-most peaks, and moreover, the setting of Miyagawa requires that at least two distinct peaks exist in each profile. In our setting, the median correspondence that looks "similar" to the left-peaks function is $F^{a,b} \in \mathcal{F}$ where $a = (0, \dots, 0)$ and $b = (0, \dots, 0, 1)$. Although this correspondence seems to choose the two left-most peaks, when two or more agents share the minimum peak, it only chooses the minimum peak. Furthermore, it should be noted that in Chapter 2 the same properties with Miyagawa (namely, *efficiency* and *replacement-dominance*) are considered, under (almost) the same setting as in this chapter. There, it is shown that each correspondence satisfying said properties is essentially a function,

reconfirming the characterization of Vohra (1999) for (fixed population) *target-point functions*.²⁶ In addition, after weakening *replacement-dominance* to *one-sided replacement-dominance*²⁷, (fixed population) *target set correspondences*²⁸ are characterized, a sub-class of efficient median correspondences which -as discussed above- does not include either the left-peaks rule or the right-peaks rule.

3.A On min/max continuity

In the sequel, all properties are defined for correspondences in domain \mathcal{R} but also apply to correspondences in domain \mathcal{S} . Moreover, all results presented in this section, hold in both domains.

Upper-hemi continuity. *For each $V \in \mathcal{R}^N$, each $i \in N$, each $\{V_i^k\}$ in \mathcal{R} such that $V_i^k \rightarrow V_i$, and each $\{x^k\}$ in A such that $x^k \rightarrow x$, the following holds. If for each $k \in \mathbb{N}^+$, $x^k \in F(V_{-i}, V_i^k)$, then $x \in F(V)$.*

Lower-hemi continuity. *For each $V \in \mathcal{R}^N$, each $i \in N$, and each $\{V_i^k\}$ in \mathcal{R} such that $V_i^k \rightarrow V_i$, the following holds. If $x \in F(V)$, then there exists $\{x^k\}$ in A such that $x^k \rightarrow x$ and for each $k \in \mathbb{N}^+$, $x^k \in F(V_{-i}, V_i^k)$.*

Lemma 3.5. *The following two statements for correspondences are equivalent.*

- (i) *Min/max continuity is satisfied.*
- (ii) *Upper-hemi continuity and lower-hemi continuity are satisfied.*

Proof of Lemma 3.5. Let $F \in \mathcal{F}$. If F satisfies upper-hemi continuity and lower-hemi continuity then trivially, it also satisfies min/max continuity. Next, let F satisfy min/max continuity, $V \in \mathcal{R}^N$, and $\{V_i^k\}$ be in \mathcal{R} . We show that F satisfies upper-hemi continuity and lower-hemi continuity in two steps.

Step 1. We show F satisfies upper-hemi continuity. Let $\{x^k\}$ in A such that $x^k \rightarrow x$ and for each $k \in \mathbb{N}^+$, $x_k \in F(V_{-i}, V_i^k)$. Hence, for each $k \in \mathbb{N}^+$, $\underline{F}(V_{-i}, V_i^k) \leq x^k \leq \bar{F}(V_{-i}, V_i^k)$. Moreover, by min/max continuity, $\underline{F}(V_{-i}, V_i^k) \rightarrow \underline{F}(V)$ and $\bar{F}(V_{-i}, V_i^k) \rightarrow \bar{F}(V)$, which implies $\underline{F}(V) \leq x \leq \bar{F}(V)$ since otherwise, min/max continuity would imply that there exists $k^* \in \mathbb{N}^+$ such that $x_{k^*} \notin F(V_{-i}, V_i^{k^*})$. Therefore, $x \in F(V)$.

Step 2. We show F satisfies lower-hemi continuity. Let $x \in F(V)$ and $V_i^k \rightarrow V_i$. Hence, for all $k \in \mathbb{N}^+$, $\underline{F}(V_{-i}, V_i^k) \leq \bar{F}(V_{-i}, V_i^k)$ and by min/max continuity,

²⁶Each target point function is determined by its target point: if the target point is *efficient*, it is chosen; if it is not *efficient*, the closest *efficient* point is chosen.

²⁷See page 38 for a formal definition.

²⁸See page 33 for a formal definition.

$[\underline{F}(V_{-i}, V_i^k) \rightarrow \underline{F}(V)$ and $\bar{F}(V_{-i}, V_i^k) \rightarrow \bar{F}(V)]$. It follows that there exists $\{x^k\}$ in A such that $x^k \rightarrow x$ and for each $k \in \mathbb{N}^+$, $\underline{F}(V_{-i}, V_i^k) \leq x^k \leq \bar{F}(V_{-i}, V_i^k)$. \square

3.B Proofs of Propositions 3.2 and 3.3

Before proceeding to the proofs of Propositions 3.2 and 3.3, we show the following. When strategy-proofness is satisfied, *voter sovereignty* is equivalent with *unanimity*; a property stronger than *voter-sovereignty* but weaker than *efficiency*, that requires when all agents announce the same peak, only this peak to be chosen.²⁹ This result holds in both domains.

Lemma 3.6. *For strategy-proof correspondences, voter-sovereignty and unanimity are equivalent.*

Proof. Let $F \in \mathcal{F}$. Trivially, *unanimity* implies *voter sovereignty*. Hence, let F satisfy *strategy-proofness* and *voter-sovereignty*. We show that F satisfies *unanimity*.

Let $a \in A$ and $R \in \mathcal{R}^N$ be such that $p = (a, \dots, a)$. By *voter-sovereignty*, there exists $V \in \mathcal{R}^N$ such that $F(V) = a$. Let $M \subseteq N$ contain all the agents in N whose announced peak at V is not a , i.e., for each $i \in M$, $v_i \neq a$, and for each $j \in N \setminus M$, $v_j = p_j = a$. Without loss of generality, index the agents in N such that $M = \{1, \dots, m\}$. Next, consider profile $V^1 = (V_{-1}, R_1)$. By *strategy-proofness*, $F(V^1) R_1 F(V)$. Hence, single-peakedness and $F(V) = a = p_1$ imply $F(V^1) = a$. Finally, for each $k = \{2, \dots, m\}$ in increasing indexing order, consider profile $V^k = (V_{-k}^{k-1}, R_k)$. By the arguments presented for V^1 , $F(V^k) = F(V) = a$. Therefore, since $V^m = R$, $F(V^m) = F(R) = a$. \square

We proceed with the proof of Proposition 3.2, which makes use of Lemma 3.6. This proof holds only in domain \mathcal{S} because it makes use of the inherent *peaks-onliness* of this domain.

Proof of Proposition 3.2. Let $F \in \mathcal{F}$ satisfy *strategy-proofness*. The equivalence of *unanimity* and *voter-sovereignty* follows by Lemma 3.6. In addition, it is trivial to show that *efficiency* implies *unanimity*. Therefore, it remains to show that *unanimity* implies *efficiency*. We do so by contradiction; specifically, we show that if $F(V) \notin E(V)$, then *unanimity* is violated.

²⁹Formally, given $F \in \mathcal{F}$, for each $V \in \mathcal{R}^N$ such that $v = (x, \dots, x)$, $F(V) = \{x\}$.

Let $V \in \mathcal{S}^N$ and without loss of generality, assume $v_1 \leq \dots \leq v_n$. By Proposition 3.1, there are two cases.

Case 1. Let $\bar{v} < \bar{F}(V)$. For all agents $i \in N$, define $V'_i \in \mathcal{S}$ to be such that $v'_i = v_n$.

First, consider agent 1, where $\underline{v} = v_1 \leq \bar{v} < \bar{F}(V)$. By single-peakedness, either $[\bar{F}(V) \in w_{V_1}(F(V))$ and thus $w_{V_1}(F(V)) \notin E(V)$] or $[\underline{F}(V) = w_{V_1}(F(V))$ and thus $v_1 = \underline{v} < \bar{F}(V)$ and single-peakedness imply $\underline{F}(V) < \underline{v}$, and therefore, $w_{V_1}(F(V)) \notin E(V)$]. Next, recall the indifference relation r_{V_i} and let $x_1 = r_{V_1}(w_{V_1}(F(V)))$.³⁰ If $\bar{F}(V) \in w_{V_1}(F(V))$, then $v_1 < \bar{F}(V)$ and single-peakedness imply $x_1 < v_1 = \underline{v}$ and hence, $x_1 \notin E(V)$. Similarly, if $\underline{F}(V) = w_{V_1}(F(V))$, then $\underline{F}(V) < \underline{v} \leq \bar{v} < \bar{F}(V)$ and single-peakedness imply $x_1 > \bar{v}$ and hence, $x_1 \notin E(V)$. Finally, assume $R_1 = V_1$ and consider $V^1 = (V_{-1}, V'_1)$. By *strategy-proofness*, $w_{R_1}(F(V)) R_1 w_{R_1}(F(V^1))$; hence, $w_{V_1}(F(V)) \notin E(V)$, $x_1 \notin E(V)$, and single-peakedness implies $w_{R_1}(F(V^1)) \notin E(V)$. Then, since $E(V^1) \subseteq E(V)$ implies $w_{R_1}(F(V^1)) \notin E(V^1)$; and thus, $F(V^1) \notin E(V^1)$.

Next, consider agent 2 at profile V^1 and recall that $w_{R_1}(F(V^1)) \notin E(V^1)$ and $x_1 \notin E(V)$. Let $x^2 = r_{V_2}(w_{V_2}(F(V^1)))$. If $\underline{F}(V^1) \subseteq w_{R_1}(F(V^1))$, then $\underline{F}(V^1) < v_1$; hence, $v_1 \leq v_2$, single-peakedness, and $V_2 \in \mathcal{S}$ imply $\underline{F}(V^1) \subseteq w_{V_2}(F(V^1))$ and $x^2 \geq \bar{F}(V)$.³¹ Thus, $w_{V_2}(F(V^1)), x_2 \notin E(V^1)$. If $\bar{F}(V^1) = w_{R_1}(F(V^1))$, then $\bar{v}^1 < \bar{F}(V^1)$; hence, $v_2 \leq \bar{v}^1$ and single-peakedness imply either $[\bar{F}(V^1) \subseteq w_{V_2}(F(V^1))$ and $x_2 < \underline{v}_1]$ or $[\underline{F}(V^1) = w_{V_2}(F(V^1))$ and $\bar{v}^1 < \bar{F}(V^1) < x_2]$. Thus, $w_{V_2}(F(V^1)), x_2 \notin E(V^1)$. Therefore, by the arguments presented for V^1 , $F(V^2) \notin E(V^2)$.

Finally, for each $k \in \{3, \dots, n-1\}$, in increasing order, consider profile $V^k = (V_{-k}^{k-1}, V'_k)$. By the arguments presented for agents 1 and 2 above, $F(V^k) \notin E(V^k)$. Therefore, at profile V^{n-1} where $v^{n-1} = (v_n, \dots, v_n)$, $F(V^{n-1}) \notin E(V^{n-1})$ implying $F(V^{n-1}) \neq \{v_n\}$ which contradicts *unanimity*.

Case 2. Let $\underline{v} > \underline{F}(V)$. The proof is symmetric to Case 1. □

Notice that although for didactic reasons Proposition 3.3 proceeds Proposition 3.4 in the main text, the proof of Proposition 3.3 makes use of Proposition 3.4 (proof in Appendix 3.C). Recall that this result holds in both domains.

³⁰To be precise, if agent 1 has two worst points on $F(V)$, then with some abuse of notation, assume $w_{V_1}(F(V))$ is the smallest of the two worst points, which implies that x_1 is then the largest of the two worst points.

³¹To be precise, if agent 2 has two worst points on $F(V^1)$, then with some abuse of notation, assume $w_{V_2}(F(V^1))$ is the smallest of the two worst points, which implies that x_2 is then the largest of the two worst points.

Proof of Proposition 3.3. Let $F \in \mathcal{F}$ satisfy *strategy-proofness*. By Lemma 3.6, *unanimity* and *voter-sovereignty* are equivalent. In addition, it is easy to show that *efficiency* implies *unanimity*.

The proof proceeds in three steps. In Step 1 we show that if in addition to *strategy-proofness*, F satisfies *peaks-onliness* and *unanimity*, the following holds. Given an announced profile where an efficient set is chosen, if an agent with the minimum -but not unique- announced peak changes his announcement by moving his announced peak to the right, an efficient set is chosen again. Step 2 shows the same result but for the case where in addition to *strategy-proofness*, F satisfies *min/max continuity* and *unanimity*. Finally in Step 3, by *unanimity* and the intermediate results of Steps 1 and 2, we show that F satisfies *efficiency*.

Step 1. In addition to *strategy-proofness*, let F satisfy *peaks-onliness* and *unanimity*. By Proposition 3.4, F also satisfies *uncompromisingness*. Let $V \in \mathcal{R}^N$ and $i \in N$ be such that $F(V) \in E(V)$ and $v_i = \underline{v}$ but where i does not have the unique minimum peak. Hence, by Proposition 3.1, $F(V) \subseteq \text{Conv}(v)$. In addition, let $V'_i \in \mathcal{R}$ be such that $v'_i \geq \bar{v}$. Assuming $\underline{F}(V_{-i}, V'_i) < \underline{v}$ implies $\underline{F}(V_{-i}, V'_i) < v_i \leq v'_i$. Hence, by uncompromisingness, $\underline{F}(V_{-i}, V'_i) = \underline{F}(V) < \underline{v}$, which contradicts $F(V) \in E(V)$. Similarly, assuming $\bar{F}(V_{-i}, V'_i) > v'_i$ implies $\bar{F}(V_{-i}, V'_i) > v'_i \geq v_i$. Hence, by uncompromisingness, $\bar{F}(V_{-i}, V'_i) = \bar{F}(V) > \bar{v}$, which contradicts $F(V) \in E(V)$. Therefore, $F(V_{-i}, V'_i) \in E(V)$.

Step 2. In addition to *strategy-proofness*, let F satisfy *min/max continuity* and *unanimity*. Define $V \in \mathcal{R}^N$ and $V'_i \in \mathcal{R}$ as in Step 1. By single-peakedness, $w_{V'_i}(F(V)) = \underline{F}(V)$. We show that $F(V_{-i}, V'_i) \in E(V_{-i}, V'_i)$ by discrediting all three cases where $F(V_{-i}, V'_i) \notin E(V_{-i}, V'_i)$.

Case 1. Let $\underline{F}(V_{-i}, V'_i) < \underline{v}$. In addition, let $R_i = V'_i$. By single-peakedness, $\underline{F}(V) P_i \underline{F}(V_{-i}, V'_i)$, hence $w_{R_i}(F(V)) = \underline{F}(V)$ implies $w_{R_i}(F(V)) P_i w_{R_i}(F(V_{-i}, V'_i))$. Therefore, if at profile (V_{-i}, V'_i) agent i deviates by announcing V_i , his worst point improves. This contradicts *strategy-proofness*.

Case 2. Let $\underline{F}(V_{-i}, V'_i) > v'_i$. Since $\underline{F}(V) \leq \bar{F}(V) \leq v'_i$, by *min/max continuity*, there exists some profile $V''_i \in \mathcal{R}$ such that $V''_i \neq V'_i$ and $v'_i \in F(V_{-i}, V''_i)$. Let $R_i = V'_i$; hence, $b_{R_i}(F(V_{-i}, V''_i)) = v'_i$ implying $b_{R_i}(F(V_{-i}, V''_i)) P_i b_{R_i}(F(V_{-i}, V'_i))$. Therefore, if at profile (V_{-i}, V'_i) agent i deviates by announcing V''_i , his best point improves. This contradicts *strategy-proofness*.

Case 3. Let $\underline{v} \leq \underline{F}(V_{-i}, V'_i) \leq v'_i$ and $\bar{F}(V_{-i}, V'_i) > v'_i$. In the following, we describe a series of actions that when performed in sequence construct -after a finite number of “moves”- profile V' , such that $v' = (v'_i, \dots, v'_i)$ and $F(V') \neq v'_i$, i.e., a profile at which *unanimity* is violated.

Action 1. Let profile $V^0 = (V_{-i}, V'_i)$. Let $N_1 \subsetneq N$ be such that $j \in N_1$ if and only if $v_j^0 \neq v'_i$ and $v_j^0 < \underline{F}(V^0)$. If $N_1 = \emptyset$, then proceed to Action 2. Otherwise, let $j \in N_1$. By $v_j^0 < \underline{F}(V^0) \leq \bar{F}(V^0)$ and single-peakedness, $b_{V_j^0}(F(V^0)) = \underline{F}(V^0)$ and $w_{V_j^0}(F(V^0)) = \bar{F}(V^0)$. Let $V_j^1 = V'_i$ and profile $V^1 = (V_{-j}^0, V_j^1)$. Assume $R_j = V_j^0$. By *strategy-proofness*, $b_{R_j}(F(V^0)) R_j b_{R_j}(F(V^1))$ and $w_{R_j}(F(V^0)) R_j w_{R_j}(F(V^1))$; hence, by single-peakedness, either $[\underline{F}(V^0) \leq \underline{F}(V^1)$ and $\bar{F}(V^0) \leq \bar{F}(V^1)]$ or $[\underline{F}(V^1) \leq \bar{F}(V^1) < v_j^0]$. However, if $\underline{F}(V^1) \leq \bar{F}(V^1) < v_j^0$, then by *min/max continuity* there exist preference $V_j^* \in \mathcal{R}$ such that $v_j^0 \in F(V_{-j}^0, V_j^*)$. This violates *strategy-proofness* since if at profile V^0 agent j deviates by announcing V^* , his best point improves. Hence, $\underline{F}(V^0) \leq \underline{F}(V^1)$ and $\bar{F}(V^0) \leq \bar{F}(V^1)$. Therefore, $v'_i < \bar{F}(V^1)$.

Next, let $N_2 \subsetneq N$ be such that $k \in N_2$ if and only if $v_k^1 \neq v'_i$ and $v_k^1 < \underline{F}(V^1)$. If $N_2 = \emptyset$, then proceed to Action 2. Otherwise, let $k \in N_2$. In addition, let $V_k^2 = V'_i$ and profile $V^2 = (V_{-k}^1, V_k^2)$. By the process described in the previous paragraph for agent j , $v'_i < \bar{F}(V^2)$.

Finally, repeat this process μ times (where μ is smaller than the number of agents, $\mu \leq n - 1$) until the following holds. Set $N_\mu \subsetneq N$, constructed similarly to N_1 and N_2 , is empty. When this occurs, proceed to Action 2.

Action 2. Let profile $\bar{V}^0 = V^{\mu-1}$. Let $\bar{N}_1 \subsetneq N$ be such that $j \in \bar{N}_1$ if and only if $\bar{v}_j^0 \neq v'_i$ and $\bar{F}(\bar{V}^0) \subseteq w_{\bar{V}_j^0}(F(\bar{V}^0))$. Recall that $\bar{F}(\bar{V}^0) > v'_i$. If $\bar{N}_1 = \emptyset$, then proceed to Action 3. Otherwise, let $j \in \bar{N}_1$ and notice that by $N_\mu = \emptyset$ (as defined in Action 1), the choice of \bar{N}_1 implies $\underline{F}(\bar{V}^0) \leq \bar{v}_j^0 < \bar{F}(\bar{V}^0)$. Define $\bar{V}_j^1 \in \mathcal{R}$ such that $\bar{v}_j^1 = v'_i$ and $w_{\bar{V}_j^1}(F(\bar{V}^0)) = \underline{F}(\bar{V}^0)$, and let profile $\bar{V}^1 = (\bar{V}_{-j}^0, \bar{V}_j^1)$. Assume that $R_j = \bar{V}_j^0$. By *strategy-proofness*, $w_{R_j}(F(\bar{V}^0)) R_j w_{R_j}(F(\bar{V}^1))$; hence, by single-peakedness, $\bar{F}(\bar{V}^0) \leq \bar{F}(\bar{V}^1)$ and perhaps, $\underline{F}(\bar{V}^0) > \underline{F}(\bar{V}^1)$. Assume that $R_j = \bar{V}_j^1$. If $\underline{F}(\bar{V}^1) < \underline{F}(\bar{V}^0) < \bar{v}_j^1$, then single-peakedness implies $w_{R_j}(F(\bar{V}^0)) P_j w_{R_j}(F(\bar{V}^1))$. This violates *strategy-proofness* since if at profile \bar{V}^1 agent j deviates by announcing \bar{V}_j^0 , his worst point improves. Therefore, $\bar{F}(\bar{V}^0) \leq \bar{F}(\bar{V}^1)$ and $\underline{F}(\bar{V}^0) \leq \underline{F}(\bar{V}^1)$. Hence, $v'_i < \bar{F}(\bar{V}^1)$.

Next, if $\underline{F}(\bar{V}^0) < \underline{F}(\bar{V}^1)$, perhaps there exist some agents $\bar{j} \in N$ such that $v_{\bar{j}} < \underline{F}(\bar{V}^1) \leq \bar{F}(\bar{V}^1)$. If this is the case, then repeat the process described in Action 1 and denote the resulting profile (again) by \bar{V}^1 . If no such agents exist, then \bar{V}^1 is the profile constructed in the end of the previous paragraph.

Following this, let $\bar{N}_2 \subsetneq N$ be such that $k \in \bar{N}_2$ if and only if $\bar{v}_k^1 \neq v'_i$ and $\bar{F}(\bar{V}^1) \subseteq w_{\bar{V}_k^1}(F(\bar{V}^1))$, where $\bar{F}(\bar{V}^1) > v'_i$. If $\bar{N}_2 = \emptyset$, then proceed to Action 3. Otherwise, let $k \in \bar{N}_2$ and notice that either by $N_\mu = \emptyset$ (as defined in Action 1), or by Action 1 being repeated in the previous paragraph, the choice of \bar{N}_2 implies

$F(\bar{V}^1) \leq \bar{v}_k^1 < \bar{F}(\bar{V}^1)$. Define $\bar{V}_k^2 \in \mathcal{R}$ such that $\bar{v}_k^2 = v'_i$ and $w_{\bar{V}_k^2}(F(\bar{V}^1)) = \underline{F}(\bar{V}^1)$, and let profile $\bar{V}^2 = (\bar{V}_{-k}^1, \bar{V}_k^2)$. By the process described above for agent j , $\bar{F}(\bar{V}^1) \leq \bar{F}(\bar{V}^2)$ and $\underline{F}(\bar{V}^1) \leq \underline{F}(\bar{V}^2)$. Moreover, if $\underline{F}(\bar{V}^1) < \underline{F}(\bar{V}^2)$, perhaps Action 1 needs to be repeated as explained in the previous paragraph. In this case, \bar{V}^2 is the resulting profile after repeating Action 1, otherwise, \bar{V}^2 remains unchanged. In both cases, $v'_i < \bar{F}(\bar{V}^2)$.

Finally, repeat this process for a finite integer μ (where μ is smaller than the number of agents, $\mu \leq n - 1$) until the following holds. Set $\bar{N}_\mu \subsetneq N$, constructed similarly to \bar{N}_1 and \bar{N}_2 , is empty. Notice that $v'_i < \bar{F}(\bar{V}^{\mu-1})$ and proceed to Action 3.

Action 3. Let profile $\hat{V}^0 = \bar{V}^{\mu-1}$ and recall that $v'_i < \bar{F}(\hat{V}^0)$. Let $\hat{N} \subsetneq N$ be such that $j \in \hat{N}$ if and only if $\hat{v}_j^0 \neq v'_i$ and $w_{\hat{V}_j^0}(F(\bar{V}^0)) = \underline{F}(\hat{V}^0)$. Let $j \in \hat{N}$ and notice that by $\hat{v}_j^0 < v'_i < \bar{F}(\hat{V}^0)$ and single-peakedness, $\underline{F}(\hat{V}^0) < \hat{v}_j^0 < \bar{F}(\hat{V}^0)$. Define $\hat{V}_j^1 \in \mathcal{R}$ such that $\hat{v}_j^1 = v'_i$ and $w_{\hat{V}_j^1}(F(\hat{V}^0)) = \bar{F}(\hat{V}^0)$, and let profile $\hat{V}^1 = (\hat{V}_{-j}^0, \hat{V}_j^1)$. Assume that $R_j = \hat{V}_j^0$. By *strategy-proofness*, $w_{R_j}(F(\hat{V}^0)) R_j w_{R_j}(F(\hat{V}^1))$; hence, by single-peakedness, either $[\underline{F}(\hat{V}^0) \geq \underline{F}(\hat{V}^1)]$ or $[\underline{F}(\hat{V}^0) < \underline{F}(\hat{V}^1)$ and $\bar{F}(\hat{V}^0) < \bar{F}(\hat{V}^1)]$.

Next, assume that $R_j = \hat{V}_j^1$. If $\bar{F}(\hat{V}^1) > \bar{F}(\hat{V}^0) > \hat{v}_j^1$, then single-peakedness implies $w_{R_j}(F(\hat{V}^0)) P_j w_{R_j}(F(\hat{V}^1))$. This violates *strategy-proofness* since if at profile \hat{V}^1 agent j deviates by announcing \hat{V}_j^0 , his worst point improves. In addition, if $\bar{F}(\hat{V}^1) < \hat{v}_j^1 = b_{R_j}(F(\hat{V}^0))$, then single-peakedness implies $b_{R_j}(F(\hat{V}^0)) P_j b_{R_j}(F(\hat{V}^1))$. This violates *strategy-proofness* since if at profile \hat{V}^1 agent j deviates by announcing \hat{V}_j^0 , his best point improves. Therefore, $\underline{F}(\hat{V}^0) \geq \underline{F}(\hat{V}^1)$ and in addition, $v'_i \leq \bar{F}(\hat{V}^1) \leq \bar{F}(\hat{V}^0)$. Hence, $v'_i > \underline{F}(\hat{V}^1)$.

Finally, notice that by single-peakedness, $\underline{F}(\hat{V}^0) \geq \underline{F}(\hat{V}^1)$ and $v'_i \leq \bar{F}(\hat{V}^1) \leq \bar{F}(\hat{V}^0)$ the following holds; for each agent $k \in \hat{N}$, $w_{\hat{V}_k^0}(F(\bar{V}^0)) = \underline{F}(\hat{V}^0)$ implies $w_{\hat{V}_k^1}(F(\bar{V}^1)) = \underline{F}(\hat{V}^1)$. Hence, by the process described above for agent j , the announced peaks of all agents $k \in \hat{N}$, such that $k \neq j$, can be sequentially changed to v'_i and profile $\hat{V}^{|\hat{N}|}$ can be constructed. Therefore, since $\hat{v}^{|\hat{N}|} = (v'_i, \dots, v'_i)$, $\hat{V}^{|\hat{N}|} = V'$, and hence, $v'_i > \underline{F}(V')$ implies *unanimity* is violated.

Step 3. Let $V \in \mathcal{R}^N$. Without loss of generality, index the agents in N such that $v_1 \leq \dots \leq v_n$. Let $V' \in \mathcal{R}^N$ be such that $V' = (V_1, \dots, V_1)$. By *unanimity*, $F(V') = v_1$, hence by Proposition 3.1, $F(V') \in E(V')$. Next, consider profile $V^2 = (V'_{-2}, V_2)$ where $v_2 \geq v'_2 = v_1$, $v^2 = v'$, and $\bar{v}^2 \geq \bar{v}'$. Step 1 or Step 2, and $F(V') \in E(V')$ imply $F(V^2) \in E(V^2)$. Finally, for each $k = \{3, \dots, n\}$, in increasing order, consider profile $V^k = (V_{-k}^{k-1}, V_k)$. By the arguments presented for V^2 , $F(V^k) \in E(V^k)$. Therefore, since $V^n = V$, $F(V) \in E(V)$. \square

3.C Proofs of Propositions 3.4, 3.5, and 3.6

Before proceeding to the proof of Proposition 3.4 we present a lemma that holds only in domain \mathcal{R} ³² and concerns *strategy-proof* correspondences satisfying *peaks-onliness*. Loosely speaking, following an agent's announcement change, there are restrictions on the chosen set.

Lemma 3.7. *For each $F \in \mathcal{F}$ satisfying strategy-proofness and peaks-onliness, each $i \in N$, and each pair $V, V' \in \mathcal{R}^N$ such that $V_{-i} = V'_{-i}$, the following hold.*

(i) *If $v_i < \bar{F}(V)$, then $\bar{F}(V) \leq \bar{F}(V')$, and if in addition $v_i < \underline{F}(V)$, then $\underline{F}(V) \leq \underline{F}(V')$.*

(ii) *If $v_i > \underline{F}(V)$, then $\underline{F}(V) \geq \underline{F}(V')$, and if in addition $v_i > \bar{F}(V)$, then $\bar{F}(V) \geq \bar{F}(V')$.*

Proof. We prove statement (i), the proof of statement (ii) is symmetric. Let $F \in \mathcal{F}$ satisfy *strategy-proofness* and *peaks-onliness*. Let pair $V, V' \in \mathcal{R}^N$ and $i \in N$ be such that $V_{-i} = V'_{-i}$ and $v_i < \bar{F}(V)$.

Suppose R_i is such that $p_i = v_i$ and $0 P_i \bar{F}(V)$. By *peaks-onliness*, $F(V_{-i}, R_i) = F(V)$. Hence, by single-peakedness and the choice of R_i , $w_{R_i}(F(V_{-i}, R_i)) = \bar{F}(V)$. Thus, since $V' = (V_{-i}, V'_i)$, *strategy-proofness* implies $\bar{F}(V) R_i w_{R_i}(F(V'))$. Therefore, single-peakedness, the choice of R_i , and $0 \leq v_i < \bar{F}(V)$ imply $w_{R_i}(F(V')) \geq \bar{F}(V)$, and hence, $\bar{F}(V') \geq \bar{F}(V)$.

If in addition $v_i < \underline{F}(V)$, then by single-peakedness, $b_{R_i}(F(V_{-i}, R_i)) = \underline{F}(V)$. Thus, since $V' = (V_{-i}, V'_i)$, *strategy-proofness* implies $\underline{F}(V) R_i b_{R_i}(F(V'))$. Therefore, single-peakedness, $\bar{F}(V') \geq \bar{F}(V)$, and $v_i < \underline{F}(V)$ imply $\underline{F}(V') \geq \underline{F}(V)$. \square

The proof of Proposition 3.4 follows and holds only in domain \mathcal{R} because it makes use of Lemma 3.7.

Proof of Proposition 3.4. The proof is split in two parts.

Part 1: We show that *strategy-proofness* and *peaks-onliness* imply *uncompromisingness*.

Let $F \in \mathcal{F}$ satisfy *strategy-proofness* and *peaks-onliness*. Let pair $V, V' \in \mathcal{R}^N$ and $i \in N$ be such that $V_{-i} = V'_{-i}$. If $v_i = v'_i$, then *peaks-onliness* implies *uncompromisingness*. Hence, let $v_i \neq v'_i$, and by symmetry of arguments, let $v_i < v'_i$. There are four cases. Notice that Case 1.1 overlaps with Case 2.1, while Case 1.2 overlaps with Cases 2.1 and 2.2.

³²It does not hold in domain \mathcal{S} because the proof makes use of non-symmetrical single-peaked preferences.

Case 1.1. Let $v_i < v'_i \leq \underline{F}(V)$. By Lemma 3.7(i), $\underline{F}(V) \leq \underline{F}(V')$. Moreover, assuming $\underline{F}(V) < \underline{F}(V')$ results in a contradiction as follows. Since $v'_i < \underline{F}(V')$, Lemma 3.7(i) implies $\underline{F}(V') \leq \underline{F}(V)$. Therefore, $\underline{F}(V) = \underline{F}(V')$.

Case 1.2. Let $\underline{F}(V) < v_i < v'_i$. By Lemma 3.7(ii), $\underline{F}(V') \leq \underline{F}(V)$. Hence, $\underline{F}(V') < v'_i$, and by Lemma 3.7(ii), $\underline{F}(V) \leq \underline{F}(V')$. Therefore, $\underline{F}(V) = \underline{F}(V')$.

Case 2.1. Let $v_i < v'_i \leq \bar{F}(V)$. By Lemma 3.7(i), $\bar{F}(V) \leq \bar{F}(V')$. Moreover, assuming $\bar{F}(V) < \bar{F}(V')$ results in a contradiction as follows. Since $v'_i < \bar{F}(V')$, Lemma 3.7(i) implies $\bar{F}(V') \leq \bar{F}(V) < \bar{F}(V')$. Therefore, $\bar{F}(V) = \bar{F}(V')$.

Case 2.2. Let $\bar{F}(V) < v_i < v'_i$. By Lemma 3.7(ii), $\bar{F}(V') \leq \bar{F}(V)$. Hence, $\bar{F}(V') < v'_i$, and by Lemma 3.7(ii), $\bar{F}(V) \leq \bar{F}(V')$. Therefore, $\bar{F}(V) = \bar{F}(V')$.

Part 2: We show that *uncompromisingness* implies *strategy-proofness* and *peaks-onliness*. Notice that this part of the proof also hold in domain \mathcal{S} .

Let $F \in \mathcal{F}$ satisfy *uncompromisingness*. Let $i \in N$ and pair $V, V' \in \mathcal{R}^N$ be such that $V_{-i} = V'_{-i}$ and $V_i \neq V'_i$. We proceed in two steps.

Step 1. We show that F satisfies *peaks-onliness*.

Let $v_i = v'_i$. If $v_i = \underline{F}(V)$, then assuming $\underline{F}(V') \neq \underline{F}(V)$ results in a contradiction, since $v'_i = v_i \neq \underline{F}(V')$ and *uncompromisingness* imply $\underline{F}(V) = \underline{F}(V')$. Similarly, if $v_i = \bar{F}(V)$, then assuming $\bar{F}(V') \neq \bar{F}(V)$ results in a contradiction, since $v'_i = v_i \neq \bar{F}(V')$ and *uncompromisingness* imply $\bar{F}(V) = \bar{F}(V')$. Finally, if $v_i \neq \underline{F}(V)$ and $v_i \neq \bar{F}(V)$, then by *uncompromisingness*, $F(V) = F(V')$. Therefore, F satisfies *peaks-onliness*.

Step 2. We show that F satisfies *strategy-proofness*. Recall that $V_i \neq V'_i$ and by symmetry of arguments, let $v_i \leq v'_i$. By Step 1, F satisfies *peaks-onliness*, hence, if $v_i = v'_i$, then *strategy-proofness* is satisfied. By symmetry of arguments, let $v_i < v'_i$. We proceed in two stages.

Stage 1. We show that $\underline{F}(V) \leq \underline{F}(V')$ and $\bar{F}(V) \leq \bar{F}(V')$. There are 3 cases.

Case 1. Let $v_i < \underline{F}(V)$. If $v_i < v'_i \leq \underline{F}(V)$, then by *uncompromisingness*, $\underline{F}(V) = \underline{F}(V')$. Otherwise, if $\underline{F}(V) < v'_i$, then consider the following. Assuming $\underline{F}(V') < \underline{F}(V)$ results in a contradiction as follows. Let V_i^1 be such that $v_i^1 = \underline{F}(V')$. Since $v_i < \underline{F}(V)$ and $v_i^1 < \underline{F}(V)$, by *uncompromisingness*, $\underline{F}(V_{-i}, V_i^1) = \underline{F}(V)$. However, since $\underline{F}(V') < v'_i$ and $v_i^1 = \underline{F}(V')$, by *uncompromisingness*, $\underline{F}(V_{-i}, V_i^1) = \underline{F}(V')$. Hence, $\underline{F}(V) \leq \underline{F}(V')$.

Case 2. Let $v_i = \underline{F}(V) < v'_i$. Assuming $\underline{F}(V') < \underline{F}(V)$ results in a contradiction as follows. Since $\underline{F}(V') < v_i < v'_i$, by *uncompromisingness*, $\underline{F}(V') = \underline{F}(V)$. Hence, $\underline{F}(V) \leq \underline{F}(V')$.

Case 3. Let $v_i > \underline{F}(V)$. Since $v_i < v'_i$, by *uncompromisingness*, $\underline{F}(V) = \underline{F}(V')$.

Stage 2. By Stage 1, $\underline{F}(V) \leq \underline{F}(V')$ and $\bar{F}(V) \leq \bar{F}(V')$. We show that F

satisfies *strategy-proofness*. Let $R_i = V_i$. There are five cases.

Case 1. Let $p_i < \underline{F}(V)$. By peaks-onliness, $b_{R_i}(F(V)) = \underline{F}(V)$, $w_{R_i}(F(V)) = \bar{F}(V)$, $b_{R_i}(F(V')) = \underline{F}(V')$, and $w_{R_i}(F(V')) = \bar{F}(V')$. Hence, by single-peakedness, i 's best and worst points do not improve by deviating at V . Therefore, $F(V) R_i F(V')$.

Case 2. Let $p_i = \underline{F}(V)$. By peaks-onliness, $b_{R_i}(F(V)) = p_i$ and $w_{R_i}(F(V)) = \bar{F}(V)$, implying i can't improve on his best point. Regarding his worst point, since $\bar{F}(V) \leq \bar{F}(V')$, by peaks-onliness, $w_{R_i}(F(V)) R_i \bar{F}(V')$. Therefore, $F(V) R_i F(V')$.

Case 3. Let $\underline{F}(V) < p_i < \bar{F}(V)$. By peaks-onliness, $b_{R_i}(F(V)) = p_i$ and $w_{R_i}(F(V)) \subseteq \{\underline{F}(V), \bar{F}(V)\}$, implying agent i can't improve on his best point. Regarding his worst point(s), since $\underline{F}(V) < p_i \leq v'_i$, by *uncompromisingness*, $\underline{F}(V) = \underline{F}(V')$. Since also $\bar{F}(V) \leq \bar{F}(V')$, by peaks-onliness, $w_{R_i}(F(V)) R_i w_{R_i}(F(V'))$. Therefore, $F(V) R_i F(V')$.

Case 4. Let $p_i = \bar{F}(V)$. By peaks-onliness, $b_{R_i}(F(V)) = p_i$ and $w_{R_i}(F(V)) = \underline{F}(V)$, implying i can't improve on his best point. Regarding his worst point, if $\underline{F}(V) < \bar{F}(V)$, then since $\underline{F}(V) < p_i \leq v'_i$, and by *uncompromisingness*, $\underline{F}(V) = \underline{F}(V')$. Hence, $\bar{F}(V) \leq \bar{F}(V')$ implies $w_{R_i}(F(V)) R_i w_{R_i}(F(V'))$. Otherwise, if $\underline{F}(V) = \bar{F}(V)$, then $w_{R_i}(F(V)) = p_i$, implying i can't improve on his worst point. Therefore, in both cases $F(V) R_i F(V')$.

Case 5. Let $p_i > \bar{F}(V)$. Since $\bar{F}(V) < p_i \leq v'_i$, by *uncompromisingness*, $F(V) = F(V')$. Therefore, $F(V) I_i F(V')$. \square

Before proceeding to the proof of Proposition 3.5 we present two lemmata that hold only in domain \mathcal{S} (because they make use of Proposition 3.2) and concern *strategy-proof* correspondences satisfying *voter-sovereignty*. Loosely speaking, both show cases where following a change in the preferences of some agents, there are restrictions in the minimum and maximum chosen alternatives.

Lemma 3.8. *For each $F \in \mathcal{F}$ satisfying strategy-proofness and voter-sovereignty, each $V \in \mathcal{S}^N$, and each $x \in A$ the following hold.*

(i) *Let $V' \in \mathcal{S}^N$ be as follows. For each $i \in N$, if $v_i \leq x$, then $v'_i = x$, otherwise $v'_i = v_i$. Then, $x \leq \bar{F}(V)$ implies $\bar{F}(V) \leq \bar{F}(V')$; in addition, $x \leq \underline{F}(V)$ implies $\underline{F}(V) \leq \underline{F}(V')$.*

(ii) *Let $V' \in \mathcal{S}^N$ be as follows. For each $i \in N$, if $v_i \geq x$, then $v'_i = x$, otherwise $v'_i = v_i$. Then, $x \geq \underline{F}(V)$ implies $\underline{F}(V) \geq \underline{F}(V')$; in addition, $x \geq \bar{F}(V)$ implies $\bar{F}(V) \geq \bar{F}(V')$.*

Proof. We prove statement (i), the proof of statement (ii) is symmetric. Let $F \in \mathcal{F}$ satisfy *strategy-proofness* and *voter-sovereignty*. By Proposition 3.2, F also

satisfies *efficiency*. Let $V \in \mathcal{S}^N$ and $x \in A$ be such that $x \leq \bar{F}(V)$; and without loss of generality, let $v_1 \leq \dots \leq v_n$. Moreover, let $V' \in \mathcal{S}^N$ be defined as follows. For each $i \in N$, if $v_i \leq x$, then $v'_i = x$, otherwise $v'_i = v_i$. Let $M = \{1, \dots, m\} \subseteq N$ be such that $i \in M$ implies $v'_i = x$. Hence, $V' = (V_x, \dots, V_x, V_{m+1}, \dots, V_n)$, where $V_x \in \mathcal{S}$ and $v_x = x$.

Begin from profile V . By *efficiency* and Proposition 3.1, $F(V) \subseteq \text{Conv}(V)$. Let $R_1 = V_1$, hence $v_1 \leq x \leq \bar{F}(V)$ implies $w_{R_1}(F(V)) = \bar{F}(V)$. Next, let $V_1^1 = V_x$ and consider profile $V^1 = (V_{-1}, V_1^1)$. By *efficiency* and Proposition 3.1, $F(V^1) \subseteq \text{Conv}(V^1)$, and by *strategy-proofness*, $w_{R_1}(F(V)) R_1 w_{R_1}(F(V^1))$. Therefore, by single-peakedness, $v_1 \leq \bar{F}(V) \leq \bar{F}(V^1)$. If $V^1 = V'$, then we are done. Otherwise, for each $k \in \{2, \dots, m\}$, in increasing order, consider profile $V^k = (V_{-k}^{k-1}, V_k^k)$. By the arguments presented for V^1 , $\bar{F}(V^{k-1}) \leq \bar{F}(V^k)$. Therefore, $V^m = V'$ implies $\bar{F}(V) \leq \bar{F}(V')$.

If in addition $x \leq \underline{F}(V)$, then $b_{R_1}(F(V)) = \underline{F}(V)$. In this case, begin from profile V and construct profile V' as shown above. By the same arguments to the ones presented above, but expressed for the best alternative instead of the worst, it follows that $\underline{F}(V) \leq \underline{F}(V')$. \square

Lemma 3.9. *For each $F \in \mathcal{F}$ satisfying strategy-proofness and voter-sovereignty, and each $V \in \mathcal{S}^N$ the following hold.*

(i) *Let $M \subseteq N$ be such that $i \in M$ implies $v_i = \underline{v}$. Let $V' \in \mathcal{S}^N$ be as follows. For each $i \in N$, if $i \in M$, then $v'_i \leq v_i$, otherwise $v'_i = v_i$. Then, $\underline{v} < \bar{F}(V)$ implies $\bar{F}(V) \leq \bar{F}(V')$; in addition, $\underline{v} < \underline{F}(V)$ implies $\underline{F}(V) \leq \underline{F}(V')$.*

(ii) *Let $M \subseteq N$ be such that $i \in M$ implies $v_i = \bar{v}$. Let $V' \in \mathcal{S}^N$ be as follows. For each $i \in N$, if $i \in M$, then $v'_i \geq v_i$, otherwise $v'_i = v_i$. Then, $\bar{v} > \underline{F}(V)$ implies $\underline{F}(V) \geq \underline{F}(V')$; in addition, $\bar{v} > \bar{F}(V)$ implies $\bar{F}(V) \geq \bar{F}(V')$.*

Proof. We prove statement (i), the proof of statement (ii) is symmetric. Let $F \in \mathcal{F}$ satisfy *strategy-proofness* and *voter-sovereignty*, and $V \in \mathcal{S}^N$ be such that $\underline{v} < \bar{F}(V)$. By Proposition 3.2, F also satisfies *efficiency*; hence, Proposition 3.1 implies $\underline{v} < \bar{F}(V) \leq \bar{v}$. In addition, let $M \subseteq N$ be such that $i \in M$ implies $v_i = \underline{v}$, and without loss of generality, let $M = (1, \dots, m)$; hence, $\underline{v} < \bar{v}$ implies $M \subsetneq N$. Moreover, let $V' \in \mathcal{S}^N$ be as follows. For each $i \in N$, if $i \in M$, then $v'_i \leq v_i$, otherwise $v'_i = v_i$. Finally, without loss of generality, let $v'_1 \leq \dots \leq v'_m < v'_{m+1} \leq \dots \leq v'_n$.

Begin from profile V and let $\delta = |\underline{v} - \bar{F}(V)| > 0$. Assume $R_1 = V_1$. By single-peakedness, $w_{R_1}(F(V)) = \bar{F}(V)$. Change the announced preferences of agent 1 to $V_1^1 \in \mathcal{S}$ as follows. If $|v'_m - \underline{v}| < \delta$, then set $v_1^1 = v'_m$, otherwise, set

$v_1^1 = \underline{v} - \frac{\delta}{2}$. By *efficiency* and Proposition 3.1, $F(V_{-1}, V_1^1) \subseteq \text{Conv}(V_{-1}, V_1^1)$. By *strategy-proofness*, $w_{R_1}(F(V)) R_1 w_{R_1}(F(V_{-1}, V_1^1))$. Therefore, $|v_1^1 - \underline{v}| < \delta$ implies (in domain \mathcal{S}) that $\bar{F}(V) \leq \bar{F}(V_{-1}, V_1^1)$. Following this, sequentially repeat this process for all agents $i \in \{2, \dots, m\}$ (if such agents exist) and construct profile $V^1 = (V_1^1, \dots, V_m^1, V_{m+1}, \dots, V_n)$, where $\bar{F}(V) \leq \bar{F}(V^1)$. If $v_1^1 = v'_m$, proceed to the next paragraph. Otherwise, let $\delta^1 = |v_1^1 - \bar{F}(V^1)| > 0$, assume $R_1 = V_1^1$, and repeat the process to construct profile V^2 , where $\bar{F}(V) \leq \bar{F}(V^2)$. If $v_1^2 = v'_m$, proceed to the next paragraph. Otherwise, keep repeating this process until the profile $\bar{V}^m = (V'_m, \dots, V'_m, V_{m+1}, \dots, V_n)$ has been constructed, where $\bar{F}(V) \leq \bar{F}(\bar{V}^m)$.

Next, repeat the process described above for all agents $i \in \{1, \dots, m-1\}$ (if such agents exist) and construct profile $\bar{V}^{m-1} = (V'_{m-1}, \dots, V'_{m-1}, V'_m, V_{m+1}, \dots, V_n)$, where $\bar{F}(V) \leq \bar{F}(\bar{V}^{m-1})$.

Finally, continue repeating this whole process until the profile $\bar{V}^1 = V' = (V'_1, \dots, V'_m, V_{m+1}, \dots, V_n)$ has been constructed, where $\bar{F}(V) \leq \bar{F}(V')$.

If in addition, $\underline{v} < \underline{F}(V)$, begin from profile V , let $\delta = |\underline{v} - \underline{F}(V)| > 0$, and construct profile V' as shown above. By the same arguments to the ones presented above, but expressed for the best alternative instead of the worst, it follows that $\underline{F}(V) \leq \underline{F}(V')$. \square

We now proceed with the proof of Proposition 3.5 that holds only in domain \mathcal{S} because it makes indirect use of Proposition 3.2 through Lemmas 3.8 and 3.9.

Proof of Proposition 3.5. Let $F \in \mathcal{F}$. Part 2 of Proposition 3.4 on page 96 (which also holds in \mathcal{S}) shows that if F satisfies *uncompromisingness* then it also satisfies *strategy-proofness*. Hence, it follows that statement (ii) implies statement (i). Next, we show that statement (i) implies statement (ii).

Let F satisfy *strategy-proofness* and *voter-sovereignty*. Let $i \in N$ and pair $V, V' \in \mathcal{S}^N$ be such that $V_{-i} = V'_{-i}$. Without loss of generality, assume $v_1 \leq \dots \leq v_n$. Since $v_i = v'_i$ trivially satisfies *uncompromisingness* in domain \mathcal{S} , let $v_i \neq v'_i$. There are six cases.

Case 1.1. Let $v'_i < v_i \leq \underline{F}(V)$. Since $v_i = \underline{F}(V) = \bar{F}(V)$ trivially satisfies *uncompromisingness*, let $v_i < \bar{F}(V)$. In addition, let $M \subsetneq N$ be such that $j \in M$ if and only if $v_j \leq v_i$. Begin from profile V and consider profile V^1 to be such that $V_{-M} = V_{-M}^1$ and where each agent $j \in M$ announces preferences $V_j^1 = V_j$. By construction of V^1 and Lemma 3.8(i), $\underline{F}(V^1) \geq \underline{F}(V)$ and $\bar{F}(V^1) \geq \bar{F}(V)$. Moreover, begin from profile V^1 and consider profile V . Since for each $j \in M$, $v_j \leq v_j^1 = v_j$, and for each $k \in N \setminus M$, $v_k = v_k^1 > v_j^1$, by Lemma 3.9(i), $\bar{F}(V) \geq \bar{F}(V^1)$

and in addition, if $v_i < \underline{F}(V)$, then $\underline{F}(V) \geq \underline{F}(V^1)$. Therefore, $\underline{F}(V^1) = \underline{F}(V)$ and $\bar{F}(V^1) = \bar{F}(V)$.

Next, begin from profile V^1 and consider profile V' . Since for each $j \in M$, $v'_j \leq v_j^1 = v^1$, and for each $k \in N \setminus M$, $v'_k = v_k^1 > v^1$, by Lemma 3.9(i), $\bar{F}(V') \geq \bar{F}(V^1)$, and in addition, if $v_i < \underline{F}(V^1) = \underline{F}(V)$, then $\underline{F}(V') \geq \underline{F}(V^1)$. Finally, begin from profile V' and consider profile V^1 . Since for each $j \in M$, $v'_j \leq v_j^1 = v'_j$, and for each $k \in N \setminus M$, $v'_k = v_k^1 > v'_i$, by Lemma 3.8(i), $\bar{F}(V^1) \geq \bar{F}(V')$ and $\underline{F}(V^1) \geq \underline{F}(V')$. Therefore, $\bar{F}(V^1) = \bar{F}(V) = \bar{F}(V')$ and $\underline{F}(V^1) = \underline{F}(V) = \underline{F}(V')$.

Case 1.2. Let $v'_i > v_i \geq \bar{F}(V)$. The proof is symmetric to Case 1.1.

Case 2.1. Let $v_i \leq \underline{F}(V)$ and $v_i < v'_i$. If $v'_i > \bar{F}(V)$, then *uncompromisingness* is trivially satisfied; hence, let $v'_i \leq \bar{F}(V)$. In addition, let $M \subsetneq N$ be such that $j \in M$ if and only if $v_j \leq v'_i$. Begin from profile V and consider profile V^1 to be such that $V_{-M} = V_{-M}^1$ and where each agent $j \in M$ announces preferences $V_j^1 = V'_j$. By construction of V^1 and Lemma 3.8(i), $\bar{F}(V^1) \geq \bar{F}(V)$ and in addition, if $v'_i \leq \underline{F}(V)$, then $\underline{F}(V^1) \geq \underline{F}(V)$. Moreover, begin from profile V^1 and consider profile V . Since for each $j \in M$, $v_j \leq v_j^1 = v^1$, and for each $k \in N \setminus M$, $v_k = v_k^1 > v^1$, by Lemma 3.9(i), if $v_i < \bar{F}(V^1)$, then $\bar{F}(V) \geq \bar{F}(V^1)$ and in addition, if $v_i < \underline{F}(V^1)$, then $\underline{F}(V) \geq \underline{F}(V^1)$. Therefore, $\bar{F}(V^1) = \bar{F}(V)$ and in addition, if $v'_i \leq \underline{F}(V)$, then $\underline{F}(V^1) = \underline{F}(V)$. There are three sub-cases.

(i) Let $v'_i = \bar{F}(V)$. Assume $R_i = V'_i$. Hence, $b_{R_i}(F(V)) = \bar{F}(V)$. Since $V_{-i} = V'_{-i}$, by *strategy-proofness*, $\bar{F}(V) = v'_i \in F(V')$. Thus, $\bar{F}(V') \geq \bar{F}(V)$. Moreover, begin from profile V' and consider profile V^1 . Since for each $j \in M$, $v'_j \leq v_j^1 = v'_i$, and for each $k \in N \setminus M$, $v'_k = v_k^1 > v'_i$, by Lemma 3.8(i), $\bar{F}(V^1) \geq \bar{F}(V')$. Therefore, $\bar{F}(V^1) = \bar{F}(V) = \bar{F}(V')$.

(ii) Let $v'_i < \bar{F}(V)$. Begin from profile V^1 and consider profile V' . Since for each $j \in M$, $v'_j \leq v_j^1 = v^1$, and for each $k \in N \setminus M$, $v'_k = v_k^1 > v^1$, by $v'_i < \bar{F}(V)$ and Lemma 3.9(i), $\bar{F}(V') \geq \bar{F}(V^1)$, and in addition, if $v'_i < \underline{F}(V)$, then $\underline{F}(V') \geq \underline{F}(V^1)$. Moreover, begin from profile V' and consider profile V^1 . Since for each $j \in M$, $v'_j \leq v_j^1 = v'_i$, and for each $k \in N \setminus M$, $v'_k = v_k^1 > v'_i$, by $v'_i < \bar{F}(V)$ and Lemma 3.8(i), $\bar{F}(V^1) \geq \bar{F}(V')$, and in addition, if $v'_i < \underline{F}(V')$, then $\underline{F}(V^1) \geq \underline{F}(V')$. Therefore, $\bar{F}(V^1) = \bar{F}(V') = \bar{F}(V)$ and in addition, if $v'_i < \underline{F}(V)$, then $\underline{F}(V^1) = \underline{F}(V') = \underline{F}(V)$.

(iii) Let $v'_i = \underline{F}(V)$. If $v'_i = \underline{F}(V) = \bar{F}(V)$, then *uncompromisingness* is trivially satisfied; hence, let $v'_i = \underline{F}(V) < \bar{F}(V)$. As shown in the previous sub-case, $\bar{F}(V') = \bar{F}(V)$. Assume $R_i = V_i$. Since $v_i < v'_i$, by *single-peakedness*, $b_{R_i}(F(V)) = \underline{F}(V)$ and $w_{R_i}(F(V)) = \bar{F}(V)$. Hence, $V'_{-i} = V_{-i}$ and *strategy-proofness* imply $b_{R_i}(F(V)) = \underline{F}(V)$ and $b_{R_i}(F(V')) = \bar{F}(V)$. Thus, by $\bar{F}(V') = \bar{F}(V)$ and *single-*

peakedness, $b_{R_i}(F(V)) = \underline{F}(V) \leq \underline{F}(V')$. Finally, assume $R_i = V'_i$. Since $v'_i \leq \underline{F}(V') \leq \bar{F}(V')$, by single-peakedness, $b_{R_i}(F(V')) = \underline{F}(V')$ and $w_{R_i}(F(V')) = \bar{F}(V')$. Hence, $V'_{-i} = V_{-i}$ and *strategy-proofness* imply $b_{R_i}(F(V')) R_i b_{R_i}(F(V))$. Thus, by $\bar{F}(V') = \bar{F}(V)$ and single-peakedness, $b_{R_i}(F(V')) = \underline{F}(V') \leq \underline{F}(V)$. Therefore, $\underline{F}(V) = \underline{F}(V')$.

Case 2.2. Let $v_i \geq \bar{F}(V)$ and $v_i > v'_i$. The proof is symmetric to Case 2.1.

Case 3.1. Let $\underline{F}(V) < v_i < \bar{F}(V)$ and $v'_i > v_i$. In addition, let $M \subsetneq N$ be such that $j \in M$ if and only if $v_j \geq v'_j$. Begin from profile V and consider profile V^1 to be such that $V_{-M} = V_{-M}^1$ and where each agent $j \in M$ announces preferences $V_j^1 = V'_j$. By construction of V^1 and Lemma 3.8(ii), $\underline{F}(V) \geq \underline{F}(V^1)$. Moreover, begin from profile V^1 and consider profile V . Since for each $j \in M$, $v_j \geq v_j^1 = \bar{v}^1$, and for each $k \in N \setminus M$, $v_k = v_k^1 < \bar{v}^1$, by $v'_i > \underline{F}(V^1)$ and Lemma 3.9(ii), $\underline{F}(V^1) \geq \underline{F}(V)$. Therefore, $\underline{F}(V) = \underline{F}(V^1)$.

Next, begin from profile V^1 and consider profile V' . Since for each $j \in M$, $v'_j \geq v_j^1 = \bar{v}^1$, and for each $k \in N \setminus M$, $v'_k = v_k^1 < \bar{v}^1$, by $\bar{v}^1 > \underline{F}(V^1)$ and Lemma 3.9(ii), $\underline{F}(V') \leq \underline{F}(V^1)$. Finally, begin from profile V' and consider profile V^1 . Since for each $j \in M$, $v'_j \geq v_j^1 = v'_j$, and for each $k \in N \setminus M$, $v'_k = v_k^1 < v'_i$, by Lemma 3.8(ii), $\underline{F}(V^1) \leq \underline{F}(V')$. Therefore, $\underline{F}(V^1) = \underline{F}(V) = \underline{F}(V')$.

If $v'_i > \bar{F}(V)$, then we are done. If $v'_i \leq \bar{F}(V)$, then let $L \subsetneq N$ be such that $j \in L$ if and only if $v_j \leq v'_j$. Begin from profile V and consider profile V^2 to be such that $V_{-L} = V_{-L}^2$ and where each agent $j \in L$ announces preferences $V_j^2 = V'_j$. By construction of V^2 and Lemma 3.8(i), $\bar{F}(V) \leq \bar{F}(V^2)$. There are two sub-cases.

(i) Let $v'_i < \bar{F}(V)$. Begin from profile V^2 and consider profile V . Since for each $j \in L$, $v'_j \leq v_j^2 = \underline{v}^2$, and for each $k \in N \setminus L$, $v'_k = v_k^2 > \underline{v}^2$, by $\underline{v}^2 < \bar{F}(V^2)$ and Lemma 3.9(i), $\bar{F}(V^2) \leq \bar{F}(V)$. Therefore, $\bar{F}(V) = \bar{F}(V^2)$.

Next, begin from profile V' and consider profile V^2 . Since for each $j \in L$, $v'_j \leq v_j^2 = v'_j$, and for each $k \in N \setminus L$, $v'_k = v_k^2 < v'_i$, by Lemma 3.8(i), $\bar{F}(V^2) \geq \bar{F}(V')$. Finally, begin from profile V^2 and consider profile V' . Since for each $j \in L$, $v'_j \leq v_j^2 = \underline{v}^2$, and for each $k \in N \setminus L$, $v'_k = v_k^2 > \underline{v}^2$, by $\underline{v}^2 < \bar{F}(V^2)$ and Lemma 3.9(i), $\bar{F}(V') \geq \bar{F}(V^2)$. Therefore, $\bar{F}(V^2) = \bar{F}(V) = \bar{F}(V')$.

(ii) Let $v'_i = \bar{F}(V)$. Assume $R_i = V'_i$. By single-peakedness, $b_{R_i}(F(V)) = v'_i$. Hence, $V_{-i} = V'_{-i}$ and *strategy-proofness* imply $v'_i \in F(V')$. Thus, $\bar{F}(V') \geq \bar{F}(V)$.

Assuming $\bar{F}(V') > \bar{F}(V)$ results in a contradiction as follows. Begin from profile V and consider profile V^2 . Since for each $j \in L$, $v_j \leq v_j^2 = v'_j$, and for each $k \in N \setminus L$, $v_k = v_k^2 > v'_i$, by Lemma 3.8(i), $\bar{F}(V) \leq \bar{F}(V^2)$. Moreover, begin from profile V^2 and consider profile V . Since for each $j \in L$, $v_j \leq v_j^2 = \underline{v}^2$, and for each $k \in N \setminus L$, $v_k = v_k^2 > \underline{v}^2$, by $\underline{v}^2 < \bar{F}(V^2)$ and Lemma 3.9(i), $\bar{F}(V) \geq \bar{F}(V^2)$.

Therefore, $\bar{F}(V) = \bar{F}(V^2)$.

Next, begin from profile V' and consider profile V^2 as described in the previous sub-case. Since for each $j \in L$, $v'_j \leq v_j^2 = v'_i$, and for each $k \in N \setminus L$, $v'_k = v_k^2 > v'_i$, by Lemma 3.8(i), $\bar{F}(V') \leq \bar{F}(V^2)$. Finally, begin from profile V^2 and consider profile V' . Since for each $j \in L$, $v'_j \leq v_j^2 = v^2$, and for each $k \in N \setminus L$, $v'_k = v_k^2 > v^2$, by $v^2 < \bar{F}(V^2)$ and Lemma 3.9(i), $\bar{F}(V') \geq \bar{F}(V^2)$. Therefore, $\bar{F}(V^2) = \bar{F}(V')$. Therefore, $\bar{F}(V^2) = \bar{F}(V) = \bar{F}(V')$.

Case 3.2. Let $\underline{F}(V) < v_i < \bar{F}(V)$ and $v'_i < v_i$. The proof is symmetric to Case 3.1. \square

Finally, we present the proof of Proposition 3.6.

Proof of Proposition 3.6. Let $F \in \mathcal{F}$ satisfy *strategy-proofness*, *min/max continuity*, and *voter-sovereignty*. By Proposition 3.3, F also satisfies *efficiency*. Let pair $V, V' \in \mathcal{R}^N$ and $i \in N$ be such that $V_{-i} = V'_{-i}$. There are five cases.

Case 1.1. Let $v_i < \underline{F}(V)$ and $v'_i \leq \bar{F}(V)$. Notice that if $R_i = V_i$, by single-peakedness, $b_{R_i}(F(V)) = \underline{F}(V)$ and $w_{R_i}(F(V)) = \bar{F}(V)$.

Assuming $v_i \geq \underline{F}(V')$ leads to a contradiction as follows. By *min/max continuity*, there exists $V_i^* \in \mathcal{R}$ such that $\underline{F}(V_{-i}, V_i^*) = v_i$. Assume $R_i = V_i$. By single-peakedness, $b_{R_i}(F(V_{-i}, V_i^*)) = v_i \notin F(V)$. Hence, if at profile V agent i deviates by announcing V_i^* , his best point improves. This contradicts *strategy-proofness*. Therefore, $v_i < \underline{F}(V') \leq \bar{F}(V')$.

Next, assuming $\underline{F}(V') < \underline{F}(V)$ or $\bar{F}(V') < \bar{F}(V)$ leads to a contradiction as follows. Assume $R_i = V_i$. By $v_i < \underline{F}(V') \leq \bar{F}(V')$ and single-peakedness, $b_{R_i}(F(V')) P_i b_{R_i}(F(V))$ or $w_{R_i}(F(V')) P_i b_{R_i}(F(V))$. Hence, if at profile V agent i deviates by announcing V'_i , his best point or his worst point improves. This contradicts *strategy-proofness*. Therefore, $\underline{F}(V') \geq \underline{F}(V)$ and $\bar{F}(V') \geq \bar{F}(V)$.

Finally, assuming $\underline{F}(V) < \underline{F}(V')$ or $\bar{F}(V) < \bar{F}(V')$ leads to a contradiction as follows. Assume $R_i = V'_i$. By $v'_i \leq \underline{F}(V) \leq \bar{F}(V)$ and single-peakedness, $b_{R_i}(F(V)) P_i b_{R_i}(F(V'))$ or $w_{R_i}(F(V)) P_i b_{R_i}(F(V'))$. Hence, if at profile V' agent i deviates by announcing V_i , his best point or his worst point improves. This contradicts *strategy-proofness*.

Therefore, $\bar{F}(V') = \bar{F}(V)$ and in addition, if $v'_i \leq \underline{F}(V)$, then $\underline{F}(V') = \underline{F}(V)$.

Case 1.2. Let $v_i = \underline{F}(V)$ and $v'_i \leq \bar{F}(V)$. By the same arguments to the ones presented in Case 1.1 for the maximum point chosen, it follows that $\bar{F}(V') = \bar{F}(V)$.

Case 2.1. Let $v_i > \bar{F}(V)$ and $v'_i \geq \underline{F}(V)$. By symmetric arguments to those presented in Case 1.1, it follows that $\underline{F}(V') = \underline{F}(V)$ and in addition, if $v'_i \geq \bar{F}(V)$, then $\bar{F}(V') = \bar{F}(V)$.

Case 2.2. Let $v_i = \bar{F}(V)$ and $v'_i \geq \underline{F}(V)$. By symmetric arguments to those presented in Case 1.2, it follows that $\underline{F}(V') = \underline{F}(V)$.

Case 3. Let $\underline{F}(V) < v_i < \bar{F}(V)$. By symmetry of arguments, let $v_i \geq v'_i$. Without loss of generality, let $v_1 \leq \dots \leq v_n$ and notice that by *efficiency* and Proposition 3.1, $F(V) \subseteq \text{Conv}(V)$; hence, agent $i \notin \{1, n\}$. In addition, for each agent $j \in N \setminus \{i\}$, define preferences $\bar{V}_j \in \mathcal{R}$ be such that $\bar{V}_j = V'_j$.

Begin from profile V and consider profile $V^1 = (V_{-1}, \bar{V}_1)$. By *efficiency* and Proposition 3.1, $F(V) \subseteq \text{Conv}(V)$. Hence, since $v_1 = \underline{v}$, by either Case 1.1 (if $v_1 < \underline{F}(V)$) or Case 1.2 (if $v_1 = \underline{F}(V)$), $\bar{F}(V^1) = \bar{F}(V)$. Moreover, by *efficiency* and Proposition 3.1, $F(V^1) \subseteq \text{Conv}(V^1)$; hence, $v_2 = \underline{v}^1$. Next, for agents $k \in \{2, \dots, i\}$, in increasing order, consider profile $V^k = (V_{-k}^{k-1}, \bar{V}_k)$. By the arguments presented for V^1 , $\bar{F}(V^k) = \bar{F}(V)$. Therefore, at profile $V^i = (\bar{V}_1, \dots, \bar{V}_i, V_{i+1}, \dots, V_n)$, $\bar{F}(V^i) = \bar{F}(V)$. Finally, begin from profile V' . By the same technique as the one described for profile V , change the preferences of agents $k \in \{1, \dots, i-1\}$, in increasing order, to again construct profile $V^i = (\bar{V}_1, \dots, \bar{V}_i, V_{i+1}, \dots, V_n)$. Therefore, $\bar{F}(V^i) = \bar{F}(V') = \bar{F}(V)$.

Similarly, if $v'_i \leq \underline{F}(V)$, then once can show that $\underline{F}(V') = \underline{F}(V)$, by using symmetrical arguments to the ones presented above. Specifically, begin from profile V and change the preferences of agents $k \in \{i, \dots, n\}$, in decreasing order, and show that $\underline{F}(V_1, \dots, V_{i-1}, \bar{V}_i, \dots, \bar{V}_n) = \underline{F}(V)$. Finally, begin from profile V' and change the preferences of agents $k \in \{i+1, \dots, n\}$, in decreasing order, and show that $\underline{F}(V_1, \dots, V_{i-1}, \bar{V}_i, \dots, \bar{V}_n) = \underline{F}(V') = \underline{F}(V)$. \square

3.D Proof of Theorem 3.1 (equivalence of statements (ii) and (iii))

We first show for Theorem 3.1 that statement (iii) implies statement (ii) in domain \mathcal{R} . Moreover, as discussed in Section 3.5.3, this result also holds in domain \mathcal{S} .

Proof of Theorem 3.1 (statement (iii) implies statement (ii)). Let $F_G^{\alpha, \beta} \in \mathcal{F}_G$. By the definition of \mathcal{F}_G , to show that $F_G^{\alpha, \beta}$ satisfies *uncompromisingness*, it suffices to show that the minimum and maximum chosen alternatives by $F_G^{\alpha, \beta}$ are not compromised. Moreover, by symmetry of arguments, we only need to show that $\underline{F}_G^{\alpha, \beta}(V)$ is not compromised.

Let $V \in \mathcal{R}^N$ and without loss of generality, let $v_1 \leq \dots \leq v_n$. Let $i \in N$ and $V' \in \mathcal{R}^N$ be such that $V_{-i} = V'_{-i}$. Moreover, let $v_i \neq \underline{F}_G^{\alpha, \beta}(V)$. Hence, $\underline{F}_G^{\alpha, \beta}(V) = \text{med}(v, \tilde{\alpha}_v)$ and $\underline{F}_G^{\alpha, \beta}(V') = \text{med}(v', \tilde{\alpha}_{v'})$. There are two cases.

Case 1. Let $j \in N$ and $\underline{F}_G^{\alpha,\beta}(V) = \text{med}(v, \tilde{\alpha}_v) = v_j$. Hence, $v_i \neq \underline{F}_G^{\alpha,\beta}(V)$ implies $i \neq j$. Since at V , $v_1 \leq \dots \leq v_n$, at least j agents announce peaks smaller than or equal to v_j and at least $n - j + 1$ agents announce peaks larger than or equal to v_j . Thus, since there are n agents in total and $\tilde{\alpha}_v \in A^{n+1}$, by the median operator, vector $\tilde{\alpha}_v$ contains at least $n - j + 1$ coordinates smaller than or equal to v_j and at least j coordinates larger than or equal to v_j . Therefore, since $\alpha_N \leq \dots \leq \alpha_\emptyset$, if $j = 1$, $\alpha_{\{1\}} \leq v_j \leq \alpha_\emptyset$, and otherwise, $\alpha_{\{1,\dots,j\}} \leq v_j \leq \alpha_{\{1,\dots,j-1\}}$. There are two sub-cases.

(i) Let $v_i < \underline{F}_G^{\alpha,\beta}(V) = v_j$, that is, $i \in \{1, \dots, j - 1\}$. This implies $j \in \{2, \dots, n\}$ and $\alpha_{\{1,\dots,j\}} \leq v_j \leq \alpha_{\{1,\dots,j-1\}}$. In addition, let $v'_i \leq v_j$. Thus, at profile V' , at least j agents announce peaks smaller than or equal to v_j (i.e., agents $1, \dots, j$) and at least $n - j + 1$ agents announce peaks larger than or equal to v_j (i.e., agents j, \dots, n). Moreover, $V_{-i} = V'_{-i}$ and $v'_i \leq v_j$ imply that $v'_i \leq v_j \leq v_{j+1} \leq \dots \leq v_n$, that is, the agents announcing the $j - 1$ smallest peaks at V (i.e., agents $1, \dots, j - 1$) also announce the $j - 1$ smallest peaks at V' . Similarly, the agents announcing the j smallest peaks at V (i.e., agents $1, \dots, j$) also announce the j smallest peaks at V' . Hence, coordinates $\alpha_{\{1,\dots,j\}}$ and $\alpha_{\{1,\dots,j-1\}}$ are included in vector $\tilde{\alpha}_{v'}$. Thus, $\alpha_{\{1,\dots,j\}} \leq v_j \leq \alpha_{\{1,\dots,j-1\}}$ and the definition of \mathcal{F}_G implies that vector $\tilde{\alpha}_{v'}$ contains at least $n - j + 1$ coordinates smaller than or equal to v_j and at least j coordinates larger than or equal to v_j . Therefore, $\underline{F}_G^{\alpha,\beta}(V') = \text{med}(v', \tilde{\alpha}_{v'}) = v_j = \underline{F}_G^{\alpha,\beta}(V)$.

(ii) Let $v_i > \underline{F}_G^{\alpha,\beta}(V) = v_j$, that is, $i \in \{j + 1, \dots, n\}$. The proof is symmetric to (i).

Case 2. Let $M \subseteq N$ such that $|M| = m$. Let $\underline{F}_G^{\alpha,\beta}(V) = \text{med}(v, \tilde{\alpha}_v) = \alpha_M$, such that for each $i \in N$, $v_i \neq \alpha_M$. Hence, if $|M| = 0$, $\alpha_M = \alpha_\emptyset$, and otherwise, $\alpha_M = \alpha_{\{1,\dots,m\}}$. Since $\alpha_N \leq \dots \leq \alpha_\emptyset$, vector $\tilde{\alpha}_v$ contains at least $n - m + 1$ coordinates smaller than or equal to α_M (i.e., coordinates $\alpha_{\{1,\dots,m\}}, \dots, \alpha_N$) and at least $m + 1$ coordinates larger than or equal to α_M (i.e., coordinates $\alpha_\emptyset, \dots, \alpha_{\{1,\dots,m\}}$). Thus, since there are n agents in total and none of their announced peaks equals α_M , by the median operator, at V , m agents announce peaks smaller than α_M (i.e., agents $1, \dots, m$) and $n - m$ agents announce peaks larger than α_M (i.e., agents $m + 1, \dots, n$). Therefore, since $v_1 \leq \dots \leq v_n$, if $m = 0$, $\alpha_M = \alpha_\emptyset < v_1$, if $m = n$, $\alpha_M = \alpha_N > v_n$, and otherwise, $v_m < \alpha_M = \alpha_{\{1,\dots,m\}} < v_{m+1}$. There are four sub-cases.

(i) Let $m = 0$. Hence, $\alpha_M = \alpha_\emptyset < v_1 \leq v_i$. In addition, let $\alpha_M = \underline{F}_G^{\alpha,\beta} \leq v'_i$. Thus, at V' , all n agents announce peaks larger than α_M . In addition, since

$\alpha_N \leq \dots \leq \alpha_\emptyset = \alpha_M$, vector $\tilde{\alpha}_{v'}$ contains at least $n + 1$ coordinates smaller than or equal to α_M (i.e., coordinates $\alpha_\emptyset, \dots, \alpha_N$) and at least 1 coordinate larger than or equal to α_M (i.e., coordinate α_\emptyset). Therefore, $\underline{F}_G^{\alpha, \beta}(V') = \text{med}(v', \tilde{\alpha}_{v'}) = \alpha_M = \underline{F}_G^{\alpha, \beta}(V)$.

(ii) Let $m = n$. The proof is symmetric to (i).

(iii) Let $m \in \{1, \dots, n - 1\}$ and $v_i < \alpha_{\{1, \dots, m\}} = \alpha_M$. Hence, $v_i \leq v_m < \alpha_M < v_{m+1}$. In addition, let $v'_i \leq \alpha_M$. Thus, at V' , at least m agents announce peaks smaller than or equal to α_M (i.e., agents $1, \dots, m$) and $n - m$ agents announce peaks larger than α_M (i.e., agents $m + 1, \dots, n$). Moreover, $V_{-i} = V'_{-i}$ and $v'_i \leq \alpha_M$ imply that $v'_i \leq \alpha_M < v_{m+1} \leq \dots \leq v_n$, that is, the agents announcing the m smallest peaks at V (i.e., agents $1, \dots, m$) also announce the m smallest peaks at V' . Hence, coordinate $\alpha_{\{1, \dots, m\}}$ is included in vector $\tilde{\alpha}_{v'}$. Thus, the definition of \mathcal{F}_G implies that vector $\tilde{\alpha}_{v'}$ contains at least $n - m + 1$ coordinates smaller than or equal to α_M and at least $m + 1$ coordinates larger than or equal to α_M . Therefore, $\underline{F}_G^{\alpha, \beta}(V') = \text{med}(v', \tilde{\alpha}_{v'}) = \alpha_M = \underline{F}_G^{\alpha, \beta}(V)$.

(iv) Let $m \in \{1, \dots, n - 1\}$ and $v_i > \alpha_{\{1, \dots, m\}} = \alpha_M$. The proof is symmetric to (iii). \square

Before showing for Theorem 3.1 that statement (ii) implies statement (iii), we first prove the following intermediate result that holds in both domains \mathcal{R} and \mathcal{S} .

Lemma 3.10. *Let $F \in \mathcal{F}$ satisfy strategy-proofness, peaks-onliness, and uncompromisingness. Then, for each $i \in N$ and each pair $V, V' \in \mathcal{R}^N$ such that $V'_{-i} = V_{-i}$, if $v_i \leq v'_i$, then $\underline{F}(V) \leq \underline{F}(V')$ and $\bar{F}(V) \leq \bar{F}(V')$.³³*

Proof. Let $F \in \mathcal{F}$ satisfy strategy-proofness, peaks-onliness, and uncompromisingness. Let $i \in N$ and pair $V, V' \in \mathcal{R}^N$ be such that $V'_{-i} = V_{-i}$. Since by peaks-onliness, $v_i = v'_i$ implies $F(V) = F(V')$, let $v_i < v'_i$. There are three cases.

Case 1. Let $v_i < \underline{F}(V)$ and $v_i < v'_i$. Concerning the maximum alternative chosen, if $v'_i \leq \bar{F}(V)$, then by uncompromisingness, $\bar{F}(V) = \bar{F}(V')$. Let $V_i^1 \in \mathcal{R}$ be such that $v_i^1 = \bar{F}(V)$. Hence, by uncompromisingness, $\bar{F}(V_{-i}, V_i^1) = \bar{F}(V)$. If $v'_i > \bar{F}(V)$, then assuming $\bar{F}(V') < \bar{F}(V)$ leads to a contradiction as follows. Begin from V' and let agent i change his announcement to V_i^1 . Since $\bar{F}(V') < v_i^1 < v'_i$, by uncompromisingness, $\bar{F}(V'_{-i}, V_i^1) = \bar{F}(V')$. Thus, $\bar{F}(V'_{-i}, V_i^1) = \bar{F}(V_{-i}, V_i^1)$ contradicts $\bar{F}(V') < \bar{F}(V)$. Therefore, in both cases, $\bar{F}(V') \geq \bar{F}(V)$.

³³Notice that this result simply shows that *strategy-proofness* and *uncompromisingness* imply *peak-monotonicity*, a property that we refrain from introducing formally since it is only used in the “only if” part of Theorem 3.1. Loosely speaking, this property requires the following: if an agent’s announced peak moves to the right (left), then the chosen set also moves to the right (left).

Concerning the minimum alternative chosen, assume $R_i = V_i$. Since $v_i < \underline{F}(V)$ and $\bar{F}(V) \leq \bar{F}(V')$, if $\underline{F}(V') < \underline{F}(V)$, then single-peakedness implies $b_{R_i}(F(V'))R_i < b_{R_i}(F(V))$. Hence, if at profile V agent i deviates by announcing V'_i , his best point improves. This contradicts *strategy-proofness*. Therefore, $\underline{F}(V') \geq \underline{F}(V)$.

Case 2. Let $\underline{F}(V) \leq v_i < \bar{F}(V)$ and $v_i < v'_i$. Concerning the maximum alternative chosen, by the arguments presented in Case 1, $\bar{F}(V') \geq \bar{F}(V)$. Concerning the minimum alternative chosen, if $\underline{F}(V') < \underline{F}(V)$, then $\underline{F}(V') < v_i < v'_i$ and *uncompromisingness* imply $\underline{F}(V') = \underline{F}(V'_i, V_i) = \underline{F}(V)$. Therefore, $\underline{F}(V') \geq \underline{F}(V)$.

Case 3. Let $\bar{F}(V) \leq v_i$ and $v_i < v'_i$. Concerning the maximum alternative chosen, if $\bar{F}(V') < \bar{F}(V)$, then $\bar{F}(V) \leq v_i < v'_i$ and *uncompromisingness* imply $\bar{F}(V') = \bar{F}(V'_i, V_i) = \bar{F}(V)$. Similarly, concerning the minimum alternative chosen, if $\underline{F}(V') < \underline{F}(V)$, then $\underline{F}(V) \leq v_i < v'_i$ and *uncompromisingness* imply $\underline{F}(V') = \underline{F}(V'_i, V_i) = \underline{F}(V)$. \square

The last part of the proof of Theorem 3.1 follows. Notice that this part holds in both domains \mathcal{R} and \mathcal{S} .

Proof of Theorem 3.1 (statement (ii) implies statement (iii)). Let $F \in \mathcal{F}$ satisfy *uncompromisingness*. By Proposition 3.4, F satisfies *strategy-proofness* and *peaks-onliness*. For each $i \in N$, let pair $V_i^{\min}, V_i^{\max} \in \mathcal{R}$ be such that $v_i^{\min} = 0$ and $v_i^{\max} = 1$. We proceed in three steps.

Step 1. We show that at each announced profile $V \in \mathcal{R}^N$ and for each $i \in N$, the minimum chosen alternative is the median of: (i) the announced peak of i at profile V (i.e., v_i), (ii) the minimum chosen alternative if i changes his announcement to V_i^{\min} (i.e., $\underline{F}(V_{-i}, V_i^{\min})$), and (iii) the minimum chosen alternative if i changes his announcement to V_i^{\max} (i.e., $\underline{F}(V_{-i}, V_i^{\max})$). By symmetry of arguments, we do not show the equivalent result for the maximum chosen alternative.

Let $i \in N$ and $V \in \mathcal{R}^N$. Consider profiles $V^{\min} = (V_{-i}, V_i^{\min})$ and $V^{\max} = (V_{-i}, V_i^{\max})$. Since $V_{-i} = V_{-i}^{\min} = V_{-i}^{\max}$ and $v_i^{\min} \leq v_i \leq v_i^{\max}$, by Lemma 3.10, $\underline{F}(V^{\min}) \leq \underline{F}(V) \leq \underline{F}(V^{\max})$. There are three cases.

Case 1. Let $v_i < \underline{F}(V^{\min}) \leq \underline{F}(V)$. Since $0 = v_i^{\min} \leq v_i < \underline{F}(V)$, *uncompromisingness* implies $\underline{F}(V^{\min}) = \underline{F}(V)$. Therefore, $\underline{F}(V^{\min}) = \underline{F}(V) = \text{med}(\underline{F}(V^{\min}), v_i, \underline{F}(V^{\max}))$.

Case 2. Let $v_i > \underline{F}(V^{\max}) \geq \underline{F}(V)$. Symmetric proof to Case 1.

Case 3. Let $\underline{F}(V^{\min}) \leq v_i \leq \underline{F}(V^{\max})$. Assuming $v_i < \underline{F}(V)$ and thus $\underline{F}(V^{\min}) < \underline{F}(V)$ results in a contradiction as follows. Since $0 = v_i^{\min} \leq v_i < \underline{F}(V)$, *uncompromisingness* implies $\underline{F}(V^{\min}) = \underline{F}(V)$. Similarly, assuming $\underline{F}(V) < v_i$ and thus $\underline{F}(V) < \underline{F}(V^{\max})$ results in a contradiction as follows. Since

$\underline{F}(V) < v_i \leq v_i^{\max}$, uncompromisingness implies $\underline{F}(V) = \underline{F}(V^{\max})$. Therefore, $\underline{F}(V) = v_i = \text{med}(\underline{F}(V^{\min}), v_i, \underline{F}(V^{\max}))$.

Step 2. We construct two vectors α and β . In this step of the proof and in contrast to the rest of the paper, we will use a different letter to label announced profiles (U instead of V). This is done in an attempt to facilitate the notation used in Step 3 of the proof that follows.

For each $M \subseteq N$, let $U^M \in \mathcal{R}^N$ be such that all agents in M announce 0 as their peak and all other agents announce 1 as their peak, i.e., $u^M = (\underbrace{0, \dots, 0}_{i \in M}, \underbrace{1, \dots, 1}_{i \in N \setminus M})$.

Next, let vectors $\alpha = (\alpha_M)_{M \subseteq N}$ and $\beta = (\beta_M)_{M \subseteq N}$ be such that $\alpha_M = \underline{F}(U^M)$ and $\beta_M = \bar{F}(U^M)$, hence, $\alpha_M \leq \beta_M$. Moreover, for each $L, M \subseteq N$ such that $L \subsetneq M$ notice the following. For each $i \in M \setminus L$, $u_i^L = 1 > 0 = u_i^M$, and for each $j \notin M \setminus L$, $U_j^L = U_j^M$. Begin from profile U^L and consider that all agents i (sequentially) change their announcements to U_i^M . Since $u_i^L > u_i^M$, by (sequentially) applying Lemma 3.10, both $\alpha_L \geq \alpha_M$ and $\beta_L \geq \beta_M$.

Step 3. We show that F is a generalized median correspondence associated with vectors α and β constructed in Step 2.

Let $V \in \mathcal{R}^N$. Without loss of generality, index the agents in N such that $v_1 \leq \dots \leq v_n$. Recall vectors α, β and profiles U^M , for $M \subseteq N$, defined in Step 2. Let vectors $\tilde{\alpha}_v, \tilde{\beta}_v \in A^{n+1}$ be such that $\tilde{\alpha}_v = (\alpha_\emptyset, \alpha_{\{1\}}, \alpha_{\{1,2\}}, \dots, \alpha_N)$ and $\tilde{\beta}_v = (\beta_\emptyset, \beta_{\{1\}}, \beta_{\{1,2\}}, \dots, \beta_N)$.

Since the coordinates of $\tilde{\alpha}_v$ are such that $0 \leq \alpha_N \leq \dots \leq \alpha_\emptyset \leq 1$ and $u^\emptyset = (1, \dots, 1)$, $\underline{F}(U^\emptyset) = \text{med}(u^\emptyset, \tilde{\alpha}_v) = \alpha_\emptyset$. Moreover, for each $i \in \{1, \dots, n\}$, $u^{\{1, \dots, i\}} = (\underbrace{0, \dots, 0}_{j \in \{1, \dots, i\}}, \underbrace{1, \dots, 1}_{j \in \{i+1, \dots, n\}})$ implies $\underline{F}(U^{\{1, \dots, i\}}) = \text{med}(u^{\{1, \dots, i\}}, \tilde{\alpha}_v) = \alpha_{\{1, \dots, i\}}$. Similarly for $\tilde{\beta}_v$, $\bar{F}(U^\emptyset) = \beta_\emptyset$ and for each $i \in \{1, \dots, n\}$, $\bar{F}(U^{\{1, \dots, i\}}) = \beta_{\{1, \dots, i\}}$.

Next, for each $i \in \{1, \dots, n\}$, let $V^i \in \mathcal{R}^N$ be such that $V^i = (V_1, \dots, V_i, V_{i+1}^{\max}, \dots, V_n^{\max})$ and notice that $V^n = V$. We show that $F(V) = F_G^{\alpha, \beta}(V)$ by induction, in two stages.

Stage 1. We show that $F(V^1) = F_G^{\alpha, \beta}(V^1)$.

Consider profile $V^1 = (V_1, V_2^{\max}, \dots, V_n^{\max})$. Recall profiles $U^{\{1\}} = (V_1^{\min}, V_2^{\max}, \dots, V_n^{\max})$ and $U^\emptyset = (V_1^{\max}, \dots, V_n^{\max})$. Hence, $U^{\{1\}} = (V_{-1}^1, V_1^{\min})$ and $U^\emptyset = (V_{-1}^1, V_1^{\max})$. By Step 1, $\underline{F}(V^1) = \text{med}(\underline{F}(U^{\{1\}}), v_1, \underline{F}(U^\emptyset))$ and $\bar{F}(V^1) = \text{med}(\bar{F}(U^{\{1\}}), v_1, \bar{F}(U^\emptyset))$. Hence, $\underline{F}(V^1) = \text{med}(\alpha_{\{1\}}, v_1, \alpha_{\{\emptyset\}})$ and $\bar{F}(V^1) = \text{med}(\beta_{\{1\}}, v_1, \beta_{\{\emptyset\}})$. Moreover, since $\alpha_N \leq \dots \leq \alpha_\emptyset \leq v_2 = \dots = v_n$ and $\beta_N \leq \dots \leq \beta_\emptyset \leq v_2 = \dots = v_n$, $\underline{F}(V^1) = \text{med}(v, \tilde{\alpha}_{v,1})$ and $\bar{F}(V^1) = \text{med}(v, \tilde{\beta}_{v,1})$. Therefore, $F(V^1) = F_G^{\alpha, \beta}(V^1)$.

Stage 2. Let $i \in \{2, \dots, n\}$ be such that $F(V^{i-1}) = F_G^{\alpha, \beta}(V^{i-1})$. We show that $F(V^i) = F_G^{\alpha, \beta}(V^i)$. Notice that we only show $\underline{F}(V^i) = \underline{F}_G^{\alpha, \beta}(V^i)$. The proof showing $\bar{F}(V^i) = \bar{F}_G^{\alpha, \beta}(V^i)$ is symmetric, that is, it can be obtained using the same arguments but after replacing all references to the minimum chosen alternative and $\tilde{\alpha}_{v^i}$ with the equivalent references to the maximum chosen alternative and $\tilde{\beta}_{v^i}$ respectively.

Recall that $V^{i-1} = (V_1, \dots, V_{i-1}, V_i^{\max}, \dots, V_n^{\max})$ and $V^i = (V_{-i}^{i-1}, V_i)$. There are three cases.

Case 1. Let $v_i > \underline{F}(V^i)$. Since $V_{-i}^{i-1} = V_{-i}^i$ and $\underline{F}(V^i) < v_i \leq v_i^{\max}$, by *uncompromisingness*, $\underline{F}(V^i) = \underline{F}(V^{i-1}) = \text{med}(v^{i-1}, \tilde{\alpha}_{v^i})$. Thus, $V_{-i}^{i-1} = V_{-i}^i$ and $\text{med}(v^{i-1}, \tilde{\alpha}_{v^i}) < v_i \leq v_i^{\max}$ implies $\underline{F}(V^i) = \text{med}(v^i, \tilde{\alpha}_{v^i}) = \underline{F}_G^{\alpha, \beta}(V^i)$.

Case 2. Let $v_i < \underline{F}(V^i)$ and recall that $U^{\{1, \dots, i\}} = (V_1^{\min}, \dots, V_i^{\min}, V_{i+1}^{\max}, \dots, V_n^{\max})$. Since $v_1 \leq \dots \leq v_n$ and $v_i < \underline{F}(V^i)$, for each $j \in \{1, \dots, i\}$, $v_j^{\min} \leq v_j < \underline{F}(V^i)$; hence, by *uncompromisingness*, $\underline{F}(V_{-j}^i, V_j^{\min}) = \underline{F}(V^i)$. Therefore, beginning from profile V^i and considering that all agents $j \in \{1, \dots, i\}$ (sequentially) change their announcements to V_j^{\min} , implies by (sequentially applying) *uncompromisingness*, that $\underline{F}(V^i) = \underline{F}(U^{\{1, \dots, i\}})$ where as shown above $\underline{F}(U^{\{1, \dots, i\}}) = \alpha_{\{1, \dots, i\}}$. Therefore, since at profile V^i , for each $j \in \{1, \dots, i\}$, $v_j^i < \alpha_{\{1, \dots, i\}}$, and for each $k \in \{i+1, \dots, n\}$, $v_k^i = v_k^{\max} = 1 \geq \alpha_{\{1, \dots, i\}}$, by the median operator, $\underline{F}(V^i) = \text{med}(v^i, \tilde{\alpha}_{v^i}) = \underline{F}_G^{\alpha, \beta}(V^i)$.

Case 3. Let $v_i = \underline{F}(V^i)$. Since $V_{-i}^{i-1} = V_{-i}^i$ and $v_i \leq v_i^{\max}$, by Lemma 3.10, $\underline{F}(V^i) \leq \underline{F}(V^{i-1})$. Thus, $v_1 \leq \dots \leq v_n$ and $v_i = \underline{F}(V^i)$, imply $v_{i-1}^i = v_{i-1}^{i-1} \leq \underline{F}(V^{i-1})$. There are two sub-cases.

(i) Let $v_{i-1}^i = \underline{F}(V^{i-1})$. Thus, $v_{i-1}^i = v_i = \underline{F}(V^i) = \underline{F}(V^{i-1})$. Hence, $\underline{F}(V^{i-1}) = \underline{F}_G^{\alpha, \beta}(V^{i-1})$ implies $\text{med}(v^{i-1}, \tilde{\alpha}_{v^{i-1}}) = v_i \leq v_i^{\max}$. Therefore, by the median operator, $\underline{F}(V^i) = v_i = \text{med}(v^i, \tilde{\alpha}_{v^i}) = \underline{F}_G^{\alpha, \beta}(V^i)$.

(ii) Let $v_{i-1}^i < \underline{F}(V^{i-1})$. Recall that at profiles $U^{\{1, \dots, i-1\}} = (V_1^{\min}, \dots, V_{i-1}^{\min}, V_i^{\max}, \dots, V_n^{\max})$ and $U^{\{1, \dots, i\}} = (V_{-i}^{\{1, \dots, i-1\}}, V_i^{\min})$, $\underline{F}(U^{\{1, \dots, i-1\}}) = \alpha_{\{1, \dots, i-1\}}$ and $\underline{F}(U^{\{1, \dots, i\}}) = \alpha_{\{1, \dots, i\}}$. Since $v_i = \underline{F}(V^i) \leq \underline{F}(V^{i-1})$, it follows that $v_i \leq \alpha_{\{1, \dots, i-1\}}$.

Next, begin from profile $U^{\{1, \dots, i\}}$ and consider that all agents $j \in \{1, \dots, i\}$ (sequentially) change their announcements to V_j , i.e., the final new profile is $V^i = (V_1, \dots, V_i, V_{i+1}^{\max}, \dots, V_n^{\max})$. Since $v_j \geq v_j^{\min}$, by (sequentially) applying Lemma 3.10, $\underline{F}(V^i) \geq \underline{F}(U^{\{1, \dots, i\}}) = \alpha_{\{1, \dots, i\}}$. Hence, $v_i \geq \alpha_{\{1, \dots, i\}}$ and it follows, that $\alpha_{\{1, \dots, i\}} \leq v_i \leq \alpha_{\{1, \dots, i-1\}}$. Thus, since $\alpha_N \leq \dots \leq \alpha_\emptyset$, vector

$\tilde{\alpha}_{v^i}$ contains at least $n + 1 - i$ coordinates not larger than v_i (i.e., coordinates $\alpha_{\{1, \dots, i\}}, \dots, \alpha_N$) and at least i coordinates not smaller than v_i (i.e., coordinates $\alpha_{\emptyset}, \dots, \alpha_{\{1, \dots, i-1\}}$). In addition, since $v_1 \leq \dots \leq v_n$, at least i agents announce peaks not larger than v_i (i.e., agents $1, \dots, i$) and $n - i + 1$ agents announce peaks not smaller than v_i (i.e., agents i, \dots, n). Therefore, by the median operator, $F(V^i) = \text{med}(v^i, \tilde{\alpha}_{v^i}) = v_i = \underline{F}_G^{\alpha, \beta}(V^i)$. \square

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